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MANUFACTURING EFFECTS ON WATER CAVITATION IN LONG L/D SHARP EDGE INLET ORIFICES

by

ROBERT DALTON HICKS

A THESIS

Submitted in partial fulfillment of the requirements
for the degree of Master of Science in Mechanical Engineering
in
The Department of Mechanical and Aerospace Engineering
of
The School of Graduate Studies
of
The University of Alabama in Huntsville
HUNTSVILLE, ALABAMA
2019

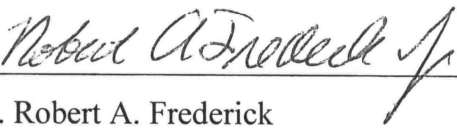
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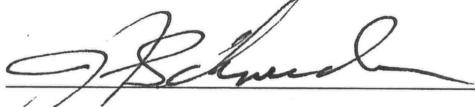
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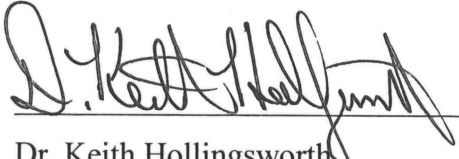
Submitted by Robert Hicks in partial fulfillment of the requirements for the degree of Master of Science in Mechanical Engineering and accepted on behalf of the Faculty of the School of Graduate Studies by the thesis committee.


We, the undersigned members of the Graduate Faculty of the University of Alabama in Huntsville, certify that we have advised and/or supervised the candidate on the work described in this thesis. We further certify that we have reviewed the thesis manuscript and approve it in partial fulfillment of the requirements of the degree of Master of Science in Aerospace Systems Engineering.

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ABSTRACT

The School of Graduate Studies

ABSTRACT

The School of Graduate Studies

The University of Alabama in Huntsville

Degree Master of Science College/Dept. Engineering/Mechanical and
Aerospace Engineering

Name of Candidate Robert Dalton Hicks

Title Manufacturing Effects on Water Cavitation in Long L/ D Sharp Edge Inlet Orifices

Additive manufacturing is becoming prevalent in the field of fluids and flow control with the advent of Selective Laser Sintering (SLS) and Selective Laser Melting (SLM). Due to the roughness of additively manufactured components, parts routinely need post-machining to reduce surface roughness and match the characteristics of subtractively manufactured components. This research aims to quantify the effects of layer-induced surface roughness on effective cross-sectional area reduction and cavitation onset conditions.

Tests were performed on a 3/16" diameter, long length-to-diameter ratio ($L/D = 20$), sharp edged inlet orifice geometry using water at ambient temperature conditions. Tests were performed over a range of Cavitation Numbers, K , from $K=1.6$ to $K=1.0$. This was achieved by measuring pressure upstream of the venturi and controlling the backpressure applied. Upstream pressure was 500 psig with a programmable backpressure globe valve set to follow a setpoint schedule of Cavitation Numbers. This was to determine the effective area ($C_c * A$) as used in the Nurick model and the cavitation onset cavitation number (K_{crit}) which will be compared between venturis with different manufacturing methods and therefore roughness. Arithmetic mean roughnesses ranging from 0.26 μm to 26.85 μm were tested using subtractive manufacturing techniques, Fused Deposition Modeling, and Selective Laser Melting.

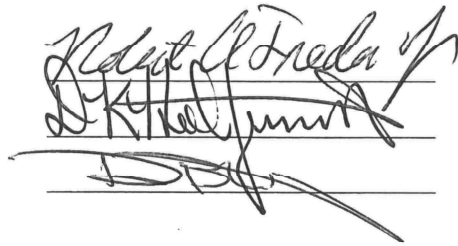
Results found shown an appreciable reduction in effective flow area with increasing roughness. Decreases in C_c of 12.3% from a smooth bore orifice to that of the roughest configuration tested were found. Additionally, delays in cavitation offset were observed with cavitation onset occurring at $K=1.08$ rather than the predicted $K=1.45$ for the roughest configuration tested.

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LIST OF SYMBOLS

SYMBOL	DEFINITION
A_{eff}	Effective Flow Area
A_{geo}	Geometric Area
C_c	Contraction Coefficient
C_D	Discharge Coefficient
C_v	Velocity Coefficient
f	Frequency
K	Cavitation Number
St	Strouhal Number
St_p	Peak Strouhal Number
A	Area
ε	Roughness
μ	Viscosity
V	Velocity
P	Pressure
P_v	Vapor Pressure
P_1	Upstream Pressure
P_2	Downstream Pressure
\dot{m}	Mass Flow
ρ	Density
r	Inlet Radius
d	Orifice Diameter
D	Orifice Diameter or Upstream Diameter
L	Orifice Length
t	Orifice Length/Thickness
L_h	Hydrodynamic Entrance Length
K_{crit}	Critical Cavitation Number
C_{Dcrit}	Discharge Coefficient at Critical Cavitation Number
Re	Reynolds Number

$Re\backslash St$	Reynolds – Strouhal Number
R_p	Maximum profile peak height
R_v	Maximum profile valley depth
R_y	Maximum peak to valley height
R_t	Total height
R_a	Average deviation
R_q	Root Mean Square Deviation
S	Mean Spacing of local peaks in profile
S_m	Mean width of profile elements
R_{sk}	Skewness
R_{ku}	Kurtosis
Δq	Root mean square slope
ν	Kinematic Viscosity

CHAPTER 1

INTRODUCTION

Cavitation is a phenomenon which occurs when the velocity of a fluid increases to the point where the minimum local static pressure drops below the fluid vapor pressure and the fluid effectively boils [1]. Cavitation has numerous beneficial uses across many industries as well as many consequences that present engineering design challenges. With uses in medical, manufacturing, and fluid control, the phenomenon's effects can be exploited for beneficial purposes. Notable work on the effects of cavitation are due to its consequences on propellers, turbomachinery, and other applications where high flow velocities substantially lower the fluid pressure. Osborne Reynolds published initial descriptions of the phenomena causing cavitation in 1873 [2]. He investigated why propellers on steamships would sometimes under high speed lose efficiency and grip on the water. Research work on cavitation has continued in applications such as pump design, inducer design, watercraft and propulsion design, in order to minimize the detrimental effects of the cavitation or increase its useful qualities. Recent work has been looking at the role of surface roughness on the cavitation phenomenon.

1.1 Objective

This work seeks to determine the relative effects of surface roughness on the cavitation phenomenon for long L/D sharp edge inlet orifices in quasi-steady-state operation. More specifically, the objective of the work is to investigate the effects of surface roughness on the effective flow area of these orifices and their resistance to flow along with any subsequent changes to the onset of cavitation. This will impact design considerations for long L/D sharp edge inlet orifice devices.

1.2 Scope

The scope of this experimental study includes the use of a long L/D ($L/D=20$) sharp edge inlet orifice geometry produced using Subtractive Manufacturing, Fused Deposition Modeling, and Selective Laser Melting manufacturing methods to create orifices with arithmetic mean roughnesses ranging from $0.26\text{ }\mu\text{m}$ to $26.85\text{ }\mu\text{m}$. Tests were performed using manipulations of downstream pressure (0 - 200 psig) with constant upstream pressure of 500 psig to obtain a range of cavitation numbers ranging from $K = 1.6$ to $K = 1.0$ in a water flow system. Water flowrates during the tests are in the range of 1-2 lbm/sec. All test samples are designed to a 3/16" orifice diameter. This is all performed while attempts are made to offset effects of the inlet radius and deviations in orifice diameter due to manufacturing differences.

1.3 Approach

Tests were performed using the High Pressure Spray Facility (HPSF) at the Johnson Research Center Facility (JRC) of the Propulsion Research Center (PRC) of the University of Alabama in Huntsville (UAH). Using a controllable backpressure globe valve a simple flow circuit was created to control the set pressure downstream of the test samples in order to attain specific test conditions. Using both static pressure transducers and high frequency dynamic pressure transducers ahead of and behind the test section the conditions before and after the sample can be determined. To meet desired sample surface roughness, a variety of manufacturing methods were used. To simulate a prototype of a system, samples were manufactured using polylactic acid (PLA) with a Fused Deposition Modeling (FDM) process. This is used as a high roughness condition. Additional samples were made on a Selective Laser Melting (SLM) process which represents metal additive manufactured processing of parts suitable for high pressure fluid flows. Lastly,

subtractively manufactured samples were made to provide samples with the lowest surface roughness.

1.4 Anticipated Results

From this investigation, the anticipated outcome is that with controlled inlet edge radius and orifice diameter, the effective flow area of the orifice would decrease with increased roughness and the onset of cavitation would occur at a lower value of Cavitation Number than the onset in a smooth orifice [3].

1.5 Outline of Report

This report will first detail the background of the main research area and review the relevant literature. Additional discussion will be made on the area of cavitation and manufacturing processes. This includes the differentiating geometries and definitions of the phenomenon of cavitation. Discussion on the setup of the test section and the test procedures will precede the discussion of the results for all test specimens. Discussion of the results will then follow along with a recommendation of future work.

CHAPTER 2

BACKGROUND

2.1 Overview of Cavitation & Bubble Formation

Cavitation can be described as “as the process of nucleation in a liquid when the pressure falls below the vapor pressure” [4, Ch. 1]. Cavitation has effects both in internal flows such as venturi-style flowmeters, orifices, inducers in pumps, and in external flows such as submarines, propellers, etc. Cavitation can cause large degrees of damage to parts and systems [5]. This damage is due to the bubbles created during the process collapsing, leaving a high stress location in the fluid and a very high local temperature as the vapor is compressed by the liquid front. This temperature can be upwards of 6700 K [4, Ch. 3]. This process on the whole can be equivocated to boiling and shares many qualities with boiling but is complicated by the fluid dynamics of the system [4, Ch. 1].

This study focuses on internal pipe flow cavitation. Certain dimensionless parameters are used in the study of cavitation. The definitions of these parameters depend on the geometry under investigation and whether the flow is internal or external. The definitions that will be used in this work include the Cavitation Number, K .

$$K = \frac{P_1 - P_v}{P_1 - P_2} \quad 1$$

and the Contraction Coefficient, C_c

$$C_c = \frac{A_{eff}}{A_{geo}} = \frac{\dot{m}}{A_{geo} \sqrt{2\rho(P_1 - P_v)}} \quad 2$$

The Cavitation Number is used to describe the ratio of the pressure drop from the upstream injection pressure to the fluid vapor pressure to that of the pressure drop across the device [6]. Cavitation Number is generally a ratio showing the relative magnitudes of the stability of the fluid

state (pressure above saturation line) to the pressure drop across the device. The closer the cavitation number approaches to $K = 1.0$ the more likely it is to cavitate as the conditions that the fluid is being exposed to are approaching the stability limit of the fluid. A value of $K \leq 1$ indicates flashing flow in which the downstream fluid never re-collapses to a liquid state. A flow will cavitate when the Cavitation Number drops below a critical value (K_{crit}). The Critical Cavitation Number depends largely on the condition of solid boundaries, partial pressure of dissolved gases, turbulent and viscous effects, and dissolved solids in the water. All of these decrease the tensile strength of water or create local areas of lower static pressure such that the working fluid can more easily flash to a gaseous state [4, Ch. 1], [7].

For general fluid flows not undergoing cavitation, Discharge Coefficient is a parameter of use to describe the effective flow area during that regime of flow.

$$C_D = \frac{A_{eff}}{A_{geo}} = \frac{\dot{m}}{A_{geo}\sqrt{2\rho(P_1 - P_2)}} \quad 3$$

The two parameters are related through the Cavitation Number.

$$\frac{C_D}{C_c} = \sqrt{K} \quad 4$$

Figure 1 shows the relative locations of the upstream condition (1), the downstream condition (2), and the throat condition at the narrow point of the vena contracta (c). In quasi-steady-state operation the pressure at the location of the vena contracta can be assumed to equal across the liquid-vapor boundary. This assumption leads to the equation of mass flow through a cavitating orifice listed in Equation 5.

$$\dot{m} = C_c A_{geo} \sqrt{2\rho(P_1 - P_v)} \quad 5$$

The Contraction Coefficient in Equation 5 is a ratio of the reduced effective orifice throat area and the actual orifice throat area. This reduction in area is due to the vena contracta in the

inlet of the orifice when cavitation occurs [6]. This is illustrated in Figure 1. The Contraction Coefficient can be affected by the surface finish, increasing boundary layer thickness, and viscous losses at the walls.

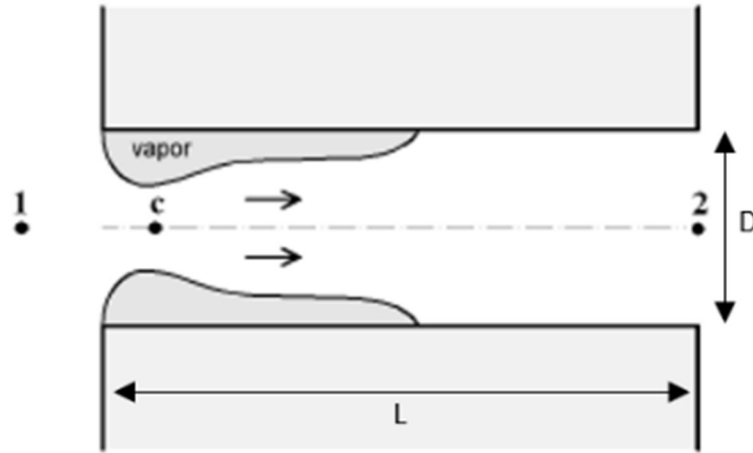


Figure 1: Vena Contracta in the Nurick Model of Cavitation [8]

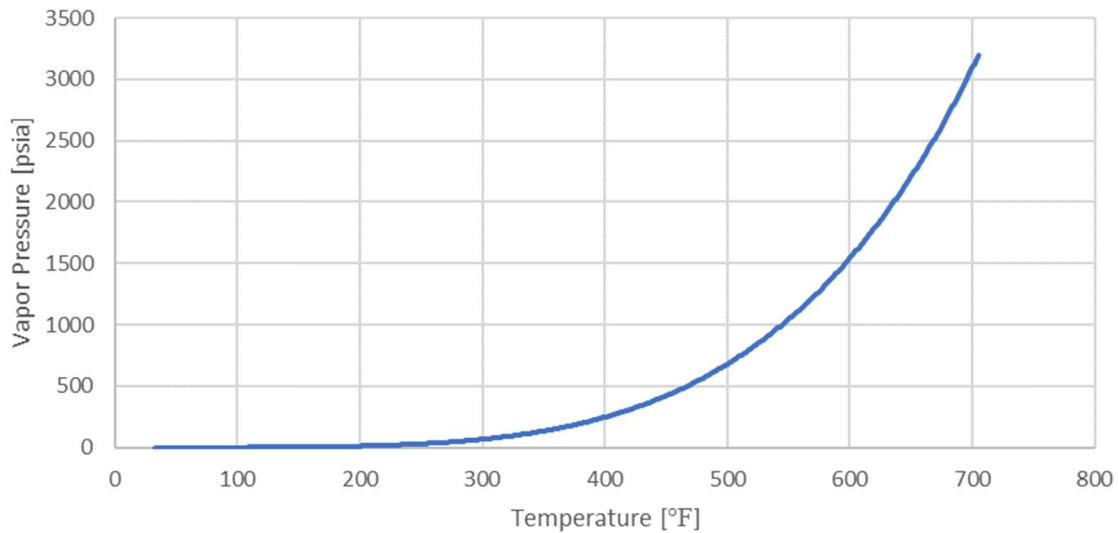


Figure 2: Temperature vs Vapor Pressure Curve for Water [9]

The Vapor Pressure curve [9] for water is shown in Figure 2. Water has a large range of available vapor pressures by increasing the fluid temperature. Figure 3 shows the Vapor Pressure curves [9] for Hydrogen, Oxygen, and Methane. Water is used as a simulant for those propellants

in flow characterization and can be heated to increase its vapor pressure to simulate the vapor pressure conditions for those propellants in cavitating flows.

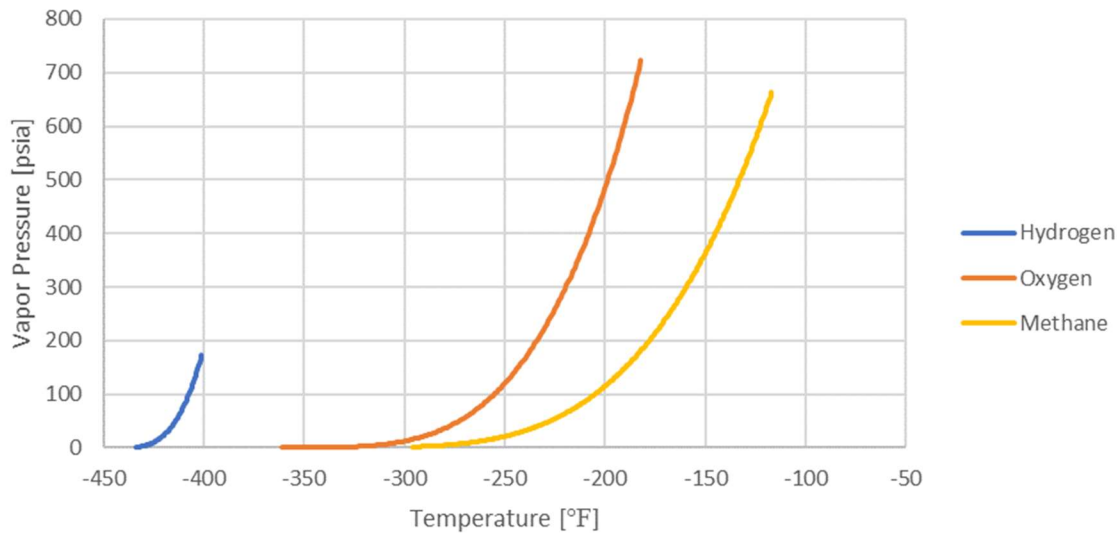


Figure 3: LH₂, LO₂, and LCH₄ Vapor Pressure [9]

2.1.1 Homogeneous Cavitation vs Heterogeneous Cavitation

Cavitation is affected by the properties of the liquid flowing. In the absence of solid-liquid boundaries and contamination of dissolved solids, the fluid undergoes cavitation as microscopic fluid voids grow to create bubbles in the flow. This is considered Homogeneous Cavitation. Heterogeneous Cavitation on the other hand requires nucleation sites to catalyze the creation of bubbles. In most engineering flows heterogeneous cavitation occurs given the inherent gasification of water, presence of dissolved solids (solid particle contaminants in the water such as dirt and dust), and solid boundaries (locations where the liquid water contacts non-liquid surfaces such as the surfaces of a propeller blade) [4, Ch. 1], [7]. Figure 4 shows the effects of water treatment on the reduction of sites for nucleation of cavitation. With filtered water free of sizable solid particles, the available number of nucleation sites decreases compared to that of

untreated water. Additionally, degassing the water reduces the number of air bubbles which can form voids in the water prematurely. These nucleation sites can lead to onset of cavitation at a higher Cavitation Number.

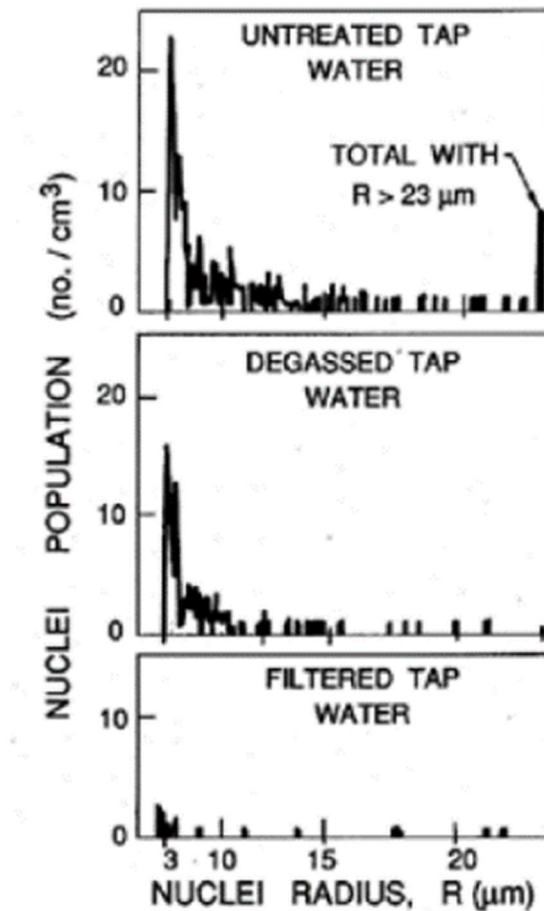


Figure 4: Comparing Nucleation Site Quantity in Untreated, Degassed, Filtered Tap Water [4, Ch. 1]

2.1.2 Bubble Collapse and Damage

With the creation of bubbles in the flow those bubbles will inevitably collapse. Bubble collapse can be used as a useful tool for mixing as well as a detrimental consequence causing damage to components. Damage is a less desired consequence of cavitation and one that a fluid system designer works to avoid. Investigations into the mechanics of bubble collapse damage and

conditions in which it is prevalent have been performed by a number of individuals [4], [5], [10]–[15].

The bubble collapse, given the high tensile capability of water [4, Ch. 1], [7] can carve into surfaces and create large amounts of damage to parts. This is caused by the large pressure differentials caused by the bubble, temperature increases at the collapse site, and high-amplitude acoustic effects upon collapse. Knapp [10] investigated the mechanics of fixed-type cavitation which refers to flows over static objects. His findings show a great deal of erosion due to the cyclical process of a re-entrant jet, shown in Figure 5, causing a shedding of a cavitation bubble and this bubble collapsing on the surface. Though, with fixed-type cavitation (cavitation over a fixed, non-moving geometry), Knapp found that this occurred very infrequently and therefore postulated that the effect of bubble collapse impingement on the fixed solid boundary operated at a high magnitude of force over larger time scales near 100 minutes for his samples. This is inherently different from that of cavitation with a moving boundary such as that of a propeller or pump.

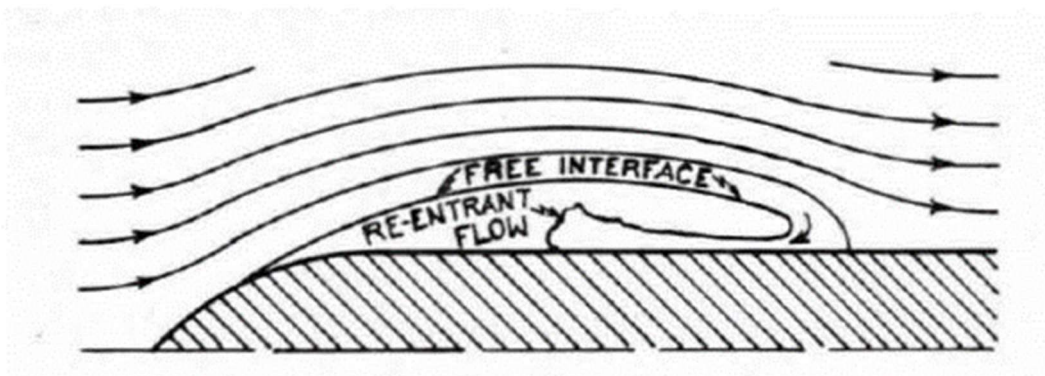


Figure 5: Fixed-Type Cavitation w/ Re-Entrant Jet [10]

Moving boundary cavitation deals with a moving solid-liquid boundary. When these surfaces move into the path of a shed, collapsing bubble, that bubble can then impinge and collapse on the surface. This explains a larger degree of damage in rotating systems such as pumps,

propellers, and other rotating machinery. Hammitt et al [11] detailed that pitting damage in flow geometry is locally random. Additionally, they determined previous damage due to bubble impact does not affect the location of future bubble impacts with the exception for extreme impact events which can create gouged areas with enough surface deformation to create local cavitation formation at that pit. Stinebring et al experimentally corroborated scaling laws for this damage and found that the rate of damage events (pits) scales with the sixth power of fluid velocity over the surface and the size of the damage in these events scales with the fifth power of fluid velocity [12]. This underscores the severity of cavitation in restrictive flow devices for long term use.

2.1.3 Analytical Modeling

Computational Flow Dynamics (CFD) and numerical modeling of cavitation under certain flow and geometrical conditions has been performed to predict the possibility of cavitation in specific flows and flow devices. Studies have been performed on the exit flow of cavitating devices used in spray generation [16], the application of previous literature and concepts to exceedingly high pressure fluid devices [1], and the effects of roughness [3] [17].

Schmidt and Corradini investigated the exit flow condition from cavitating devices and found that slug flow models for exit flow of a cavitating nozzle do not correctly account for the effects at the wall from the vapor pocket creating a local region of zero wall shear. With inclusion of the assumption of zero wall shear this one-dimensional model more closely matches that of accepted experimental data for cavitating flows as well as multi-dimensional CFD models [16].

Ebrahimi et al applied work on cavitation to high pressure flows (3000 – 7000 psia) and long L/D orifices ($L/D > 1.0$) to create models for geometries and conditions more routinely seen in engineering practice. The findings again show that cavitation scales with cavitation number

rather than pressure and the critical cavitation number of 1.81 is not outside of the values found in literature. For a long L/D orifice, it was found that the flow undergoes a double expansion, with one expansion occurring in the orifice from the vena contracta to the wall after the vena contracta and the second occurring from the orifice to the downstream pipe. Downstream pipe flow additionally seems to have a small impact on the contraction coefficient upstream [1].

Echouchene et al investigated roughness in cavitating orifices. They utilized the modified law of the wall [18] to account for the internal roughness. They found that with low injection pressure, increasing roughness height reduces C_D . Additional observation of the analysis shows that the onset of cavitation is delayed in rough parts [3]. These observations can be seen in Figure 6. Other investigations with sheet cavitation show limited to no effect of roughness on the flow [19].

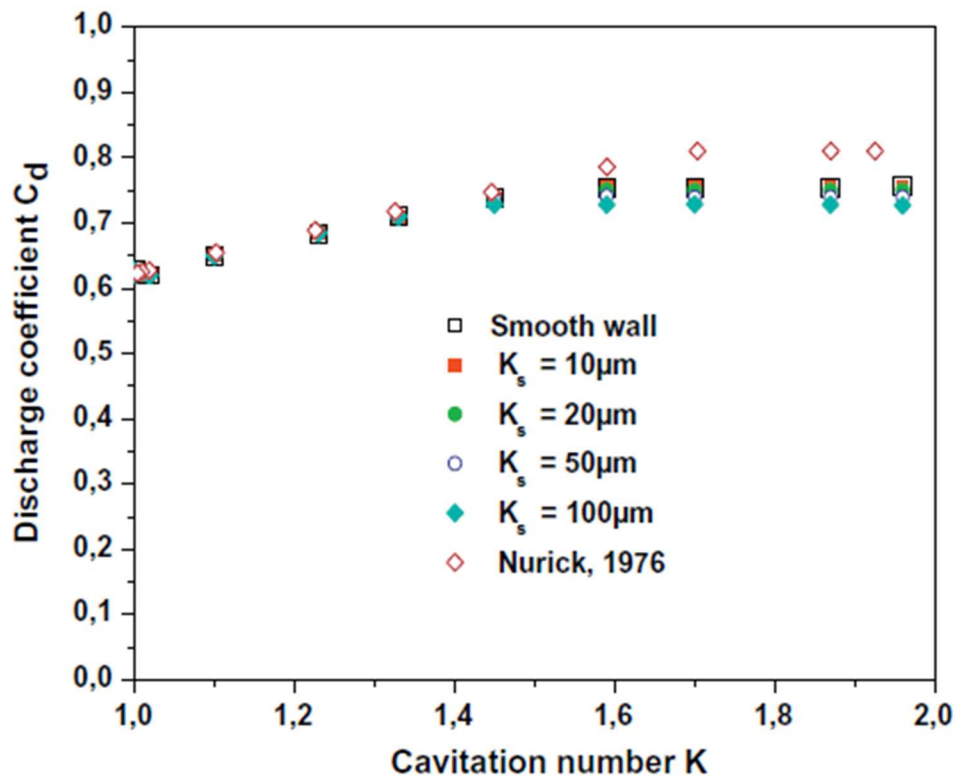


Figure 6: C_D vs K Prediction with Roughness Model [3]

2.1.4 Other Phenomena

Vortex whistling is another phenomena found with orifice devices [20]–[26]. Vortex whistling occurs with turbulence and vortex shedding in the orifice. The conditions for vortex shedding can be determined from the Strouhal Number,

$$St_X = \frac{f \cdot X}{V}, \quad 6$$

Common values for the orifice thickness Strouhal number (St_t) where vortex shedding occurs in orifice devices ranges from 0.2 – 0.35 [20]–[23], [25], [26]. Additional definitions are based on the cavitation cavity length [27] and on the diameter of the orifice. [26].

The high-frequency environment derived from vortex shedding can be determined by calculating the peak Strouhal number [25] from equation 7

$$St_p = 0.2420 \left(1 + \frac{31.69}{\sqrt{Re}} - 0.0657 \frac{D}{D-d} \right), Re \gg 5 \times 10^3 \quad 7$$

This value coincides with the expected frequency at which the maximum energy peak will occur, therefore when whistling occurs. Other dimensionless terms include the Reynolds-Strouhal number, which can more accurately account for mechanics at low flow rates.

$$Re/St = \frac{f \cdot d^2}{\nu} \quad 8$$

2.1.5 Sharp Edge inlet Orifices

One of the earlier works in cavitation was done by W.H. Nurick [8]. This work determined cavitation characteristics for sharp edge inlet orifices and the effect of cavitation on mixing of propellants [8]. Hydraulic flip is a phenomenon in which the cavitation bubble no longer reattaches to the wall of the orifice and instead attaches to the free stream atmospheric flow, this can lead to

a drastic change in flow characteristics and halt all the cavitation shedding processes as shown in Figure 8. Nurick, by using various length to diameter (L/D) factors for his orifices as shown in Figure 7 found that the L/D to limit hydraulic flip under their conditions was an L/D of 20. In Figure 7 the operation of the orifices over a range of cavitation numbers can be seen with the tell-tale sloping reduction in discharge coefficient in each plot once the flow starts to cavitate. The hydraulic flip can be seen when the discharge coefficient decreases promptly with a small decrease in cavitation number. Additionally, Nurick cited the theoretical value for the contraction coefficient at 0.62. This value was derived from Borda-Carnot losses which dictate fluid losses for flow geometries with a sudden change in cross sectional area. Howland and Richetta [28] derive this in full from the conservation of momentum and assumptions of the velocity field around the orifice and determined the theoretical contraction coefficient value to be 0.611[28]. Nurick found the cavitation onset to occur at $K = 1.45$ for an $L/D = 20$ with smooth bore, sharp edge inlet orifices.

Desantes et al [6] investigated similar geometry in a diesel injector and additionally found that while the mass flux of a cavitating venturi is dependent solely on the upstream pressure, the momentum flux is continually varying with backpressure which translates into continuously increasing downstream velocity with decreasing backpressure.

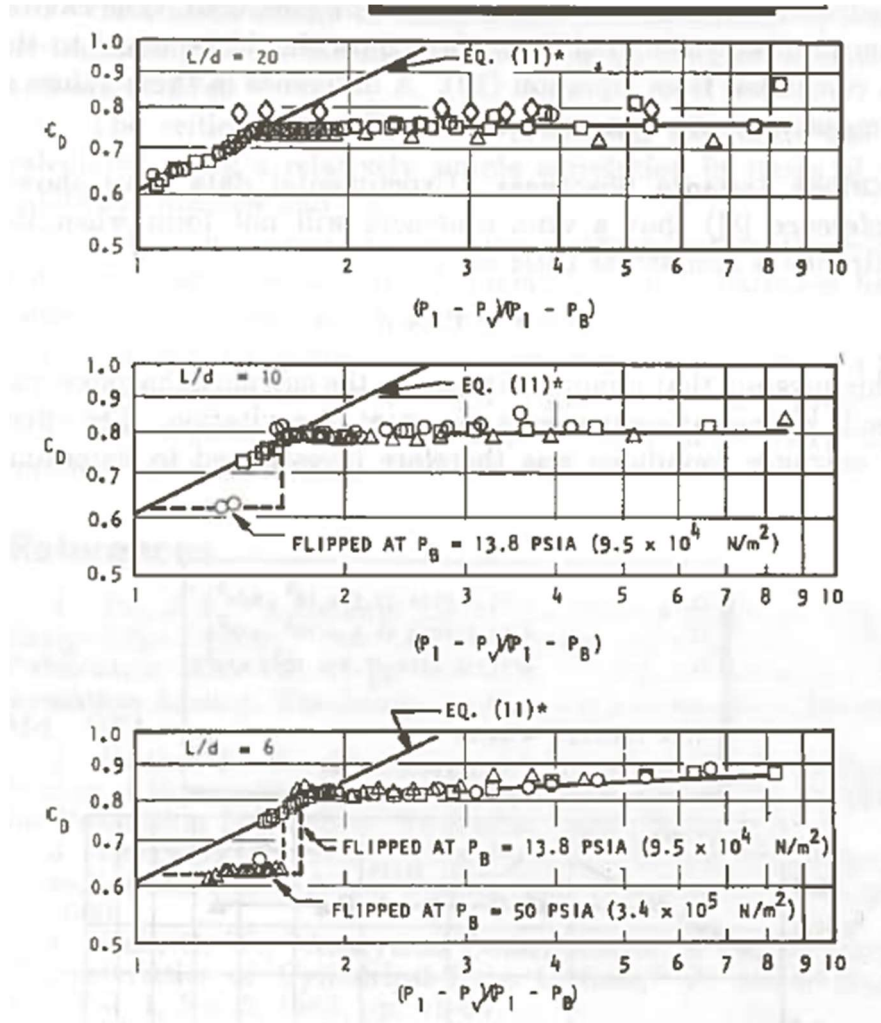


Figure 7: C_D vs K at differing L/D ratios [8]

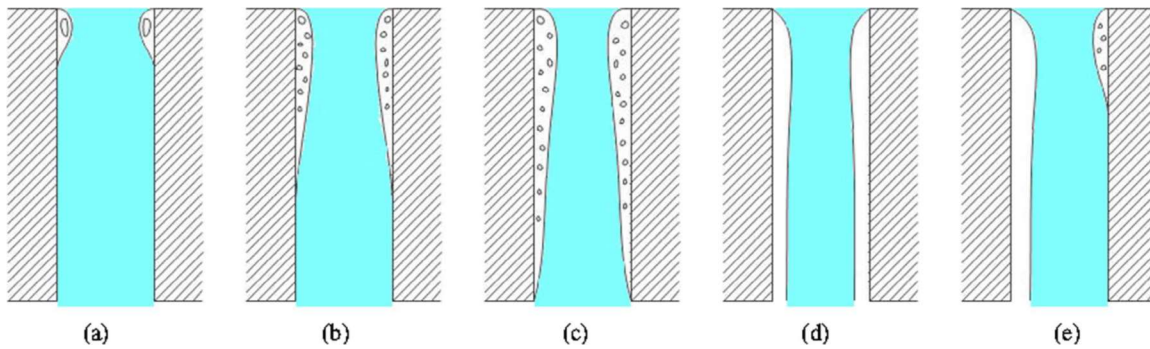


Figure 8: Representations of vapor cavity characteristics in (a) Inception, (b) Growth, (c) Supercavitation, (d) Flip, (e) Asymmetry[29]

Additional qualities of sharp edge inlet orifices are that the inlet radius into the orifice diameter influences the contraction coefficient as noted by Nurick [8] in Equation 9.

$$(C_c)_{\frac{r}{d}} = \left[\left(\frac{1}{(C_c)_{\frac{r}{d}=0}} \right)^2 - 11.4 \left(\frac{r}{d} \right) \right]^{-\frac{1}{2}} \quad 9$$

This was an additional influence on the investigated qualities of the venturis outside of the roughness and was accounted for in the final results. This effect is shown in Figure 9. The increases in inlet radius increases the contraction coefficient thereby increasing the effective flow area. This is due to lesser angle of separation from the bore of the orifice. This leads to the implication of why a venturi style geometry has a higher effective flow area than a similarly sized orifice.

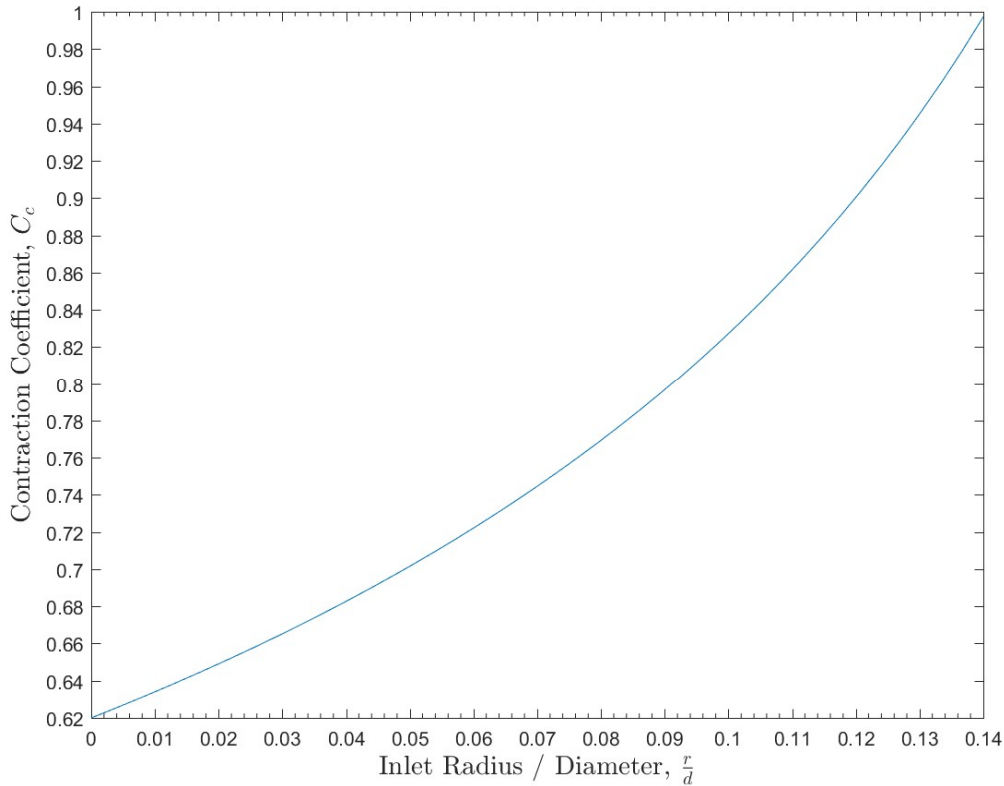


Figure 9: Contraction Coefficient as a function of the ratio of inlet radius and bore diameter [8]

Cui et al [29] investigated the effects of geometric irregularities such as conicality, inclinality, diameter errors, on the cavitation in an orifice. The experimental findings suggest that smaller diameter orifices cavitate and hydraulically flip at a lower upstream pressure at controlled downstream pressures compared to larger diameters. Divergent conicality achieves the same purpose by accelerating the flow and leading to a decrease in the required injection pressure to cavitate and the increase in critical cavitation number required.

2.1.6 Converging-Diverging Nozzles

Converging-Diverging Nozzles are used in a variety of applications. Notably they are used in mass flow measurement or control in the form of venturis. These devices use the Bernoulli principle to measure the flow of fluid by measuring the reduction in pressure between the inlet and the throat. This reduction in pressure can be correlated to a mass flow knowing the condition of the fluid. Undesired cavitation can limit the range of mass flow measurement and affect the accuracy of the measurement. Additionally, cavitation causes a large amount of pressure loss, which in the case of these devices is not always the desired outcome. Cavitating Venturis are designed to use this method of cavitation in the device to allow for a mass flow measurement using a single pressure measurement from the upstream location with a larger effective flow area than that of an orifice.[30]

2.1.7 Summary of Cavitation and Geometry Downselect

The choice of a long L/D sharp edge inlet orifice is made in order to exploit the differences caused by surface roughness. This includes hydraulic flip, reduced contraction coefficient, and a difference in the conditions needed for cavitation onset. Sharp edge inlet orifices have an already

existing database of knowledge and therefore the effects of roughness can be seen in comparison. Additionally, as the damage due to cavitation is not under investigation, using a fixed-type geometry reduces the likelihood of damage to the samples during testing allowing for a greater amount of repeatability between tests without accounting for damage due to bubble collapse

Section	Topic	Comments	References
Homogeneous and Heterogeneous Cavitation	Homogeneous Cavitation	<ul style="list-style-type: none"> - Devoid of boundaries - Assumes perfect fluid - Uncommon in engineering flows 	[4], [7]
	Heterogeneous Cavitation	<ul style="list-style-type: none"> - Most engineering flows - Explains increases in cavitation at nucleation sites - Found in flows with solid-liquid boundaries 	[4], [7]
Bubble Collapse & Damage	Damage	<ul style="list-style-type: none"> - Damage occurs on long timescales w/ fixed type cavitation - Damage scales w/ 5th power of fluid velocity 	[4], [5], [7], [10]–[15]
Analytical Modeling	Roughness	<ul style="list-style-type: none"> - leads to reduction in C_D and K_{crit} 	[3], [7]
	Exit Flows	<ul style="list-style-type: none"> - cavitation does not lead to a perfect slug flow at exit 	[16]
Other Phenomena	High-Frequency Environment	<ul style="list-style-type: none"> - Strouhal number determines the possibility for whistling - Dependent on fluid velocity 	[20]–[27]
Sharp edge inlet Orifices	General	<ul style="list-style-type: none"> - Theoretical $C_c = 0.611$ - Simplistic geometry - $L/D = 20$ for no hydraulic flip 	[6], [8], [28]
	Geometry Differences	<ul style="list-style-type: none"> - Inlet radius increases C_c - Divergent Conicality and decreases in orifice diameter leads to slight increases in K_{crit} 	[29]
C-D Nozzles	General	<ul style="list-style-type: none"> - radius increases C_c - angle of entrance increases C_c 	[30]

2.2 Overview of Manufacturing Technologies

Manufacturing of fluid systems has changed over the last 60 years. Manufacturing methods have expanded to include additive manufacturing specifically in the last couple decades. The first commercial use of additive manufacturing occurred in 1987 with Stereolithography and over the course of time, with the expiration of key patents, introductions of lower cost systems has permeated the market and led to greater adoption with a growing consumer base [31]. Additive manufacturing typically adds material in contrast to subtractive manufacturing which removes material [32] [33]. Manufacturing methods span materials, with many of these methods being applied to plastics and metals alike with adjustments made depending on the material. Additive manufacturing methods include Fused Filament Fabrication/ Fused Deposition Modeling (FFF/FDM), Selective Laser Sintering (SLS), and Selective Laser Melting (SLM). The selection of the process is determined by desired feature resolution, the physical size of the part to be manufactured, and desired surface condition and therefore is determined on a case-by-case basis for individual parts.

2.2.1 Fused Filament Fabrication/Fused Deposition Modeling Technology

Fused Filament Fabrication (FFF) or Fused Deposition Modeling (FDM) are both names for a system of additive manufacturing in which layers are produced through the heating up and extrusion of thermoforming or thermosetting plastics through a nozzle [32]. This method was first brought to market commercially by Stratasys in 1991 and through the timely release of patents has seen large adoption in the conventional consumer base [31].

Figure 10 shows the method by which parts are created by FDM printing. The diagram shows the extruder head which contains a heater and extrusion mechanism to heat the

thermoplastics up to the point of transition and squeeze the plastic through a nozzle of a certain diameter. This is then deposited onto a platform which moves in the X-Y plane while the extrusion head moves in the Y direction. Mechanical factors which affect the dimensional accuracy of this manufacturing method and therefore the roughness are the stepper motor precision, quality of mechanical assembly, drive system design (cartesian vs. delta), filament quality, nozzle diameter, and calibration method. Positional accuracy for a printer can be on the order of 0.1 mm (~ 0.005 in) for consumer printers [34]. With industrial grade printers these values do not appreciably increase but their repeatability increases greatly [35]. The build orientation and toolpath of the printer also has a large impact on the final roughness. Software Factors which affect dimensional accuracy and roughness include the sequence to print contours (inside out vs outside in), the number of contours, constant extrusion vs variable extrusion for thin wall treatment, infill/hatch overlap with contours, infill/hatch spacing, layer height, extrusion width, etc. This is all optimized by the manufacturing engineer in order to meet requirements. Examples of build orientation include whether to orient holes with the long axis perpendicular to the build table or parallel. The former orientation yields a much cleaner geometry with the latter suffering with bad surface condition on one side of the hole.

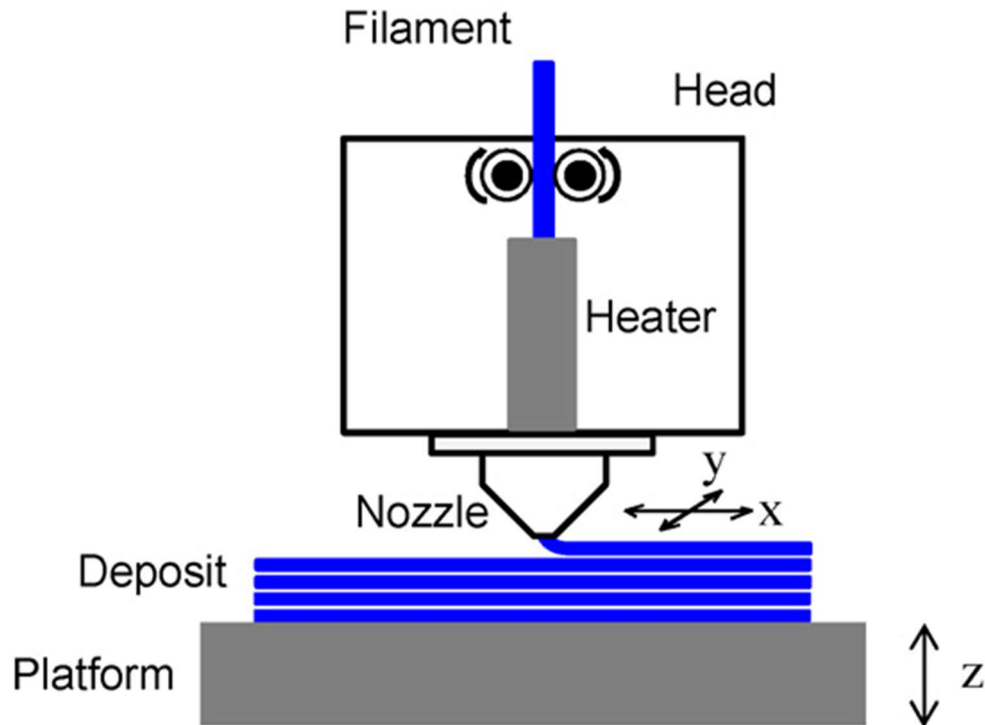


Figure 10: FDM Printing Method [32]

This method of depositing a part layer by layer creates a stair step effect in the finished part which creates a distinct waviness/roughness pattern to the part. This can be shown in Figure 11 from a test sample used in this work using 1.74mm filament size and a 300 μm z-height. Clear ridges can be seen in the part.

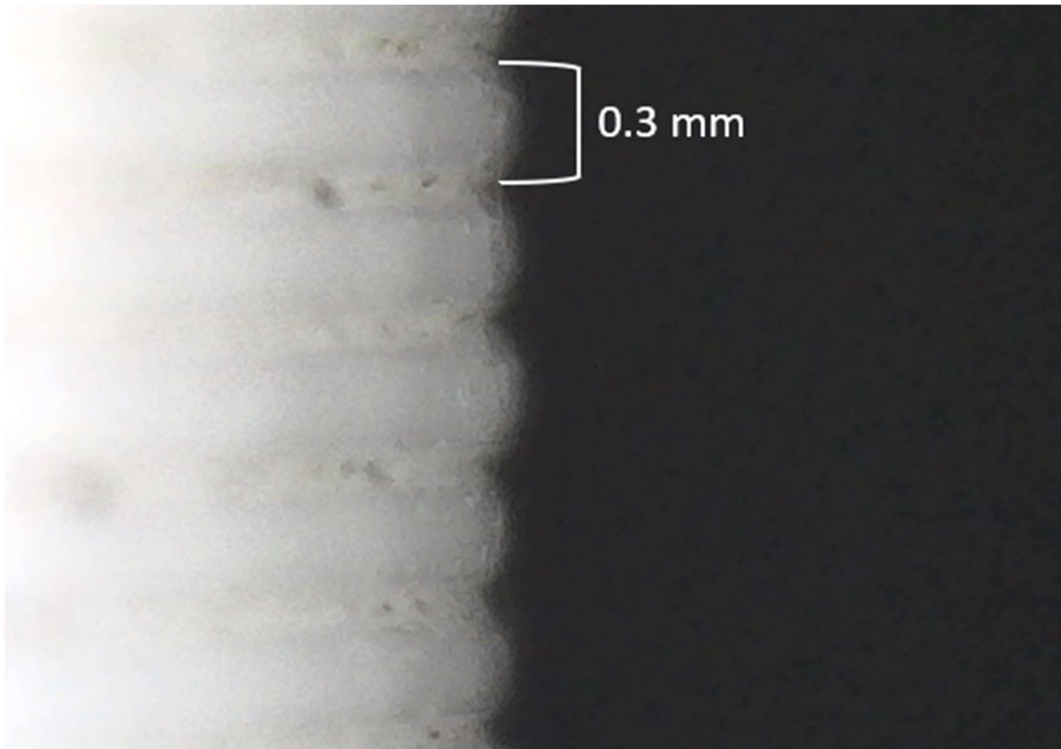


Figure 11: FDM Sample Waviness Pattern

2.2.2 SLS/SLM Technology

Selective Laser Sintering (SLS) and Selective Laser Melting (SLM) are both powder-based additive manufacturing technologies [33]. An illustration of how this system works is shown in Figure 12. In the figure a powder supply and build platform can be seen. During printing the roller moves a thin layer of powder to the platform and the mirrors move the laser through the toolpath to sinter or melt the powder to the build plate. After the layer is complete the platform lowers and another layer of powder is moved from the powder supply and process of sintering or melting is repeated. Both FDM and SLS/SLM systems use a layered process to create parts but unlike FDM the feedstock to create the parts is a powder.

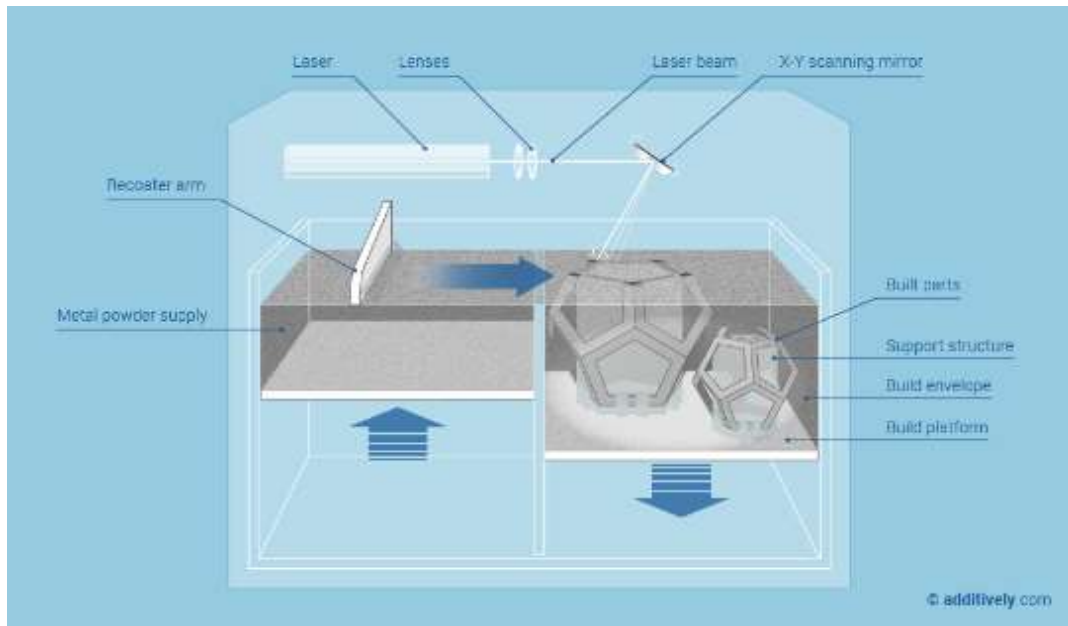


Figure 12: Illustration of SLS/SLM Printing¹

Additionally, upon close examination, irregularities in the parts surface can be seen where powder was inadvertently sintered or melted on to the surface. This is shown in Figure 13. Positional accuracy and repeatability of these machines is on the same order of industrial grade FDM printers with less than 0.05 mm accuracy. The major driver of the roughness in these parts is build orientation and layer thickness much like that of FDM printers. Unlike FDM printers, SLM and SLS printers suffer from an issue of “balling” wherein unintended particles are sintered to the part surface leading to issues in lamination of the next layers and unintended porosity [33].

¹ Obtained from Additively.com, <https://www.additively.com/en/learn-about/laser-melting>

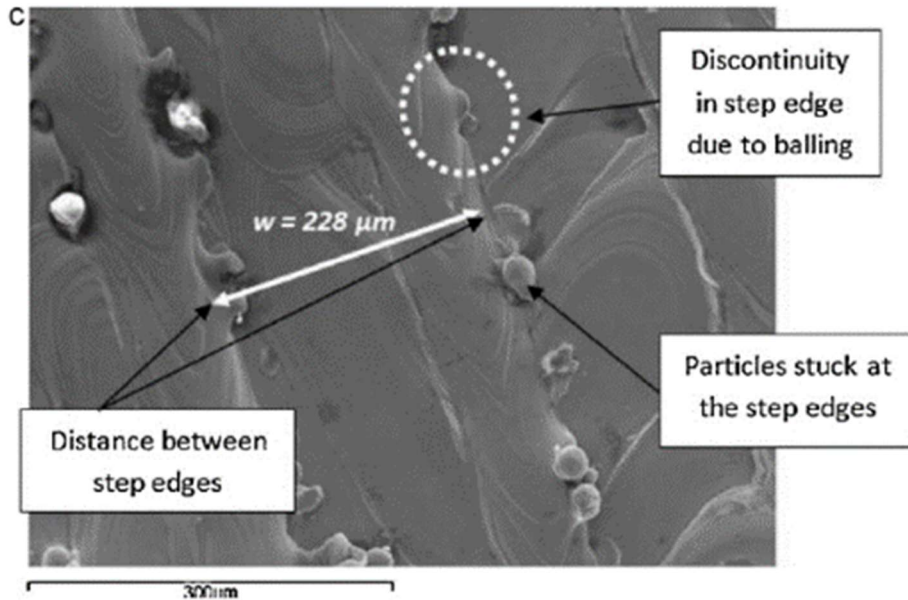


Figure 13: Surface Irregularities in SLM Printing [1]

2.2.3 Subtractive Manufacturing

Subtractive manufacturing is a common method through which parts are created by the process of removing material from a larger amount of raw material. Methods used include milling, drilling, turning, electrical discharge machining, abrasive flow machining, abrasive jet machining, electrochemical machining, etc. These methods and the subsequent post finishing processes affect the roughness patterns and degree of roughness. A chart of ranges for different post finishing processes is shown in Figure 14.

Indicative surface roughness comparisons

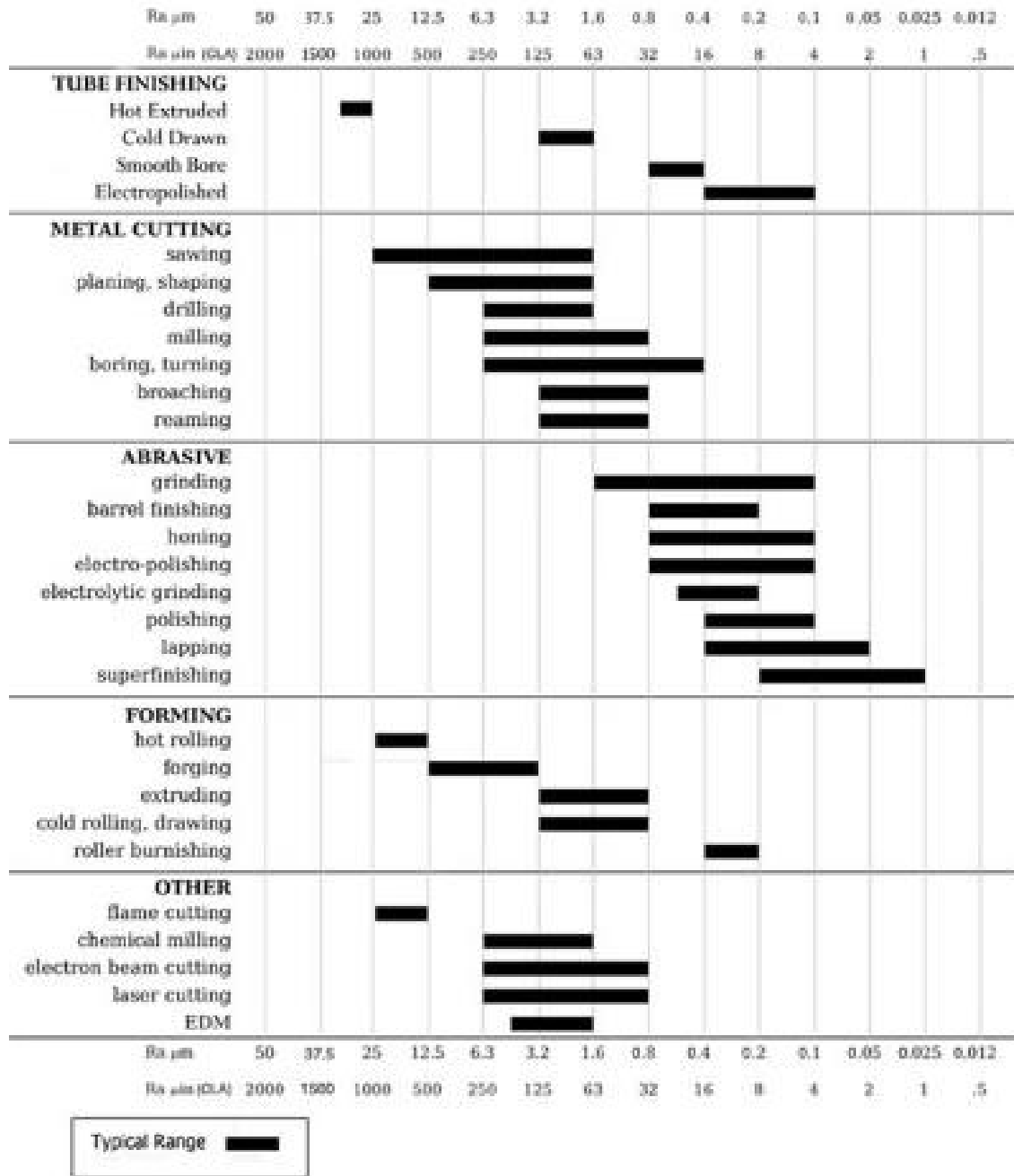


Figure 14: Surface Roughness Comparisons²

² Obtained from cnccookbook.com, <https://www.cnccookbook.com/surface-finish-chart-symbols-measure-calculators/>

Subtractive manufacturing is also traditionally used as a post-finishing processes for additive manufacturing processes and casting processes. This stems from the desire to remove the surface finish imperfections of SLS/SLM parts and create surface finishes similar to that of subtractively manufactured parts.

2.2.4 Summary of Manufacturing Technologies and Downselect of Manufacturing Methods

The chosen manufacturing technologies for this study span a range of expected roughnesses as shown in Figure 15. These also span a range of investment in a part's production with the FDM being the minimal investment in money and time and the subtractive manufacturing being the greatest in personnel time and cost. The manufacturing processes downselection to FDM, SLM, and subtractive processes was made in order to create a broad spectrum of processes found in engineering. The subtractive process is chosen in order to define a baseline. Both the FDM and SLM processes were chosen given their prevalence in additive manufacturing.

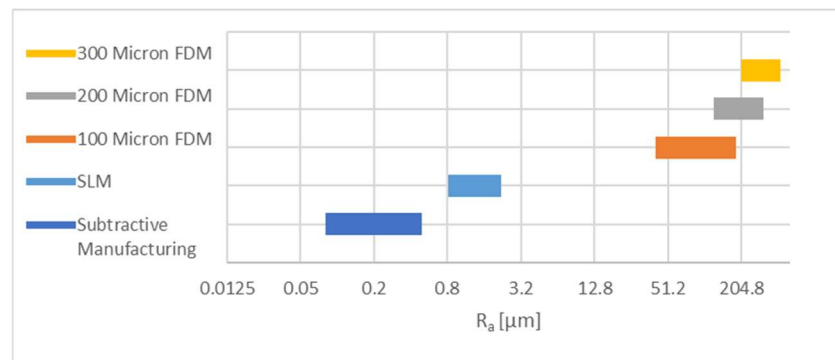


Figure 15: Comparison of Expected Roughnesses for chosen technologies

CHAPTER 3

TEST SYSTEM DESIGN & OPERATION

3.1 Choice of Geometry

The choice of system of interest dictates the choice of geometry. The interest of this study is long L/D sharp edge inlet orifices such as that commonly used in impinging injectors for liquid propellant rocket engines as well as flow control orifices in process control systems. Therefore, a long L/D sharp edge inlet orifice was chosen. An L/D of 20 was chosen in order to ensure hydraulic flip was not an issue. Inlet edge radius was maintained to as sharp as feasible with the process used and subsequently measured using a Form Talysurf surface profilometer.

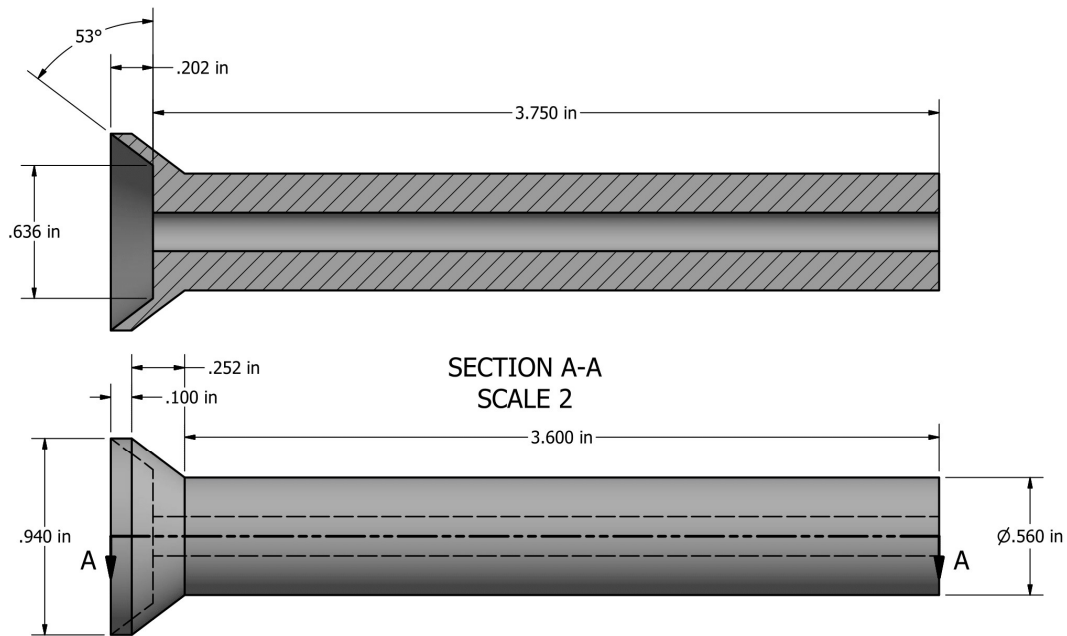


Figure 16: Design Geometry for Samples

3.2 Choice of Manufacturing Methods and Materials

In order to have a breadth of methods and subsequent surface finishes, five separate manufacturing conditions were chosen. This included three conditions of FDM, one SLM, and one Subtractively Manufactured. FDM used PLA 1.75 mm filament (1.74 mm measured) with settings optimized for the part geometry printed on a Rostock MAX V3 printer. The only allowable difference between the three different conditions is the programmed layer height, varying as 100 μm , 200 μm , and 300 μm . For the SLM condition a university partner, ASRC Federal Technical Services Propulsion Engineering Center, donated the time and material to print the test geometry on a Conceptlaser M2 using Monel K500. The M2 has a build volume of 250 x 250 x 350 mm and a layer thickness range of 20 - 80 μm with a focus diameter of 50 μm . The exact settings for the SLM printing are contained in Appendix L. For all of the printed conditions the part geometry was printed with the long axis perpendicular to the print bed with contour passes to increase model dimensional accuracy and surface condition.

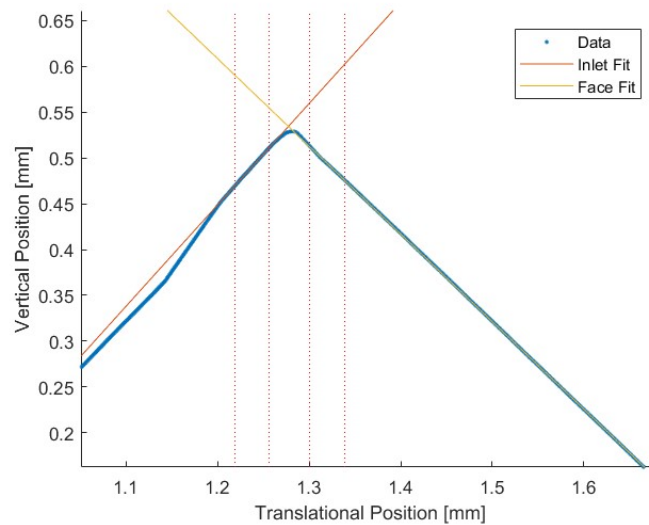
The subtractively manufactured part was made on a Haas TL-1 CNC lathe using Aluminum 6061 bar stock. The subtractively manufactured condition samples (4) were twist drilled using a #15 drill bit, reamed with a 0.1875" reamer, and then honed successively at 320, 600, and 800 grit using silicon carbide flex-hones with final treatment of an abrasive aluminum polish. These parts were, in post, sharpened by using the lathe to take 0.002" off the inlet face returning the orifice to its condition prior to bore polishing. These defining manufacturing features are summarized in Table 1.

Table 1: Configuration Summary

Sample	Defining Features
100 μm FDM	100 μm layer height, FDM, PLA Material, 1.74 mm dia feedstock
200 μm FDM	200 μm layer height, FDM, PLA Material, 1.74 mm dia feedstock
300 μm FDM	300 μm layer height, FDM, PLA Material, 1.74 mm dia feedstock
SLM	Laser Melting, Monel K500 Material, 45 μm Average Powder Size
Subtractively Manufactured	Turned, Reamed, Honed, and Polished 800 grit. Aluminum 6061 Material

3.3 Physical Dimensions, Surface Roughness, and Inlet Radius Data

The inlet radius of the parts was measured using a Form Talysurf Profilometer with a 60 mm long diamond tipped stylus allowing for a resolution of 10 nm. All data was analyzed in Matlab[36]. After finding the linear fit of the profile line of both the inlet bore and the outside face (as shown in Figure 17), an intersection point is found and the translation position value is used as a “zero” point and a half-width is defined.

**Figure 17: Example of Inlet Radius Fit Methodology**

A circular curve fit is used to fit an appropriate radius in this area of interest. This is completed for a predetermined set of half-widths and the results are filtered with a floor of 0.0001 in radius and a ceiling of 0.010 in radius. After filtering, the mode of the radius values is determined for each dataset and the average across all datasets for the same part is made. This value is then accepted as the inlet radius for that part. The inlet radii for each part is listed in Table 2.

Table 2: Test Sample Inlet Radii

Sample	Inlet Radius	Sample	Inlet Radius	Sample	Inlet Radius
Subtractive	#1 0.00129 in	300 μm	#1 0.006285 in	200 μm	#1 0.005003 in
	#2 0.00079 in		#2 0.006692 in		#2 0.004117 in
	#3 0.00155 in		#3 0.006331 in		#3 0.004746 in
	#4 0.00114 in		#4 0.005926 in	100 μm	#1 0.002362 in
SLM	#1 0.00322 in		#5 0.006562 in		#2 0.003102 in
	#2 0.00416 in				#3 0.002866 in
	#3 0.00321 in				
	#4 0.00493 in				

The roughness of the parts interior bores was additionally measured using a Form Talysurf Profilometer with a 60 mm long diamond tipped stylus. The Talysurf used five sample lengths in each evaluation length of 12.5 to 13mm. This evaluation length was then used to find an arithmetic mean roughness (Ra), root mean squared roughness (Rq), highest peak (Rp), lowest valley (Rv), mean roughness spacing (Sm), peak-to-peak spacing, as well as many other variables. These values are shown in Table 3 and the procedure, background, and full dataset related to the roughness of the parts is included in Appendix J.

Table 3: Test Article Roughness

	100 μm FDM #4	200 μm FDM #3	300 μm FDM #1	SLM #1	Subtractive #1	Subtractive #2
Ra [μm]	14.266	19.108	26.851	5.959	0.372	0.262
Rq [μm]	18.100	24.191	33.486	7.915	0.468	0.391
Rsk [μm]	-0.200	-0.378	-0.156	1.122	-0.089	-0.867
Rku [μm]	3.367	3.389	3.144	4.933	4.167	6.644
Delq [$^{\circ}$]	29.881	32.411	32.982	16.294	0.326	0.431
Lamq [μm]	199.124	239.672	322.422	169.244	494.344	335.229
S [μm]	105.324	185.294	291.024	99.034	79.742	60.621
Sm [μm]	176.759	244.900	338.544	223.771	296.371	340.601
R3z [μm]	60.104	78.383	97.932	29.733	1.247	0.914
R3y [μm]	77.196	101.226	116.745	35.756	1.765	1.635
Rp [μm]	47.743	63.999	87.880	33.266	1.185	0.841
Rv [μm]	60.472	81.974	97.473	18.444	1.662	1.900
Rt [μm]	108.215	145.973	185.353	51.710	2.847	2.741
Rtm [μm]	84.067	106.785	135.771	41.856	1.614	1.348
Rpm [μm]	37.537	47.300	57.552	27.452	0.731	0.506
Ry [μm]	103.494	137.209	181.499	49.273	2.596	2.417

The physical dimensions of the orifice in the part is documented in Table 4. This table includes information on the inlet and outlet diameters (measured using pin gages) and allows for us to see what degree of conicality the test articles have.

Table 4: Test Article Dimensions

Sample		Inlet Diameter	Outlet Diameter
Subtractive	#1	0.1920 in	0.1920 in
	#2	0.1900 in	0.1920 in
	#3	0.1920 in	0.1920 in
	#4	0.1900 in	0.1920 in
SLM	#1	0.1870 in	0.1850 in
	#2	0.1870 in	0.1850 in
	#3	0.1870 in	0.1860 in
	#4	0.1870 in	0.1850 in
300 μm	#1	0.1810 in	0.1820 in
	#2	0.1800 in	0.1810 in
	#3	0.1800 in	0.1810 in
	#4	0.1800 in	0.1810 in
	#5	0.1800 in	0.1810 in
200 μm	#1	0.1800 in	0.1810 in
	#2	0.1800 in	0.1820 in
	#3	0.1800 in	0.1810 in
100 μm	#1	0.1800 in	0.1850 in
	#2	0.1800 in	0.1850 in
	#3	0.1810 in	0.1860 in

3.4 Planned Test Conditions

Forty-Five Tests in this work were planned with a profile from $K=1.6$ to $K=1.0$ and a constant upstream pressure of 500 psig. This choice of upstream pressure was to allow for ample flexibility in attaining very low cavitation numbers close to 1.0. The choice of an upper bound of $K = 1.6$ came from reviews of other experiments and with the understanding that most likely the onset of cavitation would occur near or lower than 1.45 [2] [3]. Three test articles were to be made of each configuration and each sample was planned to be tested three times. The actual number of tests completed was sixty-six with the extra tests coming from an additional block of testing with the subtractively manufactured parts sharpened to a sharper edge as well as additionally tests performed to replace tests with less than optimal data due to underperforming back pressure

control or broken test articles. All of the test articles and the number of tests performed along with defining parameters are described in Table 5.

Table 5: Test Matrix

Block	Sample	Sample Type	K Lower	K Upper	# of Tests	Upstream Press
1	300 #0	300 μ m FDM	1.0	1.6	2	500 psig
	300 #0	300 μ m FDM	1.0	1.6	2	500 psig
	100 #0	100 μ m FDM	1.0	1.6	2	500 psig
	100 #0	100 μ m FDM	1.0	1.6	2	500 psig
2	300 #1	300 μ m FDM	1.0	1.6	1	500 psig
	300 #2	300 μ m FDM	1.0	1.6	3	500 psig
	300 #3	300 μ m FDM	1.0	1.6	3	500 psig
	300 #4	300 μ m FDM	1.0	1.6	3	500 psig
	300 #5	300 μ m FDM	1.0	1.6	3	500 psig
	200 #1	200 μ m FDM	1.0	1.6	3	500 psig
	200 #2	200 μ m FDM	1.0	1.6	3	500 psig
	200 #3	200 μ m FDM	1.0	1.6	3	500 psig
	100 #1	100 μ m FDM	1.0	1.6	3	500 psig
	100 #2	100 μ m FDM	1.0	1.6	3	500 psig
	100 #3	100 μ m FDM	1.0	1.6	3	500 psig
3	SLM #2	SLM	1.0	1.6	3	500 psig
	SLM #3	SLM	1.0	1.6	3	500 psig
	SLM #4	SLM	1.0	1.6	3	500 psig
4	SRM #2	SRM	1.0	1.6	3	500 psig
	SRM #3	SRM	1.0	1.6	3	500 psig
	SRM #4	SRM	1.0	1.6	3	500 psig
5	SRM #2	SRM Sharpened	1.0	1.6	3	500 psig
	SRM #3	SRM Sharpened	1.0	1.6	3	500 psig
	SRM #4	SRM Sharpened	1.0	1.6	3	500 psig

# Tests	66
---------	----

3.5 Inlet and Exit Conditions

The test article inlet conditions were set via the run tank pressure and set each test day to approximately 500 psig. The exact setting of the pressure does not entirely matter once the backpressure is accounted for as the experiment system operates on pressure drop over the test sample. Differences in upstream pressure only affect the minimum attainable cavitation number. Exit pressure was varied from approximately 200 psig to atmospheric pressure. The tests were

instead controlled via Cavitation Number which varied from 1.6 to 1.0 moving from no cavitation to heavy cavitation ($K \sim 1.0$) in the part. Reynolds Numbers at the inlet were of the order of 200,000 and sufficient hydrodynamic entrance length was accounted for to ensure that at the inlet plane of the orifice the flow is fully developed and turbulent. Figure 18 shows the approximate ranges of testing on a moody chart for single phase liquid flow.

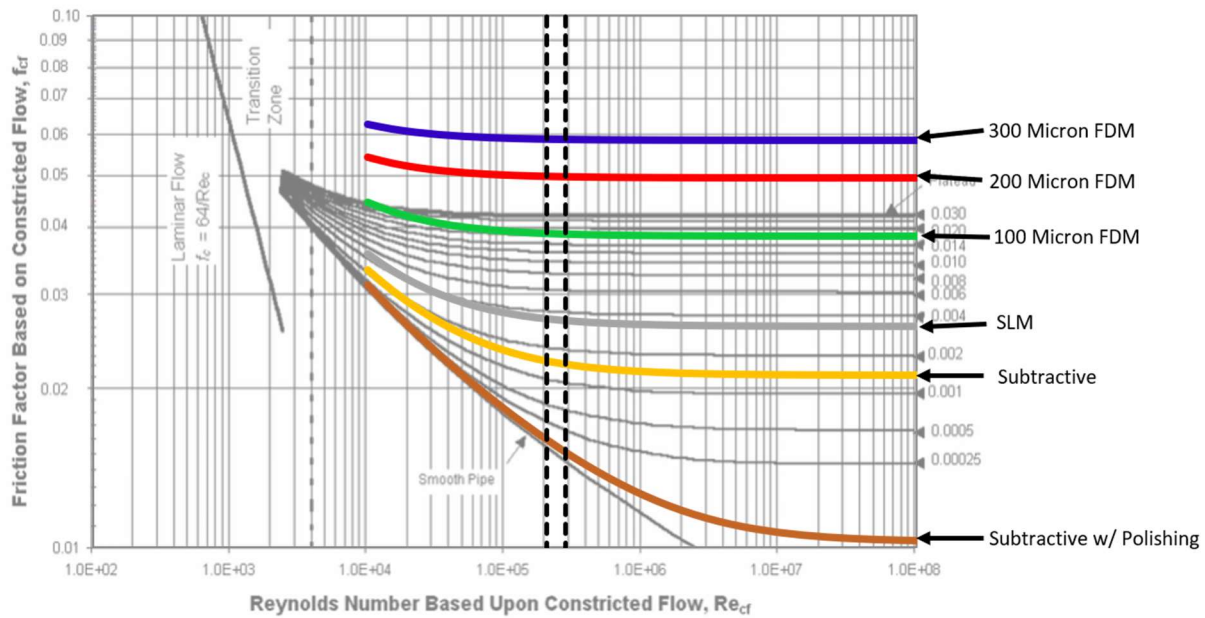


Figure 18: Range of Testing Reynolds Numbers and Expected Roughnesses

3.6 Fluid System Design, Sizing, and Selection

The Plumbing and Instrumentation Diagram (P&ID) for the HPSF is attached in Appendix A and the P&ID for the cavitation test setup is attached in Appendix H. This section will be focusing on the fluid system specific to this experiment. Components in the system are a venturi flowmeter, a liquid rated relief valve, a type K thermocouple, two high frequency dynamic pressure transducers, three static pressure transducers, a domotor actuated globe valve, a Bellofram

electrical control regulator, a high pressure gas service regulator, a needle valve, and the test sample being tested. Major components will be discussed individually.

3.6.1 Venturi Flowmeter ASF-FQ-W003

Preliminary sizing was performed once a venturi flowmeter was selected and before full flow characterization of the venturi was performed. A Flowmaxx Venturi Flowmeter currently in possession of the PRC was chosen and verified to have the correct mass flow range capability. The method by which the venturi flowmeter measures mass flow is expressed in Equation 10. By which the difference in pressures is measured from the inlet to the throat of the meter.

$$\dot{m} = C_D A \sqrt{2\rho(P_1 - P_2)} \quad 10$$

Manufacturer suggested use is to only measure within a 10% - 90% range of the maximum mass flow capability of the flowmeter of 8.13 lbm/s at 500 psig with a flowmeter C_c of 0.9 (assuming highly polished converging-diverging nozzle geometry). At the low-flow worst case condition, assuming a 50% effective area of the orifice being tested in both cavitation and non-cavitation use (C_c and C_D of 0.5) with delta-pressure operation across the sample of 500 psig to 200 psig, the mass flow is 14.13% of maximum. A 50% effective geometry is lower than what would be expected with this geometry but was chosen for increased margin. The high-flow worst case condition, assuming 95% effective area of the orifice being tested (C_c and C_D of 0.95) with cavitation operation across the sample at 500 psig upstream pressure, the mass flow is 36.63% of maximum. This flow exists in the lower half of the flowmeter's range ensuring good pressure recovery across the device to alleviate pressure loss prior to the inlet of the test sample. Further detail of sizing assumptions are detailed in Appendix B.

The actual flow capability of the venturi is characterized as an effective flow area, combining C_D and area. This was measured to be $0.07889 \text{ in}^2 \pm 0.181\%$. The venturi's maximum limit can not be tested without the possibility of damaging the instrumentation and the internal surface finish. The cases used in the preliminary sizing are conservative enough to allow for the cavitation properties to be assumed. Additionally, there is significant distance to allow for any vortex shedding or bubble formation from the flowmeter to not impact the test section.

3.6.2 System Backpressure Control Valve ASF-CV-W011

In order to allow for the 10 setpoints to occur in the same contiguous test, a variable position globe valve was used to regulate the backpressure on the sample. This valve is an Annin 2600 Series Split Body Globe Valve positioned using a Domotor Actuator (ASF-CV-W011) and is controlled using a Bellofram controller (ASF-PC-N003). Details about the fluid control properties of the valve and actuator is contained in Appendix E. The valve and controller both require a pneumatic supply which is supplied using the gas simulant line to the atmospheric spray bench. This supply needs to be stepped down from a high pressure (500-3000 psig) down to the supply of 60 psig for both the controller and valve. This is performed by a Tescom hand actuated pressure reducing regulator (ASF-PR-N002). A photo of the valve and its setup is included in Figure 19.

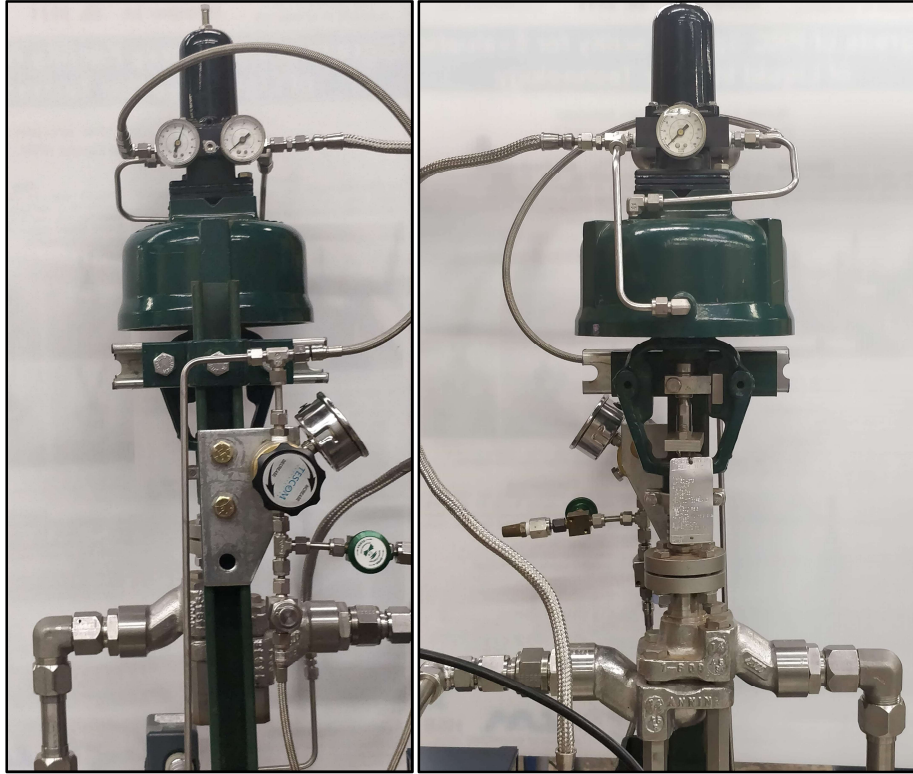


Figure 19: Backpressure Control Valve

In order to determine the response of the valve and pneumatic controls to a current applied to the controller a test was performed sweeping the controller through a range of 4-20 mA and determining associated value of the pressure of interest (ASF-PY-W010). This was used in a multi-gain proportional-integral-derivative controller to control the valve in test. A plot of the valves control response is shown in Figure 20.

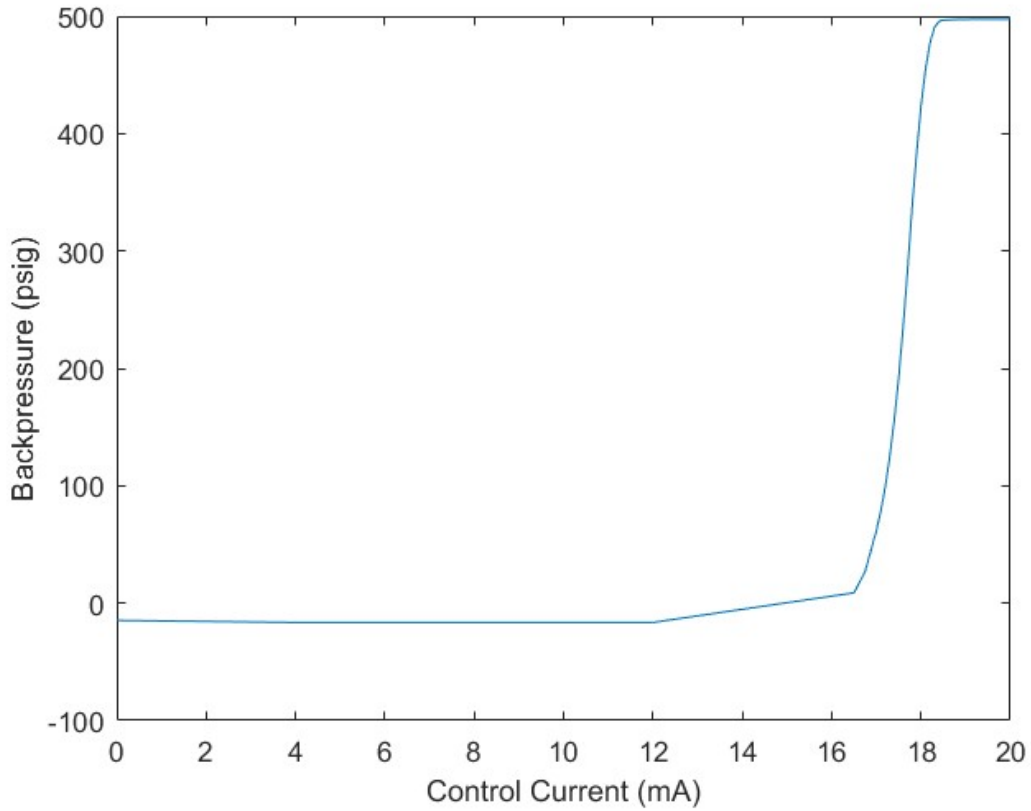


Figure 20: Backpressure Valve Static Pressure Response

3.6.3 Test Sample ASF-OR-W008

After choice of a test sample size and flow conditions, a determination of hydrodynamic entrance length was made to specify the inlet tube length. This calculation was made using Equation 11.

$$L_{h,turbulent} = 4.4 * D * Re^{1/6} \text{ [37]} \quad 11$$

The resulting value, assuming worst case conditions, came to be 22.01". The actual produced entrance length was 22.375" so to be fully developed turbulent flow at the entrance of the test sample. The sample is sandwiched between an AN-12 37° flare fitting and a flared tube section.

3.6.4 Instrumentation and Plumbing

Table 6 includes a list of all the instrumentation used in the system along with model and serial number for the device. A list of all necessary calibration sheets are included in Appendix C. Appendix H shows a schematic for the system used in this testing and Table 6 lists any pertinent component information. Figure 21 shows a view of the test section with information on placement of instrumentation with respect to the orifice.

Table 6: Instrumentation Used in Testing

Name	DAQ Channel	Patch Panel Channel	Manufacturer	Serial Number	Model	Range	Accuracy	Resolution
Venturi DP	16	B1-Ch2	Sensotec	750329	Z/741-03ZD	0-50 psid	+/- 0.25% FS	0.000762939 psi
Upstream Pres	0	B1-Ch1	Omegadyne	103110D878	PX-309-500G5V	0-500 psig	+/- 0.25% FS	0.007629395 psi
Source Pres	18	B1-Ch4	Honeywell	1249468	FPG	0-1500 psig	+/- 0.25% FS	0.022888184 psi
Downstream Pres	17	B1-Ch3	Omegadyne	083131D112	PX-309-500G5V	0-500 psig	+/- 0.25% FS	0.007629395 psi
Source Temp	TC-6	B1-TC Ch1	Omega	N/A	KMQSS-125G-6	-454°F-2501°F	1.46 °F	0.558 °F
Run Tank Pres	10	B3-Ch19	Honeywell	1196154	FPG	0-3000 psig	+/- 0.25% FS	0.045776367 psi
System Pres	6	B3-Ch14	Dwyer	3000A	N/A	0-3000 psig	+/- 0.25% FS	0.045776367 psi
Run Tank Dome	8	B1-Ch9	Honeywell	1196158	FPG	0-3000 psig	+/- 0.25% FS	0.045776367 psi
Liquid Sim	15	B2-Ch10	Honeywell	1195664	FPG	0-3000 psig	+/- 0.25% FS	0.045776367 psi
Current Control	cDAQ Ch0	N/A	Bellofram	967-020-000	T1001	N/A	N/A	N/A
Downstream HF	USB Ch0	B1-Ch14	PCB	32256	112A05	-10% to 25% Steady State	+/- 1.00% FS	0.004 psi
Upstream HF	USB Ch1	B1-Ch15	PCB	32324	112A05	-10% to 25% Steady State	+/- 1.00% FS	0.004 psi

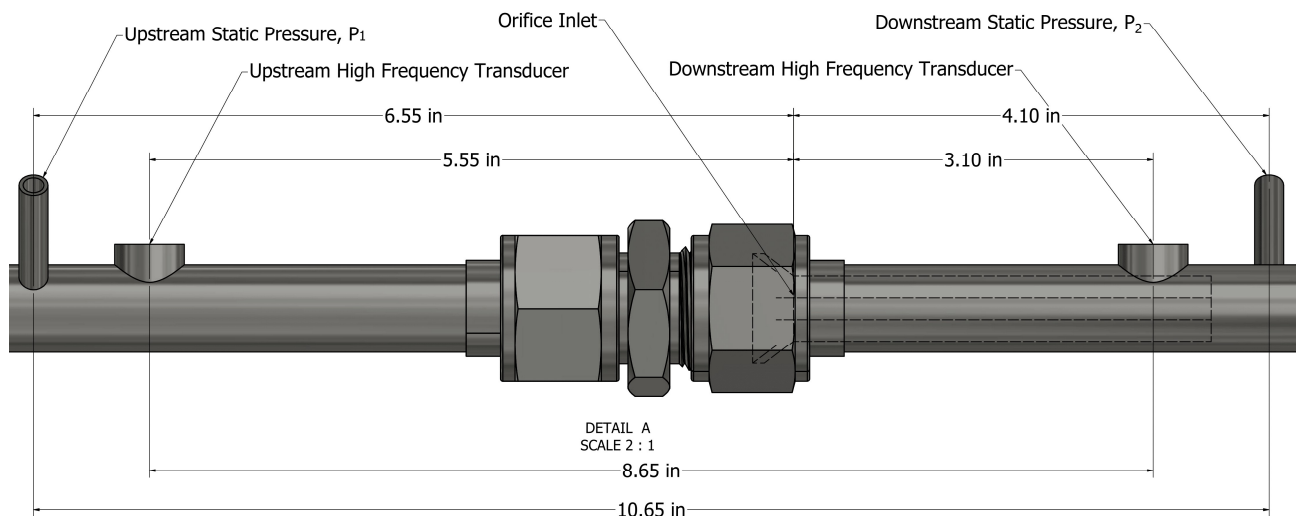


Figure 21: Test Section Instrumentation Locations

3.7 Test Setup, Operation, and Procedure

Operations for the setup are controlled using a Standard Operating Procedure (SOP) approved by the system owners of the HPSF (PRC-SOP-JRC-032-A2) and an experiment procedure which is included in Appendix K. Operations start with the standard procedures to bring the facility to a state of readiness and fill the run tank with deionized water. This works by first ensuring the system is in a known state and that all valves actuate correctly. After this, the run tank is filled with deionized water from the holding tank. A floorplan of the facility is shown in for reference.

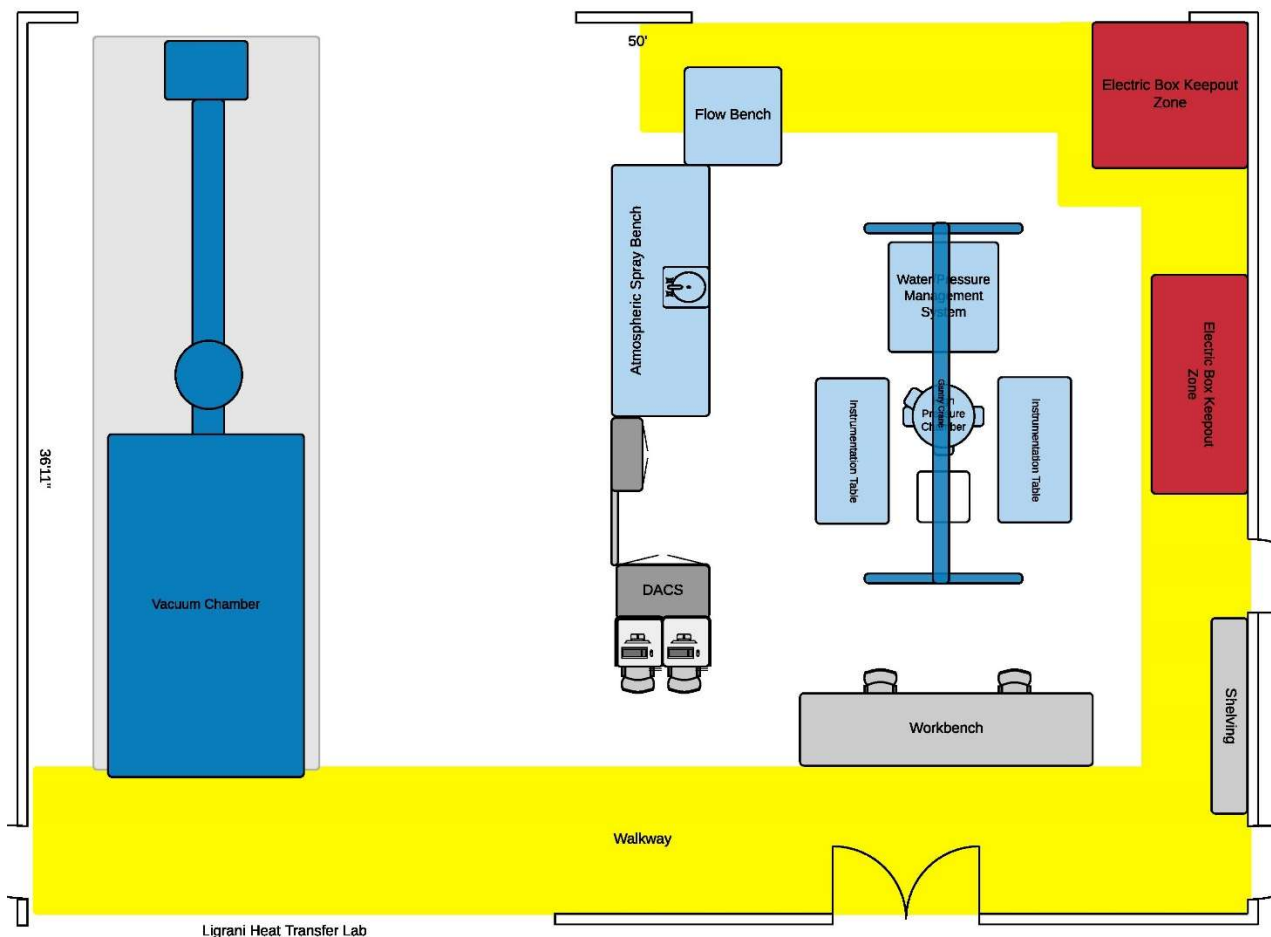


Figure 22: High Pressure Spray Facility Floorplan

Once the system is determined to be in a safe state and ready for pressure to be applied then the gas bottles can be opened and the pressure can be brought up to ~2600 psig at the Main Isolation Valve 10.01. Once this is opened then pressures for the different systems can be set by the dome-loaded regulators 14.03, 14.04, 14.05, and 14.06. After pressure has been brought up to 100 psig for valve actuation then additional valve checkouts can be performed. Once the facility is deemed ready then the Run Tank Dome Pressure can be set to ~515 psig such that the Run Tank reads ~500 psig. At this point the Experiment Procedure can be used and the Gas Simulant Pressure can be set to ~ 500 psig on the panel and the diverter valve can be set to pressurize. At this point the Gas Sim Fire Valve (10.06) can be opened. At this point the control valve regulator is set to ~60-65 psig, any excess pressure will be audibly vented out the valve weep hole. Now that pressure has been brought up on both systems instrumentation checks in Labview can be performed by verifying that all transducers are reading near zero and thermocouple readings are nominal. Once that check has been performed the names for the files for both the low speed (1 kHz) and high speed (100 kHz) data files. Then a check of the backpressure control valve is performed by forcing the valve full open and full closed to verify proper actuation. After this has been performed then the valve is overridden full open and the Liquid Sim Fire Valve is opened and the Atmospheric Spray Facility isolation valve is slowly opened. Once this valve has been fully opened the valve can be turned to closed loop control and the test schedule can be started. After this the test is now in hands off condition until the schedule is completed and the valve partially closes. At this point the Atmospheric Spray Facility isolation valve can be closed and the schedule stopped, therefore stopping the recording.

3.8 Test Cases

Tests are scheduled using a setpoint scheduler in Labview. The setpoints are set to a K of 1.6 - 1.0. A graph of the timings of these setpoints is shown in Figure 23. Each test would perform a sweep as shown in the figure. For the tests there are 5 unique test configurations in the Test Matrix (100, 200, 300 μm FDM, SLM, and Subtractive Manufacturing) each with 3-4 test samples.

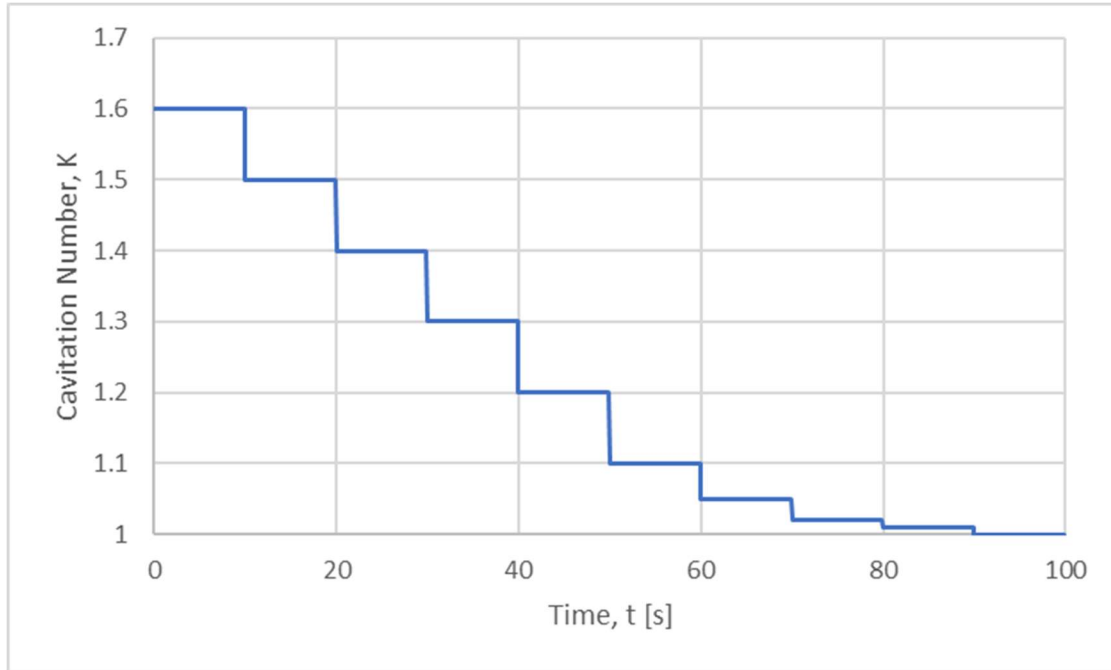


Figure 23: Setpoint Schedule

CHAPTER 4

RESULTS

4.1 FDM PLA Orifice Data

Tests in Block 1 and 2 of testing were performed on FDM PLA samples. Block 1 was a preliminary set of tests and are omitted from this report. Figure 24 shows the response of the Block 2 tests to the set conditions controlled by the globe valve. The x-axis is the time during the test and the y-axis is the cavitation number at that point in the test. Cavitation Number is seen decreasing in steps as the test progresses. The results in Figure 24 closely follow the expected setpoint schedule shown in Figure 23 terminating at a full open globe valve condition for $K \approx 1.0$. Fluctuations seen in the cavitation number can be attributed to the closed loop control by the globe valve and when nondimensionalized and averaged over an entire setpoint the values are valid for use in further analyses. For configurations that had large deviations from the planned setpoints, additional tests were performed. The legend for all these figures uses the following naming convention for the tests, [Block Number] – [Sample Type] – [Sample Number] – [Test Number].

Figure 25 shows the mass flow during the tests. The x-axis for this figure is the time during the test and the y-axis is the mass flow in kg/s calculated using the venturi flowmeter and Equation 10. During Block 2 testing the mass flow can be seen changing through a majority of the test. The individual steps in mass flow is due to the step-wise nature of the testing and the transient movement to each setpoint is due to the closed loop control of the globe valve in the test. The mass flow rate differences from configuration-to-configuration can be seen, as well as the test-to-test and part-to-part deviation possibly due to slight differences in inlet radius, roughness, cavitation number, etc.

Figure 26 shows the mass flow with reference to a nondimensional cavitation number which removes the influence of test-to-test differences in upstream pressures, downstream pressures, and time. The increasing mass flow section of the figure from $K = 1.6$ until $K \approx 1.1$ indicates non-cavitating operation whereby the decreasing downstream pressure increases mass flow up until the cavitation point. The constant mass flow section of the figure from $K \approx 1.1$ to $K = 1.0$ indicates cavitation in the test sample and constant mass flow control whereby the mass flow is only due to the upstream pressure. The figure shows that these samples do not restrict mass flow until $K \approx 1.1$ -1.15 as until that point in the plot the mass flow is still changing. This is much lower than the predicted value of $K = 1.45$ for the cavitation mechanism to start based on work by Nurick [8]. This could be attributed to roughness effects as it is a deviation from expected. This is backed up by fact that the lower roughness 100 μm samples trip to cavitation at a lower value of $K \approx 1.15$.

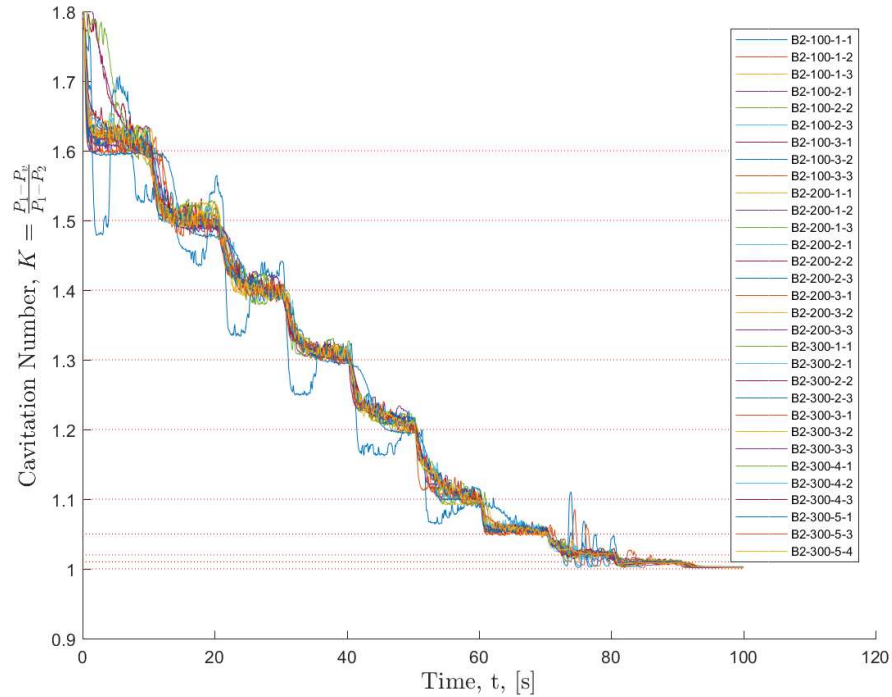


Figure 24: Block 2 Sample Cavitation Number trend with Time

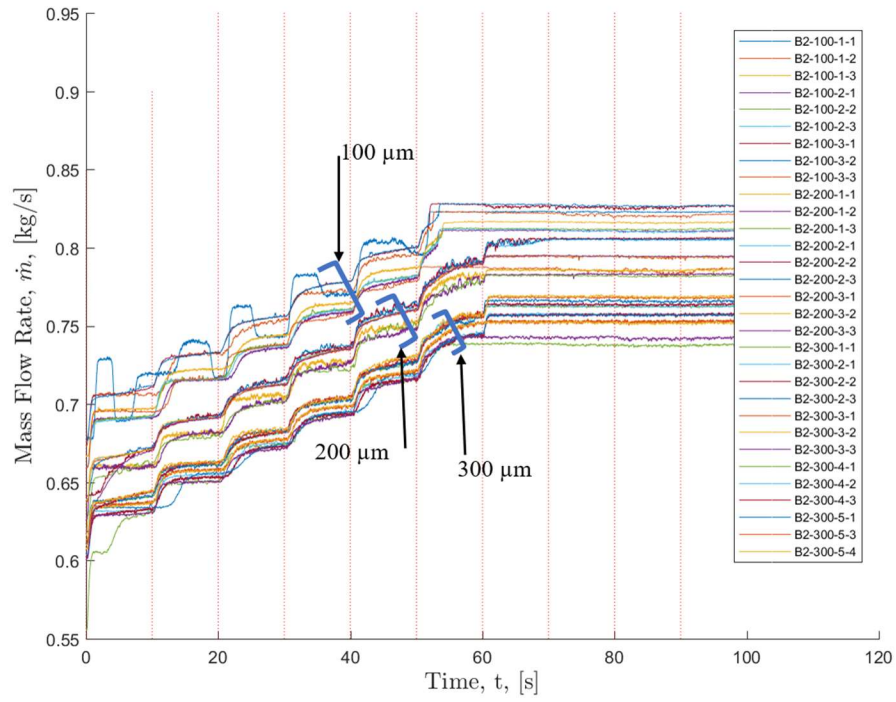


Figure 25: Block 2 Sample Mass Flow trend with Time

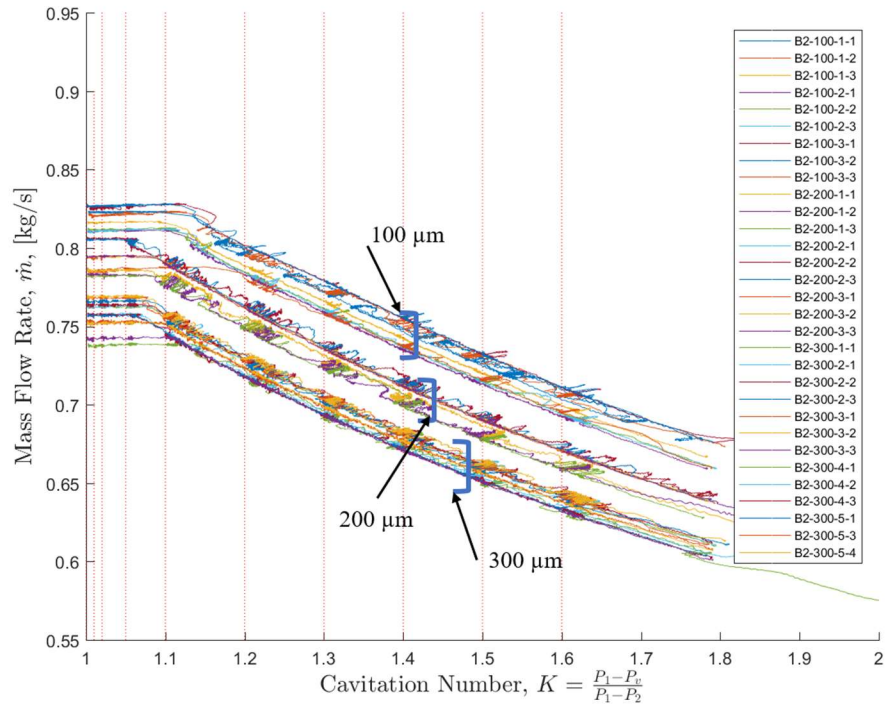


Figure 26: Block 2 Sample Mass Flow Relation to Cavitation Number

For comparisons sake, Figure 27 shows the discharge coefficient with respect to nondimensional cavitation number for all of the Block 2 tests compared to the predicted value for a sharp edge inlet orifice transitioning to cavitation at $K = 1.45$ derived from Equation 3 and Equation 5. By plotting the data with respect to the discharge coefficient and the cavitation number the variance due to testing variables such as upstream and downstream pressure are factored out of the data. The differences between the curves is now solely due to the inlet radius, roughness, other geometrical effects, as well as uncontrollable deviances such as differences in water purity and gasification. At this point two tests were removed from the analysis set using Chauvenet's Criterion. These tests (B2-100-3-3 & B2-300-1-1) are annotated in Figure 27. Additionally, as Equation 4 shows, the values of C_D and K are related through C_c which therefore means that Figure 27 can be used to graphically analyze the differences in cavitation operation for the different configurations and tests. Three groupings can be seen in Figure 27 and are annotated. The tests group by configuration with the 100 μm parts having an overall larger value of C_D than the other configurations and 300 μm parts having a lower value of C_D than the other configurations. In Figure 27, the knee in the curves is the cavitation number at which the tests transition from non-cavitating orifice flow to cavitation.

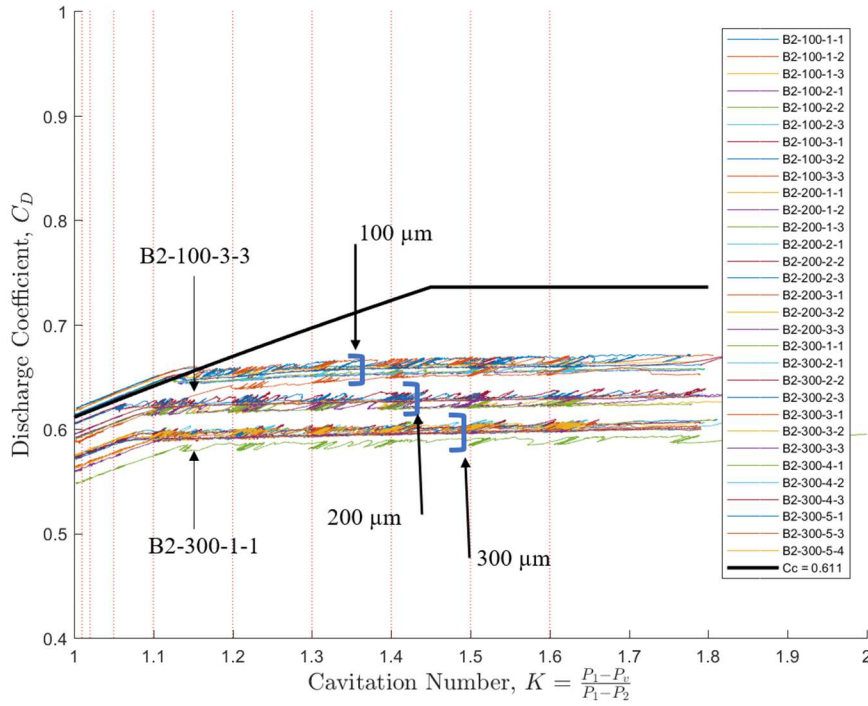


Figure 27: Block 2 Sample Discharge Coefficient and Cavitation Number Relationship (Prediction and Measured)

4.1.1 Contraction Coefficient

Contraction Coefficient for each test was determined using,

$$C_c = \left(\frac{C_E}{A_{geo}} \right) \sqrt{\frac{DP_{meter}}{P_1 - P_v}} \quad 12$$

This equation uses the flowmeter flow coefficient (C_E), which combines C_D and Area, and flowmeter drop in pressure (DP_{meter}) to measure the mass flow during the test. This is then used in Equation 2 to determine the C_c . The last 5000 points of each test are used to determine the C_c for the test. These C_c values are then averaged across all tests for a certain configuration to find the configuration C_c . Uncertainty analysis described in Appendix I shows a maximum $\pm 0.584\%$ uncertainty in C_c when all factors are accounted for. Standard deviation of the calculated variable from measurement is at $\pm 0.0227\%$ and therefore the uncertainty analysis is assumed to yield the

uncertainty of the mean value for each test. Bias in the measurement values is tared out at the beginning of the testing day, thereby negating bias errors between tests. This analysis does not include correlated bias factors.

To compare the contraction coefficient value for each sample configuration an average and 95% confidence limits of the mean was determined. Figure 28 shows a probability distribution function for each Block 2 configuration and is shown with the dotted lines demarcating the 95% confidence limits. This shows that the mean configurations are statistically different with respect to their mean contraction coefficient values. Values determined were 0.6146 for 100 μm , 0.5969 for 200 μm , and 0.5699 for 300 μm . These values can be adjusted for their inlet edge radius using a relation derived by Nurick [2]. This empirical relation, outlined in Equation 9, adjusts these C_c values to account for their varying inlet radii. Using the measured inlet radii of each part as well as the inlet diameter one can find an inlet r/d . This is then used in the empirical relation, rewritten to convert to sharp edge inlet equivalent value, in Equation 13.

$$(C_c)_{\frac{r}{d}=0} = \left[\left(\frac{1}{(C_c)_{\frac{r}{d}}} \right)^2 + 11.4 \left(\frac{r}{d} \right) \right]^{-\frac{1}{2}} \quad 13$$

Each part's measured C_c is then converted to the equivalent sharp edge inlet value and then the average for the configuration is found. The original values for each configuration and the values after sharp-edge adjustment are listed in Table 7 with the average inlet r/d measured for each configuration and the limits for 95% confidence in the mean. An uncertainty analysis for this calculation is included in Appendix I. These values can be compared to that of the reference derived from work by Nurick[8] and Howland and Richetta[28].

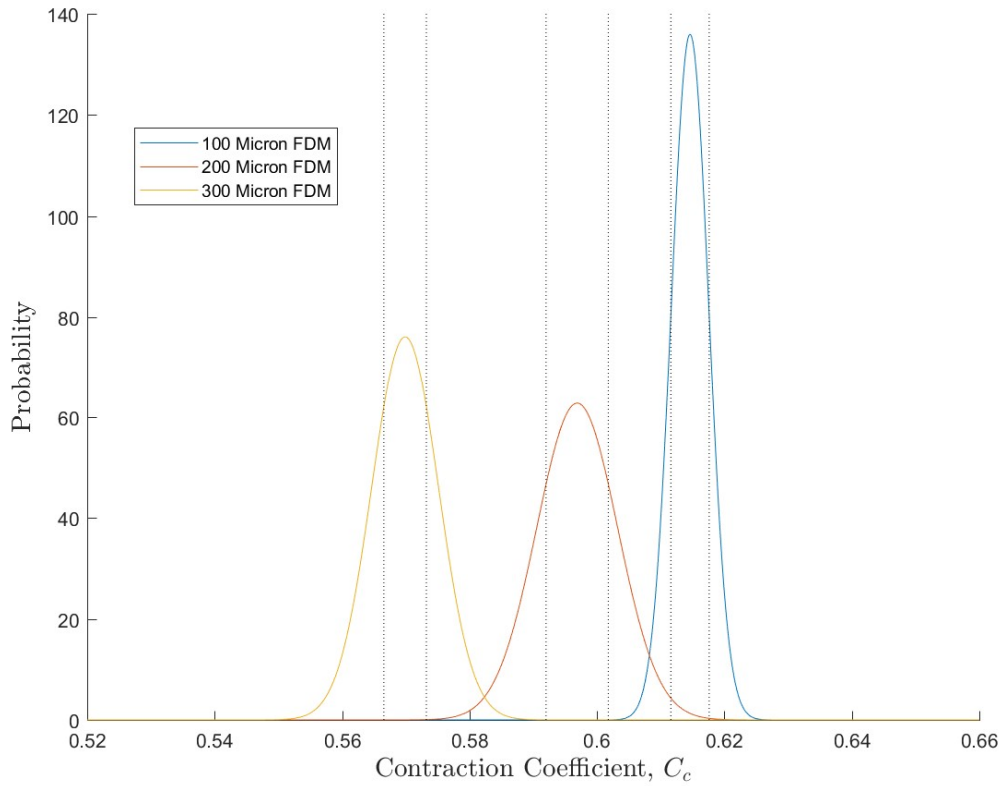


Figure 28: Block 2 Contraction Coefficient Probability Density Functions

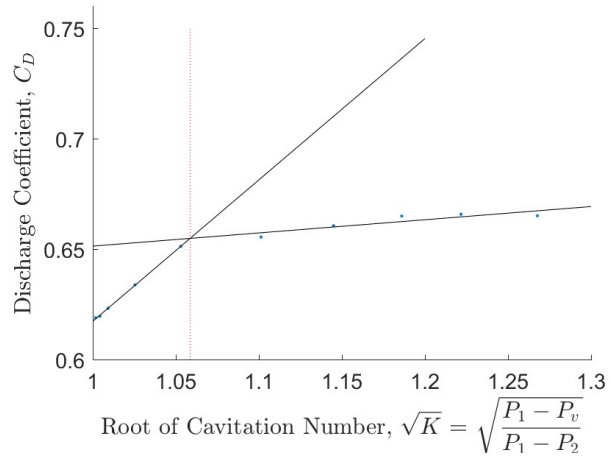
Table 7: Original and Adjusted Values for Block 2 Average Contraction Coefficient

	Cc				
Sample Type	Original	95% Limits	Radius Adjustment	95% Limits	Average r/d
100 μm FDM	0.6146	\pm 0.0030	0.5953	\pm 0.0059	1.54E-02
200 μm FDM	0.5969	\pm 0.0049	0.5681	\pm 0.0060	2.57E-02
300 μm FDM	0.5699	\pm 0.0033	0.5358	\pm 0.0039	3.53E-02
Reference	0.611	\pm N/A	0.611	\pm N/A	0.00E+00

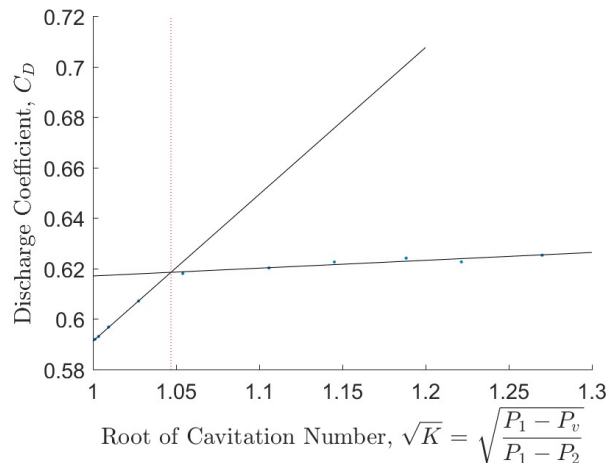
4.1.2 Critical Cavitation Number

The critical cavitation number for each test was determined by averaging the C_D and K at each setpoint in the individual test. The data for each test was then fit to a set of linear functions of C_D as a function of the square root of K for the cavitating and non-cavitating regimes of flow as

we know that these values are related to each other linearly through Equation 9. Through inspection of the data the ranges for each curve fit were determined. The intersection point of the two linear curve fits is taken to be the critical cavitation number. Figure 29 shows a representative plot of the two curve fits and their resulting intersection points for each of the FDM configurations. Table 8 lists the average K_{crit} for each sample configuration.



(a)



(b)

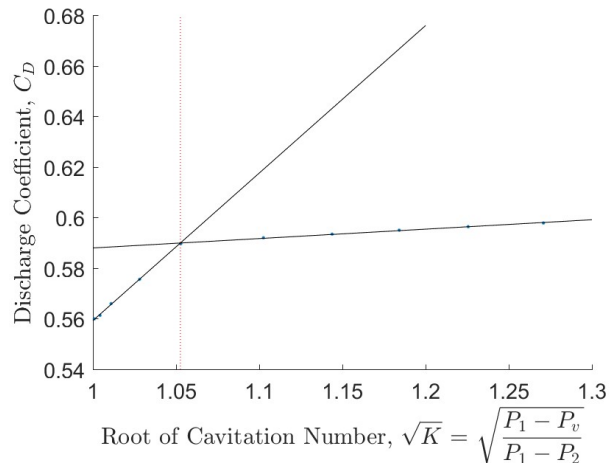


Figure 29: Block 2 Results to Determine K_{crit} : (a) B2-100-1-2, (b) B2-200-1-2, (c) B2-300-3-3

Table 8: Block 2 and Reference K_{crit} & Associated C_{Dcrit} Values

Sample Configuration	K_{crit}	C_{Dcrit}
300 μm	1.078	0.6151
200 μm	1.083	0.6462
100 μm	1.116	0.6877
Reference	1.45	0.7360

4.1.3: High Frequency Results

The results of the high-frequency pressure measurements for a single representative test for this block of testing is shown in Figure 30. The individual plots are fast fourier transforms taken over differing timeframes during the test. This is presented as such given the test's step-wise nature. Notable frequency peaks are identified with markers. Note that the y-axis is not constant across all plots. This is done in order to view some of the lower intensity peaks. The sampling frequency was 100 kHz with both the charge amplifier used as well as the data acquisition unit having a frequency limit of 100 kHz. The charge amplifier acts as a low pass filter with a cutoff at 100 kHz. No additional anti-aliasing filter was used due to restrictions on the data acquisition unit used. The main frequencies are still considered to be valid due to the explanation via Strouhal number analysis later in the section.

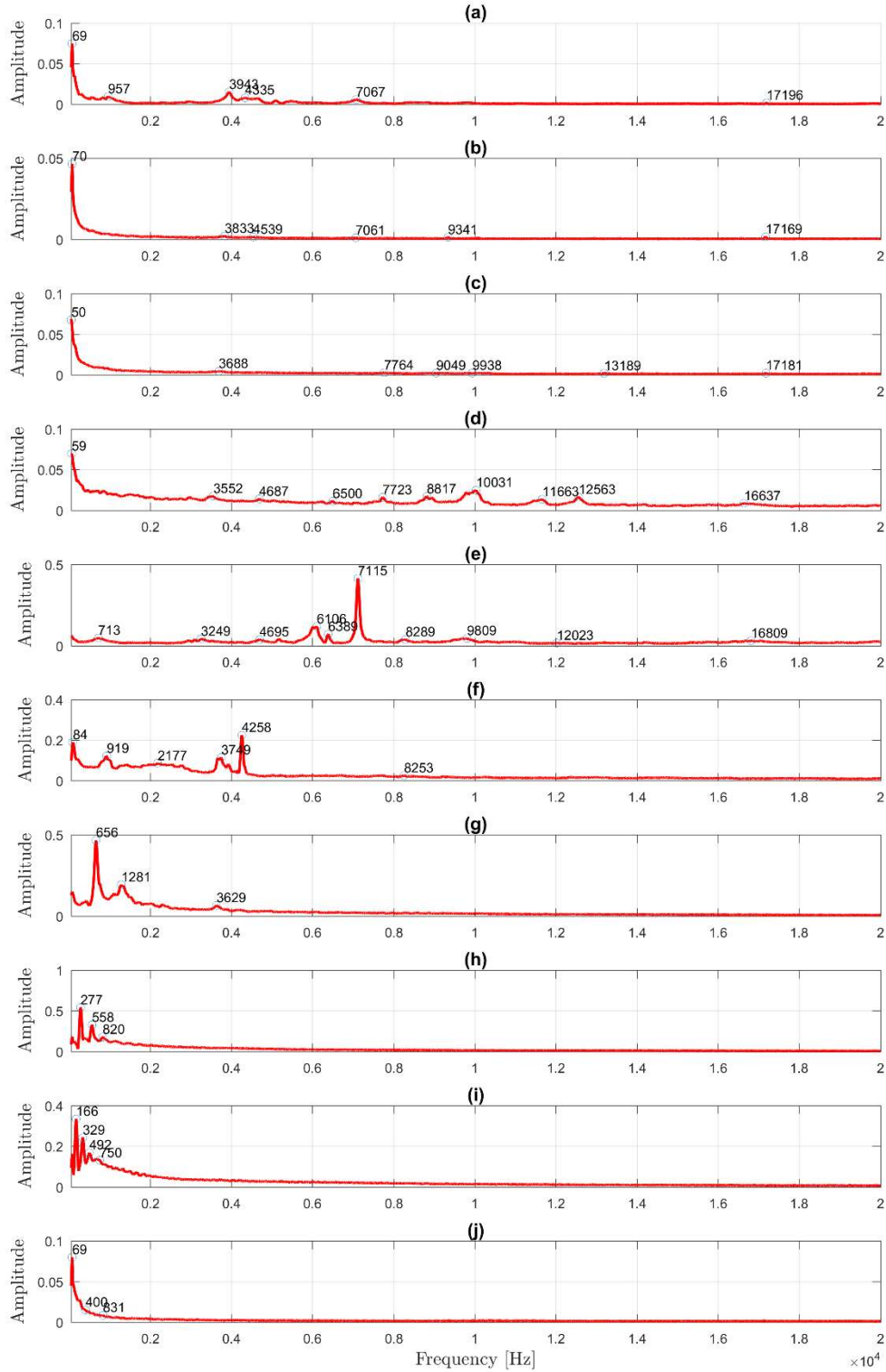


Figure 30: B2-100-3-1 HF Plots: (a) $t = 6-9s$ $K = 1.6$, (b) $t = 16-19s$ $K = 1.5$, (c) $t = 26-29s$ $K = 1.4$, (d) $t = 36-39s$ $K = 1.3$, (e) $t = 46-49s$ $K = 1.2$, (f) $t = 56-59s$ $K = 1.1$, (g) $t = 66-69s$ $K = 1.05$, (h) $t = 76-79s$ $K = 1.02$, (i) $t = 86-89s$ $K = 1.01$, (j) $t = 96-99s$ $K = 1.0$

At the $K = 1.2$ setpoint in Figure 30 (e) a frequency peak of 7115 Hz is identified. This peak frequency decreases with cavitation number decrease as seen in Figure 30 (f)-(j). Due to its shifting nature with K , the peak frequency is likely not tied to the mass flow of the device. The peak amplitude at $K = 1.2$ setpoint occurs at a Strouhal number of 0.668 based on no restriction in flow area or increase in fluid velocity at the vena contracta. This is outside the range of expected values as determined by a variety of sources previously reviewed[20]–[27]. Once cavitation is assumed by decreasing the effective area using the contraction coefficient and increasing the fluid velocity through the same decrease in area, the Strouhal number becomes 0.248 which is well within the expected range and only 5.7% different from the peak Strouhal number of 0.234 calculated for the orifice at that point during the test. The further peak amplitudes of 4258 Hz in Figure 30 (f) at $K = 1.1$ and 656 Hz in Figure 30 (g) at $K = 1.05$ don't appropriately line up with any expected Strouhal numbers. This could be attributed to the increase in flow velocity downstream with decreasing Cavitation Number which would need to be measured in order to determine the Strouhal numbers downstream of the inlet cavitation bubble. Although not the primary focus of this thesis, other similar frequency analyses of unsteady pressure phenomenon for these tests are included in Appendix E for future analysis. They generally show the same Strouhal number agreement as the test presented.

4.2 SLM Orifice Data

Block 3 Testing contained tests spanning the SLM configuration. Figure 31 shows the response of these tests to the set conditions as controlled by the globe valve. The x-axis of the chart shows the time during the test with the cavitation number plotted in the y-axis. Cavitation number is seen decreasing in planned steps as the test progresses. This results in Figure 31 closely follows the expected setpoint schedule in Figure 23 as well as the FDM data in Figure 24. The legend for these figures used the same naming convention as previously used. As previously mentioned, any fluctuations in the setpoint and transient movement is due to the closed loop control of the globe valve during the test.

Mass flow rates during the test are shown in Figure 32. The x-axis for this figure is the time in test and the y-axis is the mass flow of the test in kg/s calculated using the venturi flowmeter and Equation 10. Of note, the mass flows for the SLM configurations have a much tighter grouping than that of the FDM configurations as previously described in Figure 25. Much like in the Block 2 testing, shown in Figure 25, the mass flow can be seen changing through a majority of the test. The individual steps in mass flow is due to the step-wise nature of the testing and the transient movement to each setpoint is due to the closed loop control of the globe valve in the test. A lack of flow control occurs at the $K = 1.02$ setpoints for a few tests. This is due to the difference in fluid resistance from part-to-part which leads to a loss of closed loop control stability at certain conditions. This lack of setpoint control does lead to an increase in variance for cavitation number and discharge coefficient for that setpoint. However, due to the nature of the cavitation number at values close to $K = 1.0$, the fact that the setpoint occurs below the critical cavitation number, and the fact that this variance is due to a modulation of downstream pressure rather than upstream pressure, this variance does not affect the contraction coefficient calculation. The mass flow rate

differences from test-to-test can be seen, as well as the part-to-part deviation possibly due to slight differences in inlet radius, roughness, etc. The test-to-test deviation is especially apparent with the differences between tests B3-SLM-4-1, B3-SLM-4-2, and B3-SLM-4-3. These differences are factored out of the results when the results are compared by way of cavitation number – discharge coefficient relationship later in the analysis.

Figure 33 details the mass flow relationship with the nondimensional cavitation number for the Block 3 samples. Calculating the cavitation number and using it for comparative purposes should remove influences from the test-to-test deviations in upstream and downstream pressures. The undulations seen in the data about each of the cavitation number setpoints is due to the closed loop control of the globe valve and the process of the system steering to the setpoint. This does not adversely affect the results when accounted for using the relationship between the cavitation number and discharge coefficient. The increasing mass flow section of the figure from $K = 1.6$ until $K \approx 1.2$ indicates non-cavitating operation whereby the decreasing downstream pressure increases mass flow up until the cavitation point. The constant mass flow section of the figure from $K \approx 1.2$ to $K = 1.0$ indicates cavitation in the test sample and constant mass flow control whereby the mass flow is only due to the upstream pressure. Figure 33 shows indications of choking as indicated by the leveling of the discharge coefficient happening at $K \approx 1.2$ rather than $K \approx 1.1$ - 1.15 for the FDM samples. This transition value is lower than the reference value of $K = 1.45$ from work by Nurick [8]. This could be attributed to a difference in waviness and/or roughness profiles from that of the FDM parts as detailed in Table 3.

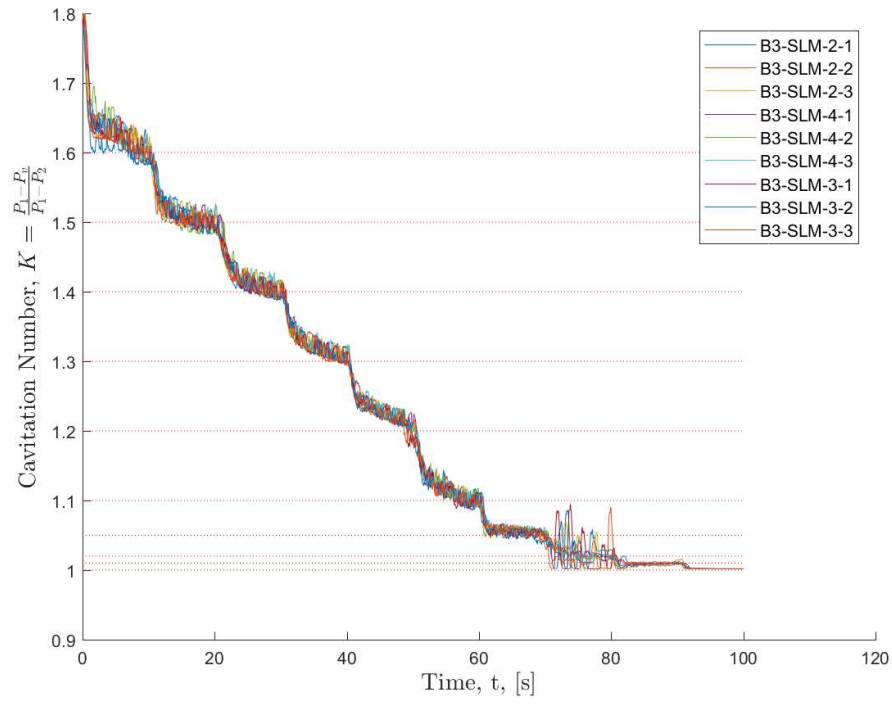


Figure 31: Block 3 Sample Cavitation Number Trend with Time

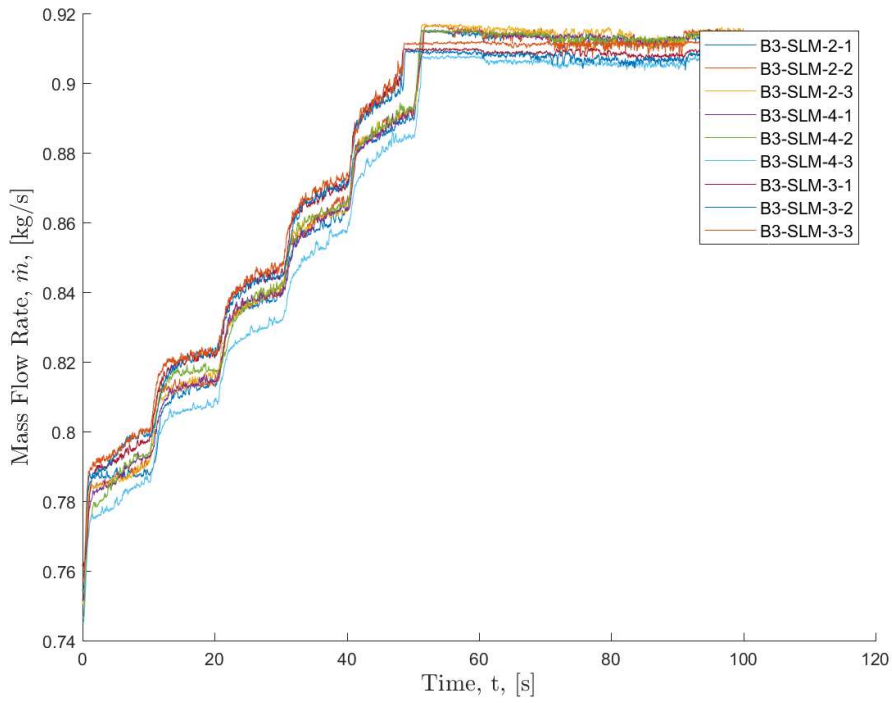


Figure 32: Block 3 Sample Mass Flow trend with Time

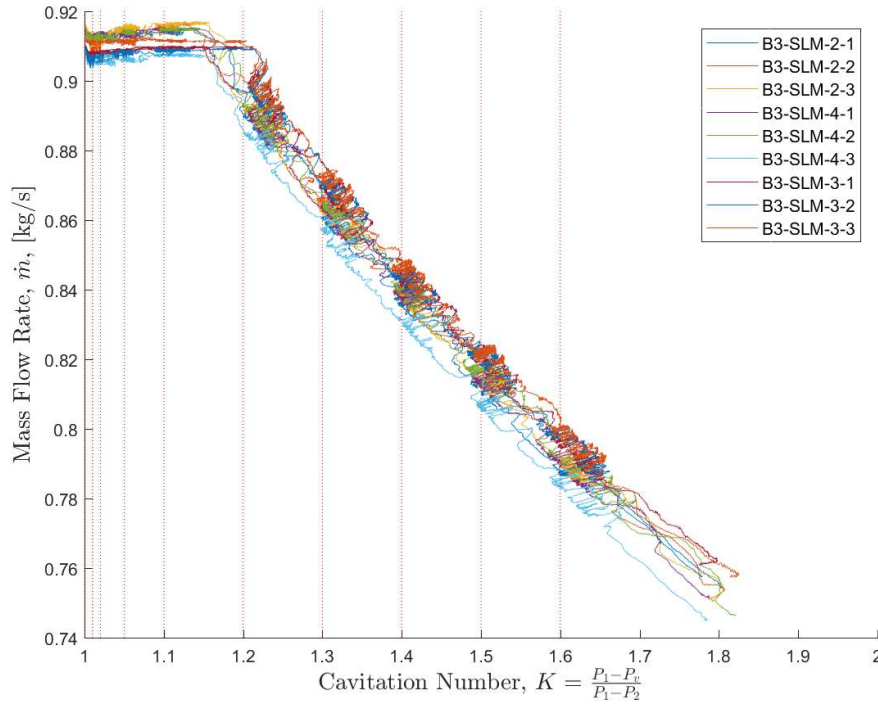


Figure 33: Block 3 Sample Mass Flow Relation to Cavitation Number

A trace of the discharge coefficient and nondimensional cavitation number for the Block 3 samples is shown in Figure 34. Plotting the data by way of nondimensional cavitation number and discharge coefficient will factor out the test-to-test differences in upstream pressure and downstream pressure as well as diameter differences between parts. The differences between the curves should be due to part-to-part differences in roughness, inlet radius, and other geometrical effects as well as test-to-test deviations that are uncontrolled such as differences in gasification and water purity. Additionally, as Equation 4 shows, the values of C_D and K are related through C_c which therefore means that Figure 34 can be used to graphically analyze the differences in cavitation operation. Compared to the accepted baseline of a C_c of 0.611 and transition cavitation number of $K = 1.45$ the SLM samples transition at a lower value of K at $K \approx 1.2$ and have a higher C_c of 0.6462. This value has not been adjusted for the inlet radius which may account for the increase over 0.611. In Figure 34, the knee in the curves is the cavitation number at which the tests

transition from non-cavitating orifice flow to cavitation. The difference in transitional cavitation number and contraction coefficient could be due to the roughness and waviness information detailed in Table 3 and its differences from that of the traditionally smooth orifices used in Nurick [8] and others. Further discussion on this is in Section 4.2.1, 4.2.2, and 4.4.

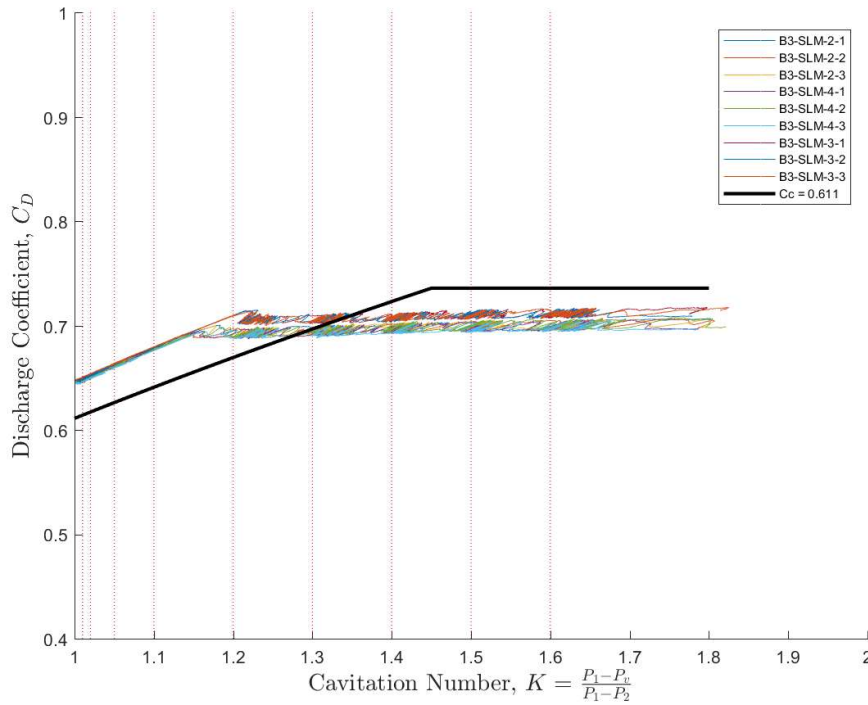


Figure 34: Block 3 Sample Discharge Coefficient and Cavitation Number Relationship (Prediction and Measured)

4.2.1 Contraction Coefficient

The Contraction Coefficient and related uncertainty for each test was determined using the same approach as used in 4.1.2. To compare the contraction coefficient value for each sample configuration an average and 95% confidence limits of the mean was determined. Figure 35 shows a probability distribution function for each configuration. Dotted lines demarcate the 95% confidence limits. This shows that the configurations are statistically different with respect to their

mean contraction coefficient values. The value determined was 0.6462 for the SLM configuration. This value can be adjusted for the inlet edge radius using a relation derived by Nurick [2]. This empirical relation outlined in Equation 13 adjusts this C_c value as previously documented in Section 4.1.2. The original value and the adjusted value is listed in Table 9 with the Block 2 FDM values and the reference derived from work by Nurick[8] and Howland and Richetta[28]

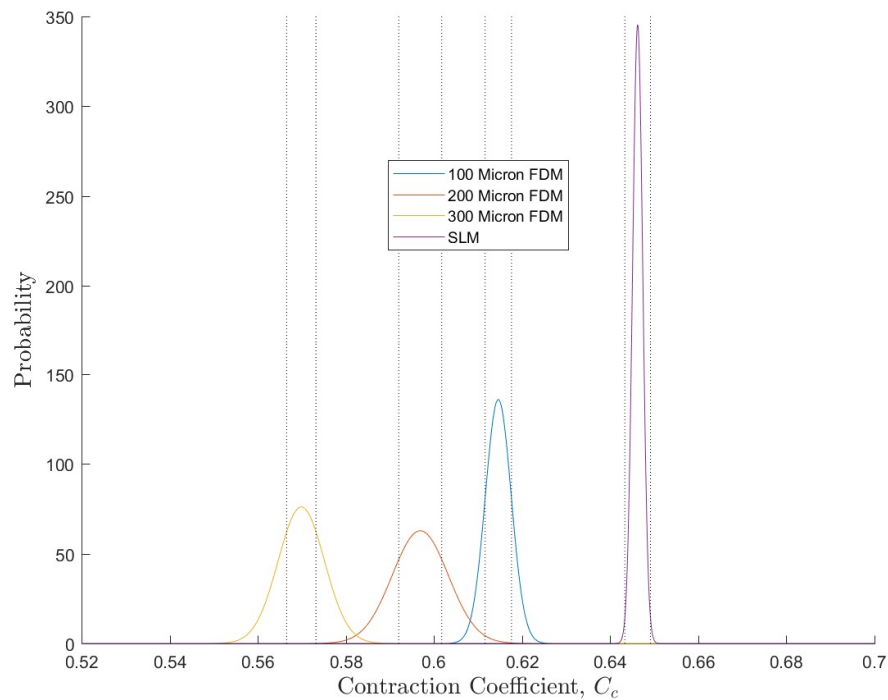


Figure 35: Block 2 and 3 Contraction Coefficient Probability Density Functions

Table 9: Original and Adjusted Values for Contraction Coefficient

Sample Type	Cc				Average r/d
	Original	95% Limits	Radius Adjustment	95% Limits	
100 μm FDM	0.6146	± 0.0030	0.5953	± 0.0059	1.54E-02
200 μm FDM	0.5969	± 0.0049	0.5681	± 0.0060	2.57E-02
300 μm FDM	0.5699	± 0.0033	0.5358	± 0.0039	3.53E-02
SLM	0.6462	± 0.0029	0.6150	± 0.0084	2.07E-02
Reference	0.611	$\pm \text{N/A}$	0.611	$\pm \text{N/A}$	0.00E+00

4.2.2 Critical Cavitation Number

The critical cavitation number for each test was determined by averaging the C_D and K at each setpoint in the individual test. The data for each test was then fit to a set of linear functions of C_D as a function of the square root of K for the cavitating and non-cavitating regimes of flow as we know that these values are related to each other linearly through Equation 4. Through inspection of the data the ranges for each curve fit were determined. The intersection point of the two linear curve fits is taken to be the critical cavitation number. Figure 36 shows a representative plot of the two curve fits and their resulting intersection point for the SLM configuration. lists the average K_{crit} for each sample configuration including the previously mentioned FDM configurations.

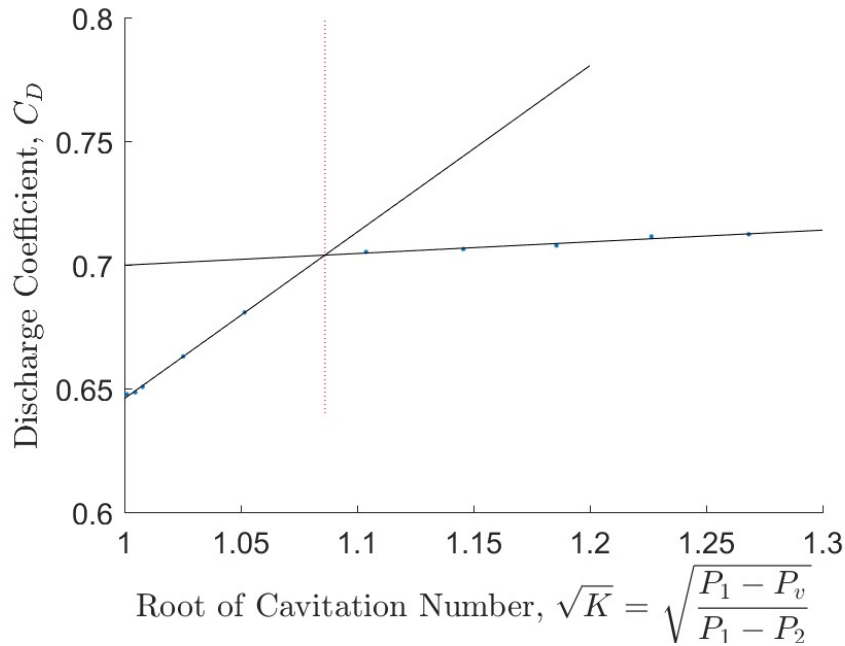


Figure 36: SLM K_{crit} Identification

Table 10: Block 2, Block 3, and Reference K_{crit} Values

Sample Configuration	K_{crit}	C_{Dcrit}
300 μm	1.078	0.6151
200 μm	1.083	0.6462
100 μm	1.116	0.6877
SLM	1.154	0.7487
Reference	1.45	0.7360

4.2.3 High Frequency Results

A set of High Frequency plots at progressing times in the test are shown in Figure 37 for a representative test, SLM Test 4-2. Notable frequency peaks are identified with markers. Each subplot in the figure is at a separate setpoint in the test.

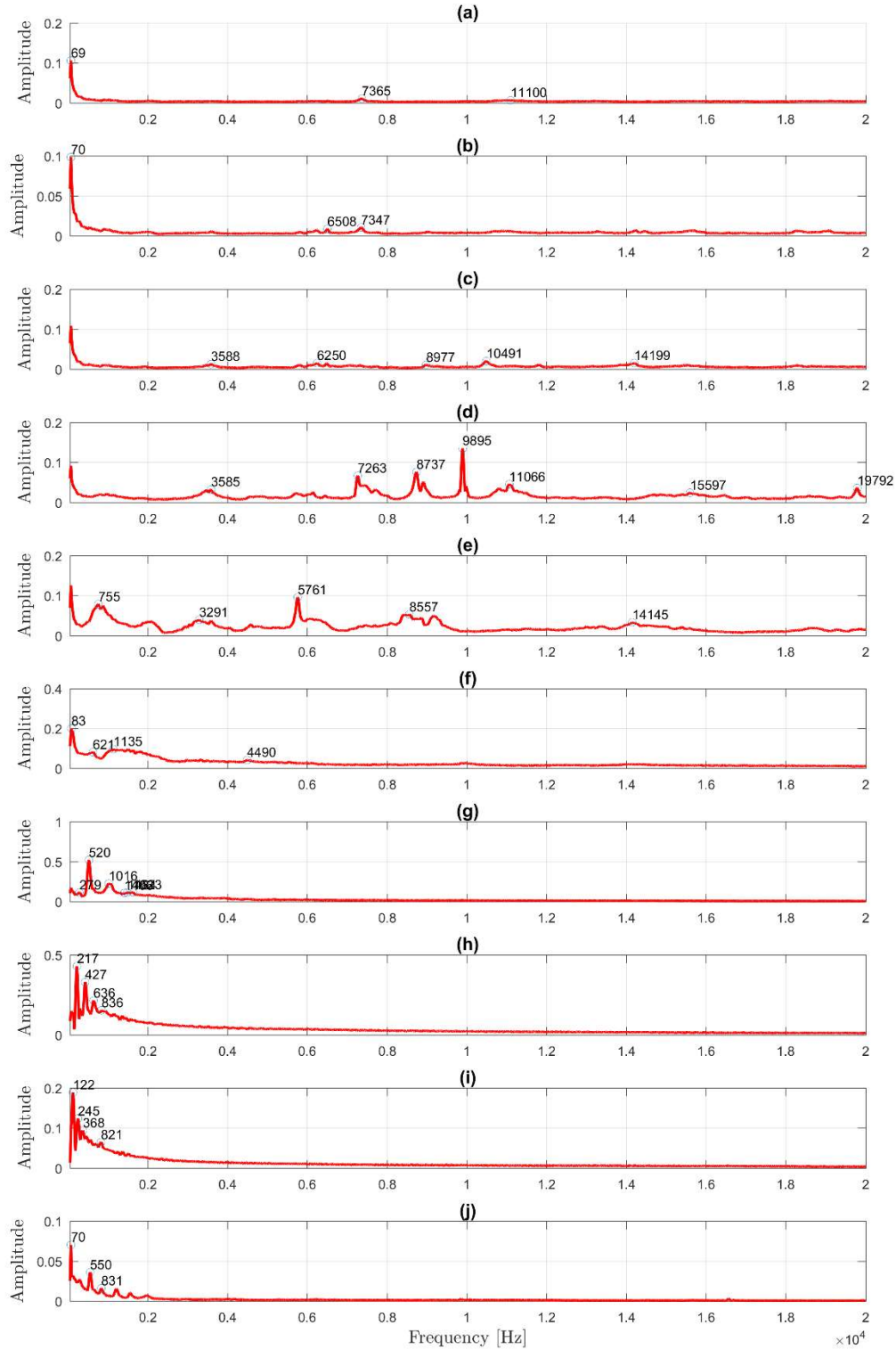


Figure 37: B3-SLM-4-2 HF Plots: (a) $t = 6-9s$ $K = 1.6$, (b) $t = 16-19s$ $K = 1.5$, (c) $t = 26-29s$ $K = 1.4$, (d) $t = 36-39s$ $K = 1.3$, (e) $t = 46-49s$ $K = 1.2$, (f) $t = 56-59s$ $K = 1.1$, (g) $t = 66-69s$ $K = 1.05$, (h) $t = 76-79s$ $K = 1.02$, (i) $t = 86-89s$ $K = 1.01$, (j) $t = 96-99s$ $K = 1.0$

At the $K = 1.3$ setpoint in Figure 37 (d) three frequencies are prevalent at 7263 Hz, 8737 Hz, and 9895 Hz. All three of these frequencies fall within Strouhal numbers that are likely for vortex shedding [20]–[27] based on the reductions in area by way of the contraction coefficient as done previously. The 7263 Hz frequency falls at a $St = 0.259$ with the peak Strouhal number being calculated to be 0.234 at that point in the test. At the $K = 1.2$ in Figure 37 (e) setpoint in the test the frequency peak shifts to 5761 Hz which is at a St value of 0.214 versus the peak value calculated to be 0.234. Further reductions in the peak frequency in Figure 37 (f)–(j) can't be explained from the data available and may be due to increase in flow velocity downstream with decreasing Cavitation Number which would need to be measured in order to determine the Strouhal numbers downstream of the inlet cavitation bubble.

Although not the primary focus of this thesis, other similar frequency analyses of unsteady pressure phenomenon for these tests are included in Appendix F for future analysis. They generally show the same Strouhal number agreement as the test presented.

4.3 Subtractively Manufactured Orifice Data

Block 4 and Block 5 tests were performed on subtractively manufactured samples. Block 4 tests were used to determine if additional sharpening of the inlet was needed and after testing it was determined that sharpening was necessary and therefore Block 4 testing data will not be included in this thesis.

Figure 38 shows the response of the Block 5 tests to the set conditions controlled by the globe valve. The x-axis is the time of the test and the y-axis is the cavitation number during the test. Cavitation Number is seen decreasing in steps as the test progresses. The results in Figure 38 closely follow the expected setpoint schedule shown in Figure 23. The fluctuations seen in the cavitation number can be attributed to the closed loop control by the globe valve as previously described in 4.2. The instability at $K = 1.02$ is due to the flow resistance as previously described in 4.3.

Figure 39 shows the mass flow trends for this block of testing. The x-axis is the time during the test and the y-axis is the mass flow in kg/s. Notably, over nearly the entire test, mass flow is generally constant and invariant to the changes in cavitation number as defined in the test. This is much different than the previous configurations. The mass flow rate differences from part-to-part can be seen, as well as the test-to-test deviation possibly due to differences in upstream pressure, cavitation number, etc. These test-to-test deviations can be partially accounted for when analyzed in the context of nondimensional cavitation number.

Figure 40 shows the relation of mass flow on the y-axis to a nondimensional cavitation number, thereby removing test-to-test differences in upstream and downstream pressure, on the x-axis which shows as cavitation number decreases from $K = 1.6$ the mass is invariant rather than increasing with increasing steps in cavitation number indicating that the mass flow is choked. The

critical cavitation number is therefore greater than $K = 1.6$ which is greater than the predicted value by Nurick [8]. This could be attributed to a roughness difference from that of the articles Nurick tested and the articles used in this work.

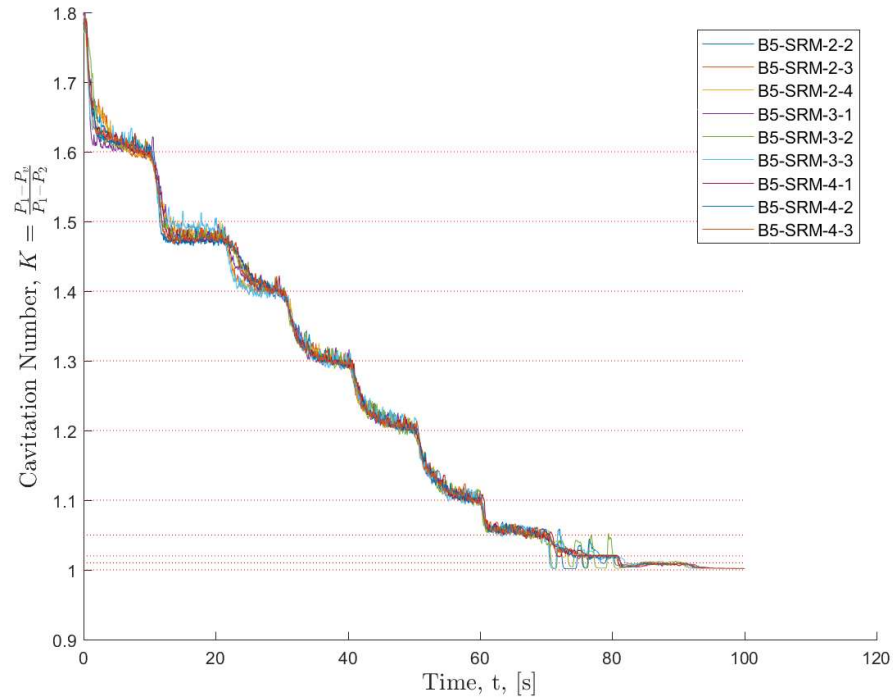


Figure 38: Block 5 Sample Cavitation Number trend with Time

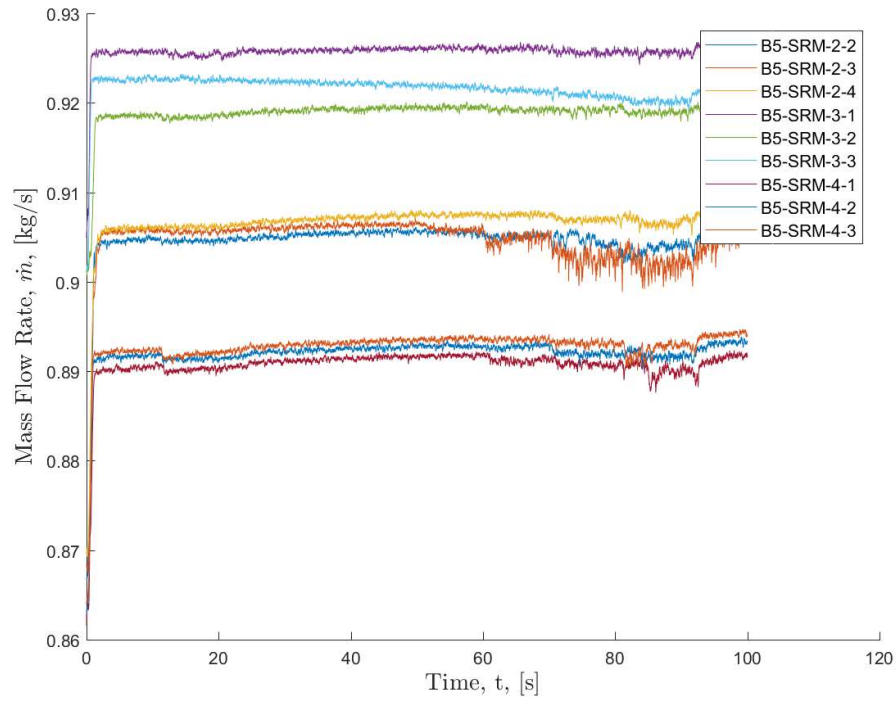


Figure 39: Block 5 Sample Mass Flow trend with Time

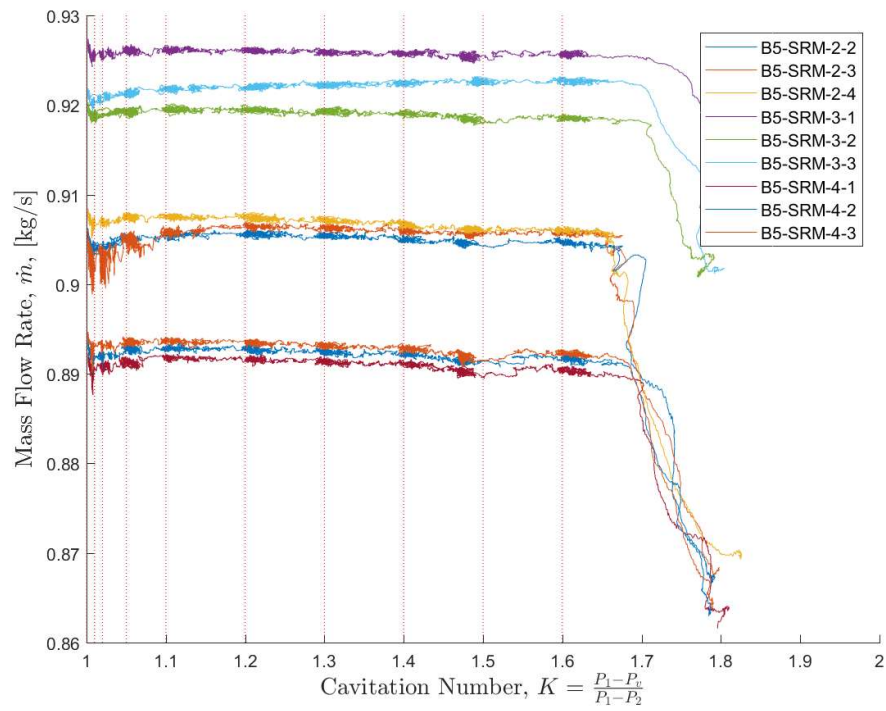


Figure 40: Block 5 Sample Mass Flow Relation to Cavitation Number

Figure 41 shows the nondimensional discharge coefficient on the y-axis with respect to the nondimensional cavitation number on the x-axis for all Block 5 tests and a predicted value for a sharp edge inlet orifice transitioning to cavitation at $K = 1.45$ derived from Equation 3 and Equation 5. This relationship shown Figure 41 shows close agreement between the subtractively manufactured configuration and the accepted reference except for the transition cavitation number. By plotting the data with respect to the discharge coefficient and the cavitation number the variance due to testing variables such as upstream and downstream pressure are factored out of the data. The differences between the curves is now solely due to the inlet radius, roughness, other geometrical effects, as well as uncontrollable deviances such as differences in water purity and gasification. Additionally, as Equation 4 shows, the values of C_D and K are related through C_c which therefore means that Figure 41 can be used to graphically analyze the differences in cavitation operation for the different articles and tests. This is likely due to difference in roughness from the subtractively manufactured configuration to that of the reference. In Figure 41, the knee in the curves is the cavitation number at which the tests transition from non-cavitating orifice flow to cavitation. The transition cavitation number from the data looks to be $K \approx 1.7$ rather than the accepted $K = 1.45$. The average cavitation number across the samples is 0.6161 compared to 0.611 of the accepted reference which is effectively in the noise.

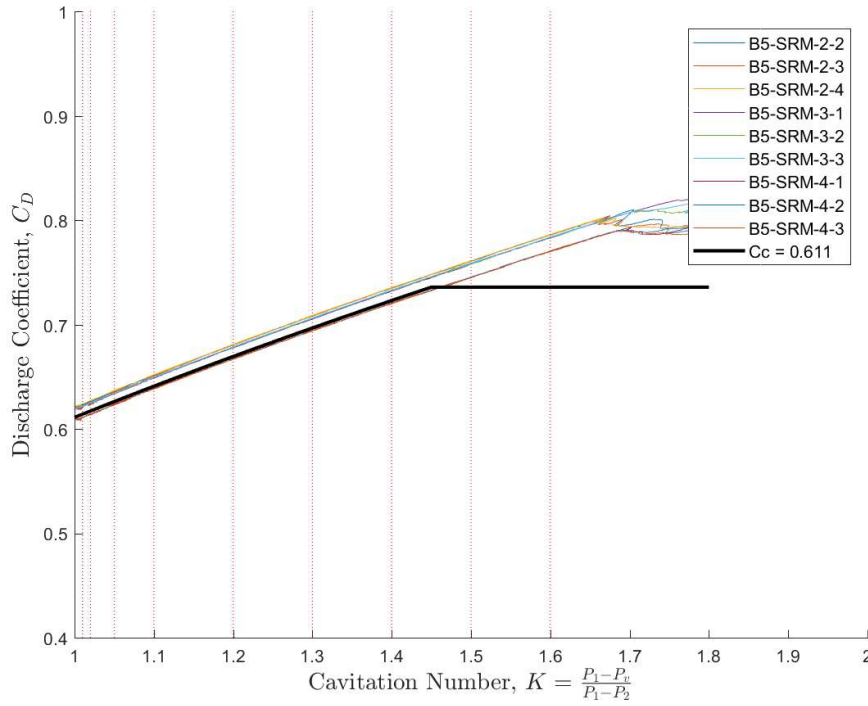


Figure 41: Block 5 Sample Discharge Coefficient and Cavitation Number Relationship (Predicted and Measured)

4.3.1 Contraction Coefficient

The Contraction Coefficient and related uncertainty for each test was determined using the same approach as used in 4.1.2. To compare the contraction coefficient value for each sample configuration an average and 95% confidence limits of the mean was determined. Figure 42 shows a probability distribution function for each configuration. Dotted lines demarcate the 95% confidence limits. This shows that the configurations are statistically different with respect to their mean contraction coefficient values. The value determined was 0.6161. This value can be adjusted for the inlet edge radius using a relation derived by Nurick [2]. This empirical relation outlined in Equation 9 adjusts this C_c value as previously documented in Section 4.1.2. The original value and the adjusted value is listed in Table 11 with the Block 2 FDM, Block 3 SLM values, and the reference derived from work by Nurick[8] and Howland and Richetta[28].

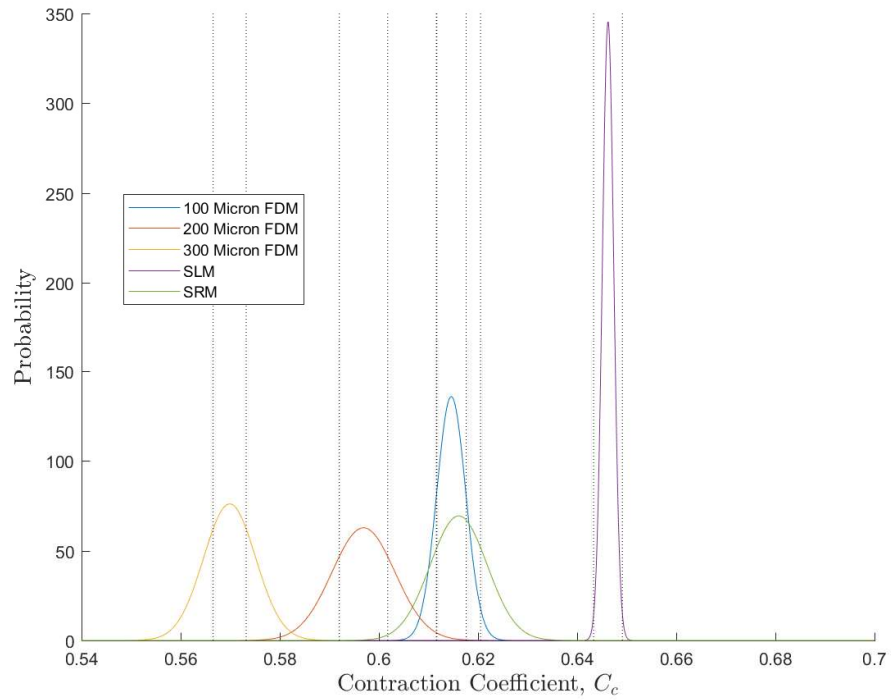


Figure 42: Block 2, 3, and 5 Contraction Coefficient Probability Density Function

Table 11: Original and Adjusted Values for Contraction Coefficient

Sample Type	Cc				Average r/d
	Original	95% Limits	Radius Adjustment	95% Limits	
100 μm FDM	0.6146	± 0.0030	0.5953	± 0.0059	1.54E-02
200 μm FDM	0.5969	± 0.0049	0.5681	± 0.0060	2.57E-02
300 μm FDM	0.5699	± 0.0033	0.5358	± 0.0039	3.53E-02
SLM	0.6462	± 0.0029	0.6150	± 0.0084	2.07E-02
SRM	0.6161	± 0.0044	0.6082	± 0.0056	6.23E-03
Reference	0.611	$\pm \text{N/A}$	0.611	$\pm \text{N/A}$	0.00E+00

4.3.2 Critical Cavitation Number

The critical cavitation number for the subtractively manufactured configuration was unable to be determined from the data as all the data points are in the cavitating regime of flow. Figure 43 shows a representative plot of this.

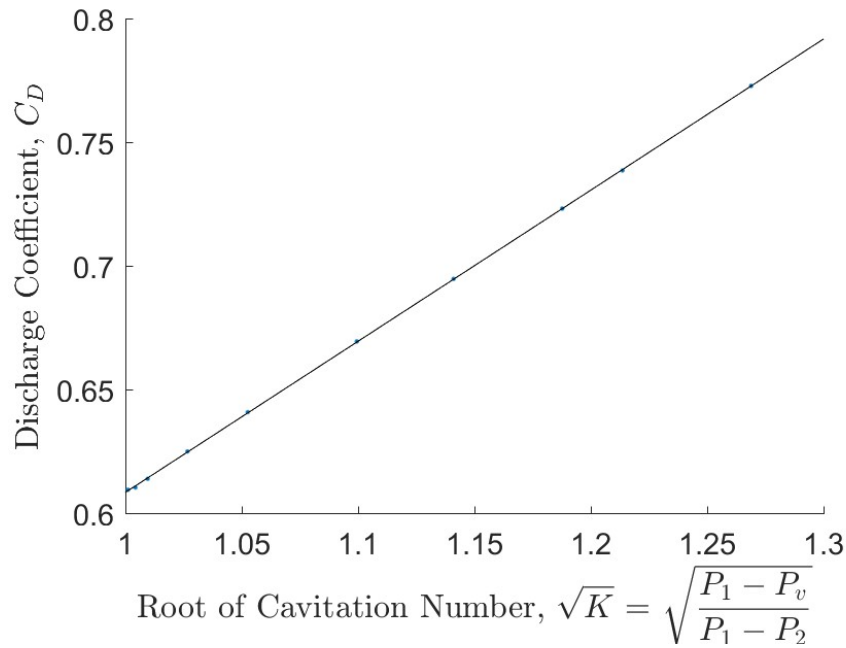


Figure 43: Block 5 K_{crit} Identification

4.3.3 High Frequency Results

A set of High Frequency plots at progressing times in the test are shown in Figure 43 for a representative test, Subtractively Manufactured Test 2-3. Notable frequency peaks are identified with markers. Each subplot in the figure is at a separate setpoint in the test.

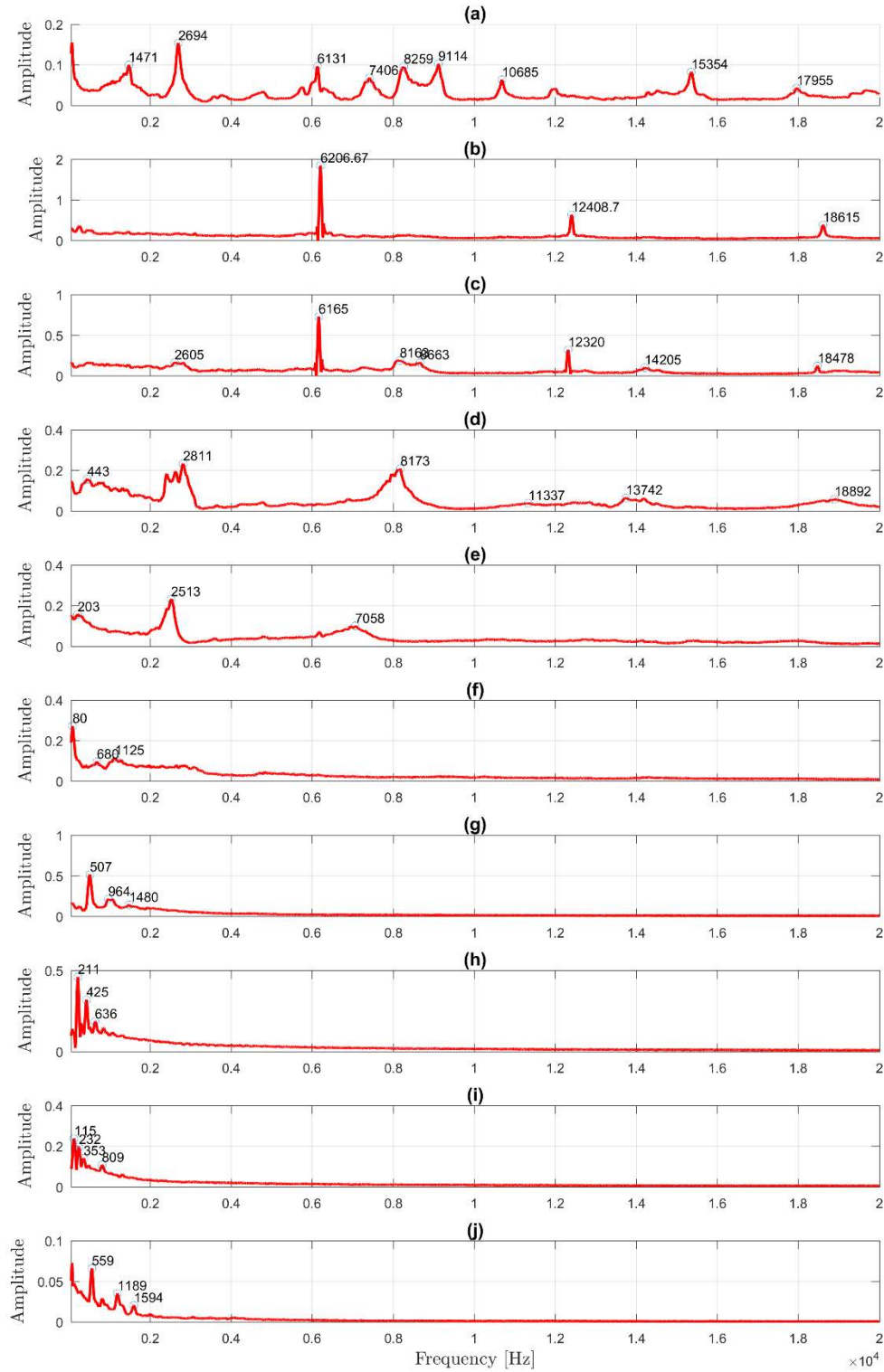


Figure 44: B5-SRM-2-3 HF Plots: (a) $t = 6-9s$ $K = 1.6$, (b) $t = 16-19s$ $K = 1.5$, (c) $t = 26-29s$ $K = 1.4$, (d) $t = 36-39s$ $K = 1.3$, (e) $t = 46-49s$ $K = 1.2$, (f) $t = 56-59s$ $K = 1.1$, (g) $t = 66-69s$ $K = 1.05$, (h) $t = 76-79s$ $K = 1.02$, (i) $t = 86-89s$ $K = 1.01$, (j) $t = 96-99s$ $K = 1.0$

At the $K = 1.5$ setpoint in Figure 44 (b) a frequency peak of 6207 Hz is identified. This peak corresponds with a Strouhal number of 0.233 whereas the peak Strouhal number for this point during the test is identified to be 0.234. This close agreement between the peak Strouhal number and the number attained during the test along with the high intensity of the frequency peak suggests that this peak is due to a vortex shedding frequency of the fluid device. Additionally, at the $K = 1.4$ setpoint a similar peak at 6165 Hz is identified which corresponds with $St = 0.231$ whereas the peak is at $St = 0.234$. This is additionally explained by way of the vortex shedding frequency. Further reductions in the peak frequency in Figure 44 (d)-(j) can't be explained from the data available and may be due to increase in flow velocity downstream with decreasing Cavitation Number which would need to be measured in order to determine the Strouhal numbers downstream of the inlet cavitation bubble.

Although not the primary focus of this thesis, other similar frequency analyses of unsteady pressure phenomenon for these tests are included in Appendix F for future analysis. They generally show the same Strouhal number agreement as the test presented.

4.4 Roughness Relationships to the Contraction Coefficient and Critical Cavitation Number

By comparing the contraction coefficient and critical cavitation number across multiple configurations by way of certain roughness variables, some relationships and trends can be seen in the data. Roughness variables analyzed in this section include the FDM layer height, h , the arithmetic mean roughness, Ra , the mean roughness spacing, S , and the highest peak value, Rp all documented in Table 1 or Table 3.

4.4.1 FDM Layer Height

FDM layer height was used to analyze tests in Block 2. Figure 45 shows the data along with a linear fit of the data. The equation for the linear fit of the data is shown in Equation 14. This equation predicts a value of 0.6259 for a part with “zero layer height” which is close to the value of the sharp edge inlet reference. This indicates not only a generally good agreement with the Block 2 data but also with the accepted reference value for C_c .

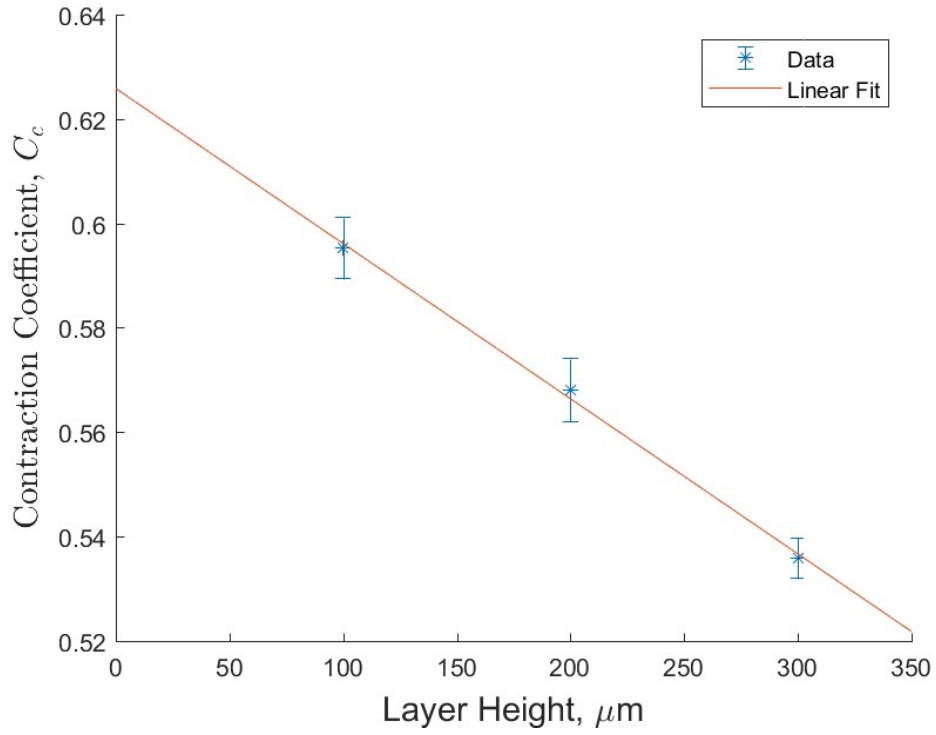


Figure 45: Layer Height - Contraction Coefficient Relationship

$$C_c = (-2.9735 * 10^{-4}) * h + 0.6259$$

14

When comparing K_{crit} using this variable, Figure 46 shows a few fits to the data. The limited datapoints for this variable limit the degree of information we can glean but an exponential fit does well to predict the zero layer height critical cavitation number of $K = 1.45 - 1.6$.

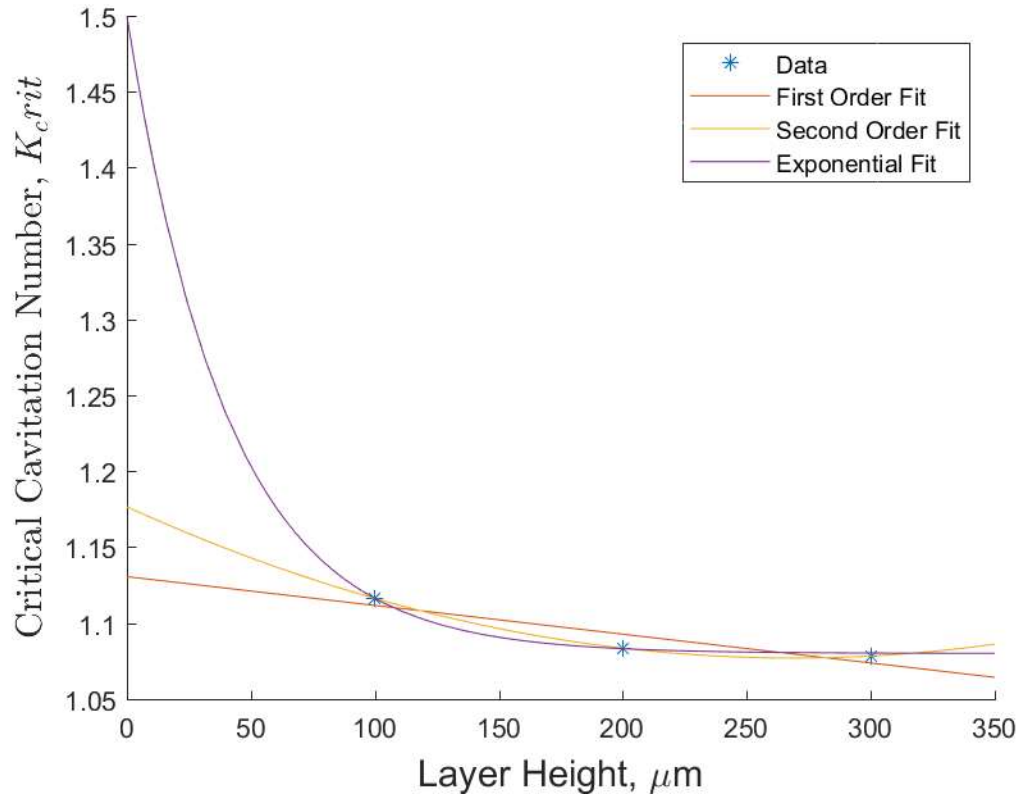


Figure 46: Layer Height - Critical Cavitation Number Relationship

4.4.2 Arithmetic Mean Roughness (Ra)

Figure 47 compares contraction coefficient using arithmetic mean roughness (Ra) of the part configurations. Both a linear fit and second order fit do well to predict values close the ideal value of 0.611 predicted by Howland and Richetta [28]. The linear fit predicts a zero roughness C_c of 0.6230 whereas the second order fit predicts a value of 0.6111 for the y-intercept value. Therefore, both of these functions fit the data well and fit predictions for zero roughness ideal configurations. More information would allow for the finer details of this relationship to be understood.

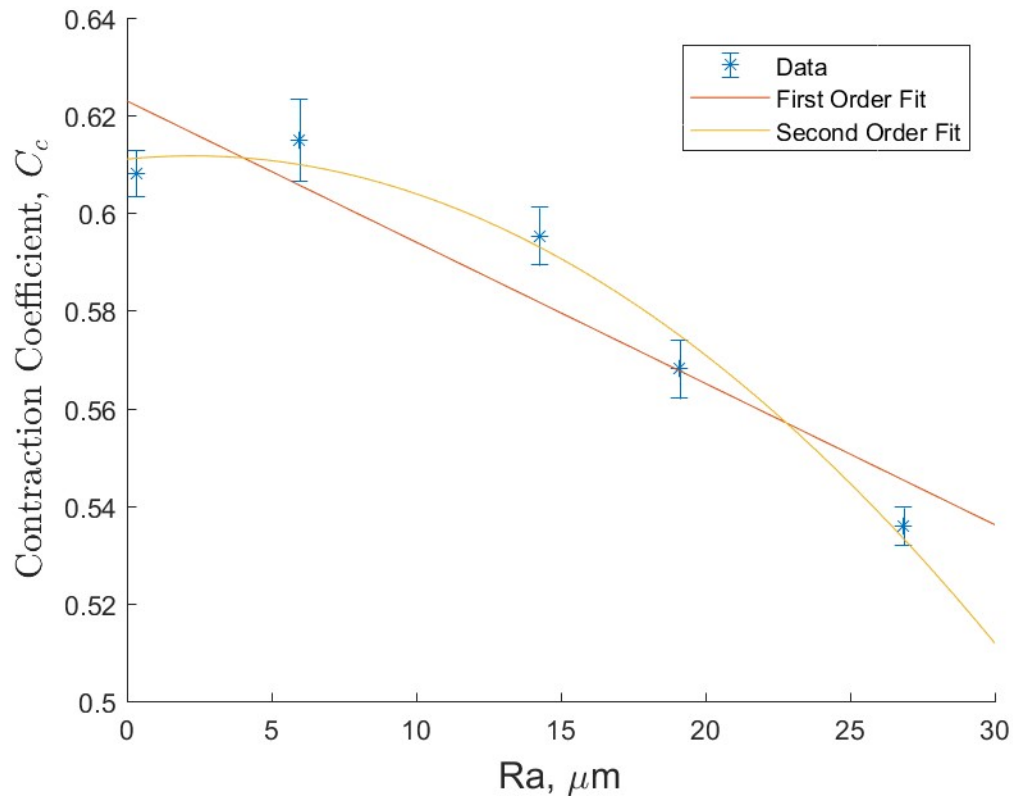


Figure 47: Mean Roughness - Contraction Coefficient Relationship

Figure 48 compares critical cavitation number using arithmetic mean roughness. None of the chosen fits shows good agreement to the data. This may mean that arithmetic mean roughness is not tied to the onset of cavitation.

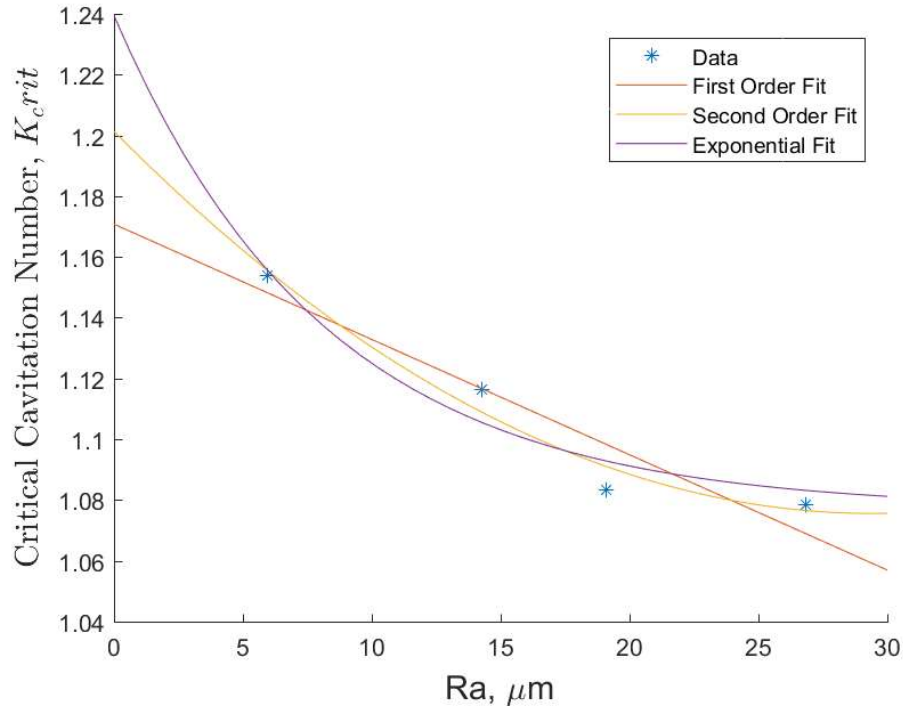


Figure 48: Mean Roughness - Critical Cavitation Number Relationship

4.4.3 Roughness Profile Spacing (S)

Using the roughness profile spacing. One can draw a possible linear fit to the data for contraction coefficient as shown in Figure 49. This fit is very similar to that of the layer height due to the intrinsic link between the layer height and peak-to-peak spacing of the roughness profile of the parts. The fit slightly over predicts a “zero” value closer to 0.64. Comparing the critical cavitation number with the peak-to-peak spacing does not find any significant curve fits to the data as shown in Figure 50.

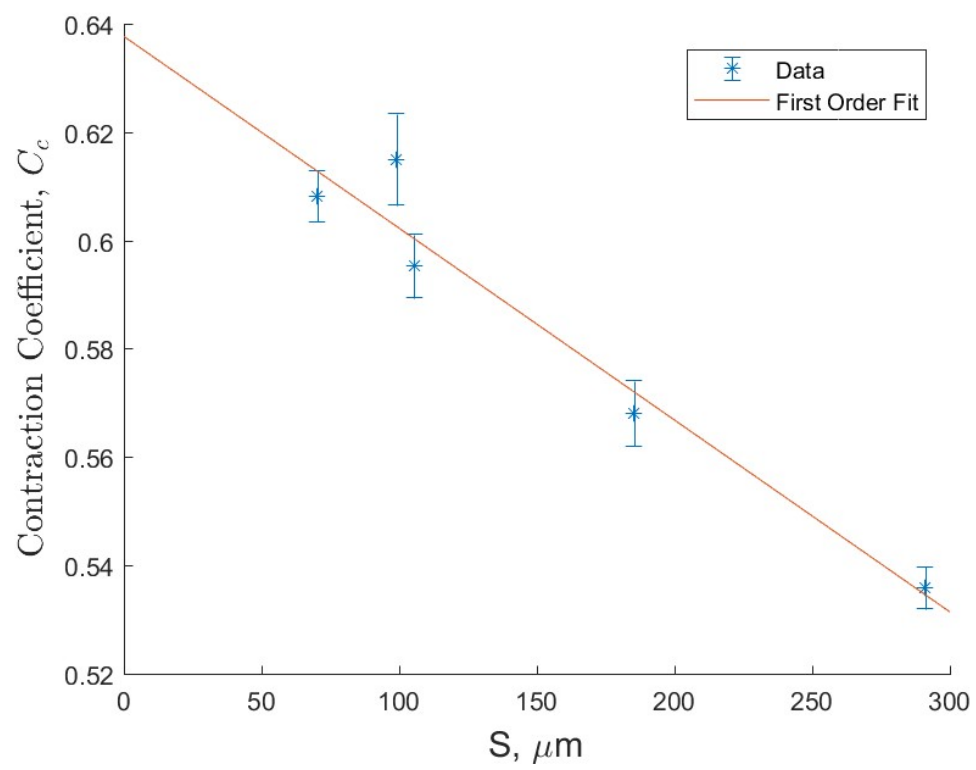


Figure 49: Peak-to-Peak Spacing - Contraction Coefficient Relationship

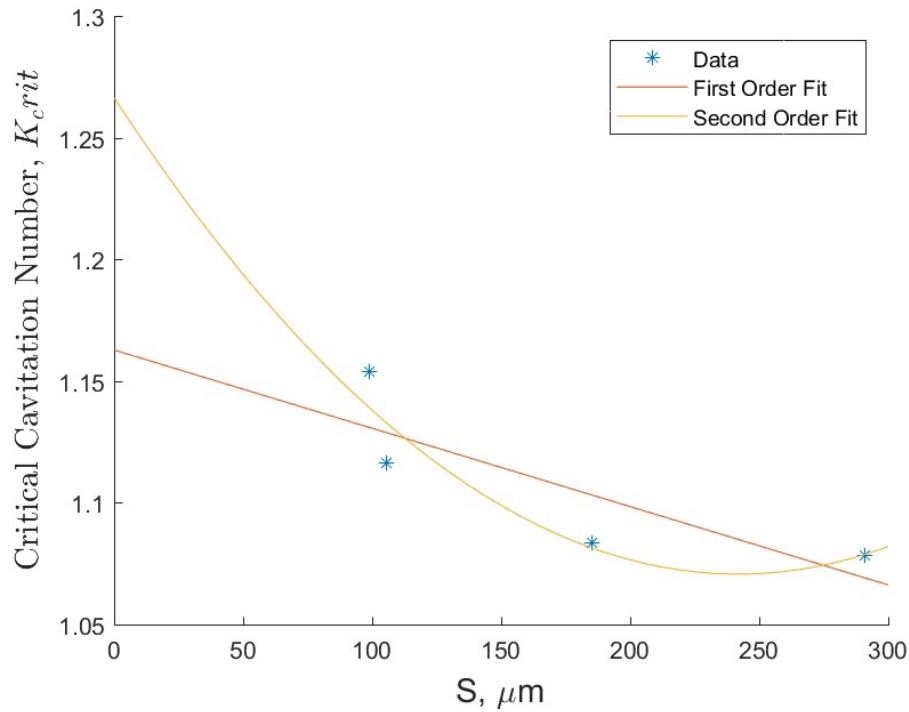


Figure 50: Peak-to-Peak Spacing - Critical Cavitation Number Relationship

4.4.4 Peak Height (R_p)

The peak height in the internal bore of the parts does well to characterize the level of obstruction in the diameter of the orifice. Figure 51 shows the peak height in micrometers on the x-axis and the contraction coefficient value in the y-axis. None of the fits chosen for the data show good agreement to the data. Figure 52 shows the peak height in micrometers on the x-axis in relation to the critical cavitation number on the y-axis. The exponential fit closely aligns with the data available and predicts a y-intercept of 1.6296. The second order fit aligns well but predicts a y-intercept of 1.3058. More information is necessary to find detailed trends of the data and how the variables effect the fluid phenomena in a more detailed way.

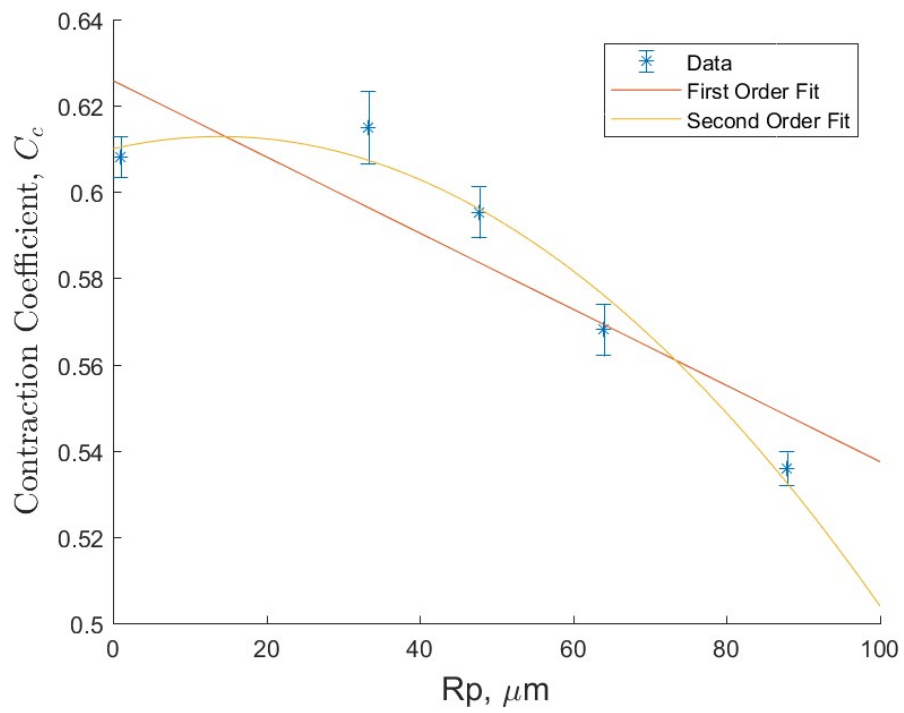


Figure 51: Peak Height - Contraction Coefficient Relationship

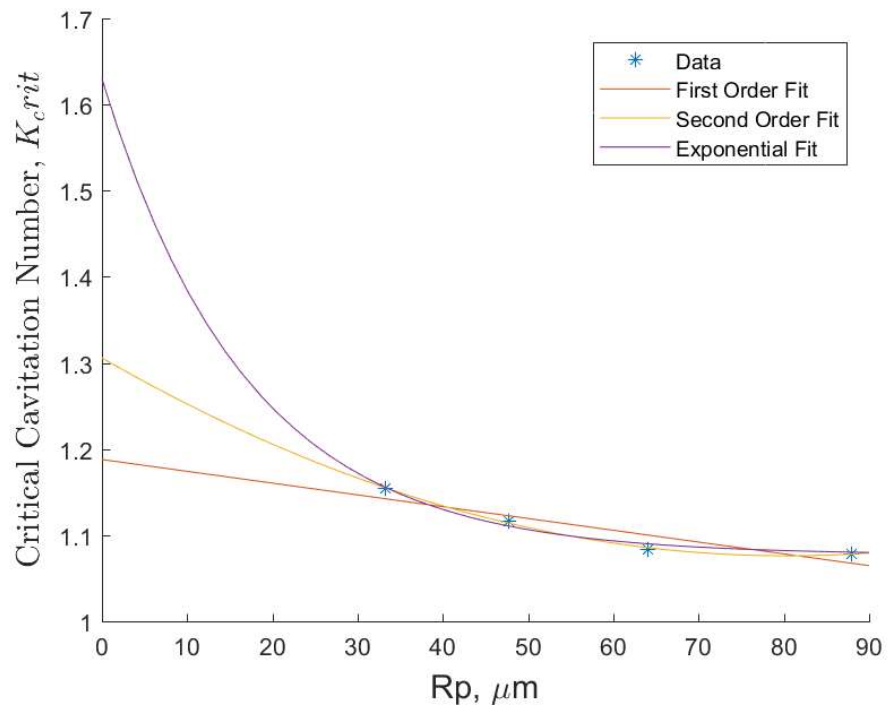


Figure 52: Peak Height - Critical Cavitation Number Relationship

CHAPTER 5

CONCLUSIONS

From these results a few conclusions can be inferred. These are both qualitative observations as well as quantitative differences between the five different configurations.

1. Effective area decreases with increasing roughness spacing/manufacturing characteristic length. The FDM parts have a known characteristic length of their layer height. By fitting the adjusted Contraction Coefficient data to the layer height, a possible linear trend, detailed in Equation 14, appears as shown in Figure 45. With accounting for the inlet radius of the parts the 200 μm parts yield a 4.6% reduction in effective area when compared to the 100 μm parts and the 300 μm parts have a 10.0% reduction. When compared to the baseline value of 0.611 the 100 μm parts have a 2.6% reduction, the 200 μm parts have a 7.0% reduction and the 300 μm parts have a 12.3% reduction. This can additionally be shown in a plot of the peak-to-peak spacing of the roughness peaks to the contraction coefficient shown in Figure 49.
2. Onset of the cavitation occurs at a lower value of K in rougher/larger characteristic manufacturing length parts. In the higher roughness configurations, the onset of the cavitation occurs later than expected and the discharge coefficient on the whole is reduced when compared to the subtractively manufactured parts. This could be due in part to the large viscous boundary layer inhibiting the production of cavitation cavities along the wall at the inlet and reducing the free movement of the re-entrant jet. An exponential relationship looks to be apparent with K_{crit} and Peak Roughness Height (R_p) with a critical cavitation number floor of around 1.077. Figure 52 shows this exponential relationship. This relationship explains the plateau effect we see with increasing layer

heights/roughnesses not drastically changing the critical cavitation number for the configuration. Additionally, it predicts a “zero roughness” critical cavitation number value close to the values found in literature and close to the estimate for the subtractive parts in this study.

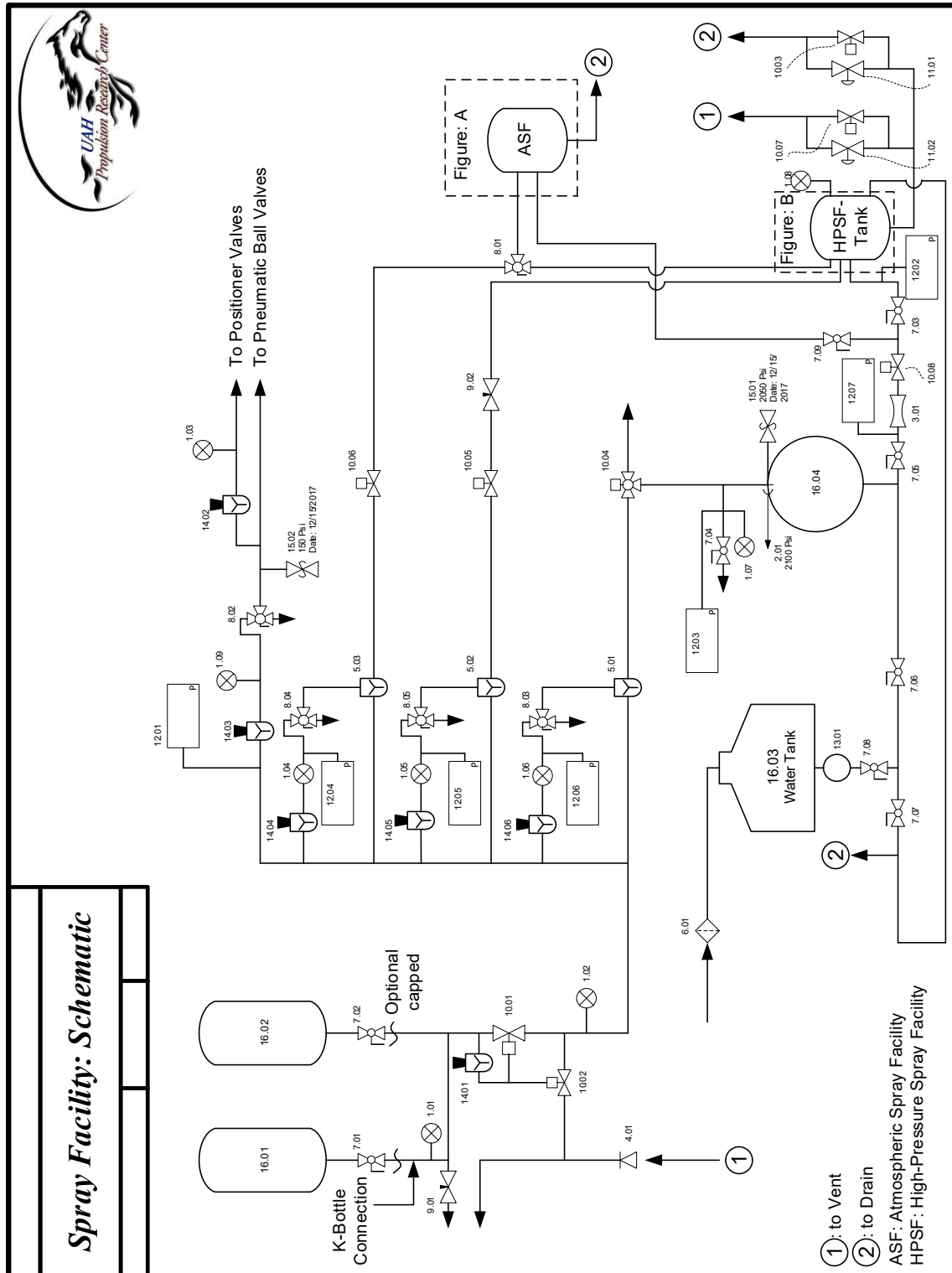
3. The acoustic environment in rougher configurations, characterized by higher R_p , R_a , and other roughness variables, is more broadband in nature. Compared to the narrow frequency bands in the subtractively manufactured parts the FDM and SLM parts have lower amplitude frequency peaks when vortex shedding is predicted. With the subtractive parts the peak frequencies are at a high amplitude and situated in close proximity to the peak Strouhal Number associated with vortex shedding for the part during that point in the test. Whereas, the FDM and SLM parts have lower amplitude frequency peaks with a greater offset from the peak Strouhal number. Qualitatively, this is also backed up by a loud high-pitched whistling noise that could be heard during testing of the subtractively manufactured parts. Likely this frequency, as previously described, is not tied to cavitation directly but instead tied to the turbulent vortex shedding flow condition inside of the orifice. Nonetheless, the rough parts such as the SLM and the FDM parts do not allow for such frequencies to persist in the device.

Future Work on this topic should be focused in the area of expanding the dataset with samples of greater layer height and more intermediate layer heights to determine the scaling function with layer height on FDM type samples. This can also be duplicated on the SLM type samples looking at profile spacing or layer height. Additional work expanding the dataset with

more inlet diameters and L/D ratios would allow for determination of the scaling relationship with those values.

Appendices

Appendix A: HPSF Plumbing & Instrumentation Diagram



Appendix B: Detailed Sizing Assumptions related to Venturi Flowmeter

Worst Case Low							
Backpressure: Ambient				Backpressure: 200 psig			
DP Operation		Cav Operation		DP Operation		Cav Operation	
rho	998 kg/m3	rho	998 kg/m3	rho	998 kg/m3	rho	998 kg/m3
P1	3193858.8 Pa	P1	3193859 Pa	P1	3193859 Pa	P1	3193859 Pa
PB	101325 Pa	PB	101325 Pa	PB	1480304 Pa	PB	1480304 Pa
Pv	3170 Pa	Pv	3170 Pa	Pv	3170 Pa	Pv	3170 Pa
Cc	0.5	Cc	0.5	Cc	0.5	Cc	0.5
D	0.1875 in	D	0.1875 in	D	0.1875 in	D	0.1875 in
	0.0047625 m		0.004763 m		0.004763 m		0.004763 m
A	1.78139E-05 m2	A	1.78E-05 m2	A	1.78E-05 m2	A	1.78E-05 m2
K	1.031739346	K	1.031739	K	1.862029	K	1.862029
mdot	0.699789399 kg/s	mdot	0.710808 kg/s	mdot	0.520906 kg/s	mdot	0.710808 kg/s
D2	0.62 in	D2	0.62 in	D2	0.62 in	D2	0.62 in
	0.015748 m		0.015748 m		0.015748 m		0.015748 m
A2	0.003116454 m2	A2	0.003116 m2	A2	0.003116 m2	A2	0.003116 m2
Vline	39.36198205 m/s	Vline	39.98176 m/s	Vline	29.30007 m/s	Vline	39.98176 m/s
Vinlet	0.224996696 m/s	Vinlet	0.228539 m/s	Vinlet	0.167482 m/s	Vinlet	0.228539 m/s
P1	463.230055 psi	P1	463.2301 psi	P1	463.2301 psi	P1	463.2301 psi
rho	998 kg/m3	rho	998 kg/m3	rho	998 kg/m3	rho	998 kg/m3
P1	3548732 Pa	P1	3548732 Pa	P1	3548732 Pa	P1	3548732 Pa
PB	101325 Pa	PB	101325 Pa	PB	1480304 Pa	PB	1480304 Pa
Pv	3170 Pa	Pv	3170 Pa	Pv	3170 Pa	Pv	3170 Pa
Cc	0.9	Cc	0.9	Cc	0.9	Cc	0.9
D	0.31 in	D	0.31 in	D	0.31 in	D	0.31 in
	0.007874 m		0.007874 m		0.007874 m		0.007874 m
A	4.86946E-05 m2	A	4.87E-05 m2	A	4.87E-05 m2	A	4.87E-05 m2
K	1.028472124	K	1.028472	K	1.714134	K	1.714134
mdot	3.686769808 kg/s	mdot	3.68677 kg/s	mdot	3.68677 kg/s	mdot	3.68677 kg/s
D2	0.62 in	D2	0.62 in	D2	0.62 in	D2	0.62 in
	0.015748 m		0.015748 m		0.015748 m		0.015748 m
A2	0.003116454 m2	A2	0.003116 m2	A2	0.003116 m2	A2	0.003116 m2
Vline	75.8638325 m/s	Vline	75.86383 m/s	Vline	75.86383 m/s	Vline	75.86383 m/s
Vinlet	1.185372383 m/s	Vinlet	1.185372 m/s	Vinlet	1.185372 m/s	Vinlet	1.185372 m/s
P1	514.7000611 psi	P1	514.7001 psi	P1	514.7001 psi	P1	514.7001 psi
% limit	0.189810982	% limit	0.1928	% limit	0.141291	% limit	0.1928
viscosity	0.000853477	viscosity	0.000853	viscosity	0.000853	viscosity	0.000853
Re	219205.1762	Re	222656.7	Re	163170.8	Re	222656.7

Worst Case High							
Backpressure: Ambient				Backpressure: 200 psig			
DP Operation		Cav Operation		DP Operation		Cav Operation	
rho	998 kg/m3	rho	998 kg/m3	rho	998 kg/m3	rho	998 kg/m3
P1	3193858.8 Pa	P1	3193859 Pa	P1	3193859 Pa	P1	3193859 Pa
PB	101325 Pa	PB	101325 Pa	PB	1480304 Pa	PB	1480304 Pa
Pv	3170 Pa	Pv	3170 Pa	Pv	3170 Pa	Pv	3170 Pa
Cc	0.95	Cc	0.95	Cc	0.95	Cc	0.95
D	0.1875 in	D	0.1875 in	D	0.1875 in	D	0.1875 in
	0.0047625 m		0.004763 m		0.004763 m		0.004763 m
A	1.78139E-05 m2	A	1.78E-05 m2	A	1.78E-05 m2	A	1.78E-05 m2
K	1.031739346	K	1.031739	K	1.862029	K	1.862029
mdot	1.329599858 kg/s	mdot	1.350535 kg/s	mdot	0.989721 kg/s	mdot	1.350535 kg/s
D2	0.62 in	D2	0.62 in	D2	0.62 in	D2	0.62 in
	0.015748 m		0.015748 m		0.015748 m		0.015748 m
A2	0.003116454 m2	A2	0.003116 m2	A2	0.003116 m2	A2	0.003116 m2
Vline	74.7877659 m/s	Vline	75.96535 m/s	Vline	55.67014 m/s	Vline	75.96535 m/s
Vinlet	0.427493723 m/s	Vinlet	0.434225 m/s	Vinlet	0.318216 m/s	Vinlet	0.434225 m/s
P1	463.230055 psi	P1	463.2301 psi	P1	463.2301 psi	P1	463.2301 psi
rho	998 kg/m3	rho	998 kg/m3	rho	998 kg/m3	rho	998 kg/m3
P1	3548732 Pa	P1	3548732 Pa	P1	3548732 Pa	P1	3548732 Pa
PB	101325 Pa	PB	101325 Pa	PB	1480304 Pa	PB	1480304 Pa
Pv	3170 Pa	Pv	3170 Pa	Pv	3170 Pa	Pv	3170 Pa
Cc	0.9	Cc	0.9	Cc	0.9	Cc	0.9
D	0.31 in	D	0.31 in	D	0.31 in	D	0.31 in
	0.007874 m		0.007874 m		0.007874 m		0.007874 m
A	4.86946E-05 m2	A	4.87E-05 m2	A	4.87E-05 m2	A	4.87E-05 m2
K	1.028472124	K	1.028472	K	1.714134	K	1.714134
mdot	3.686769808 kg/s	mdot	3.68677 kg/s	mdot	3.68677 kg/s	mdot	3.68677 kg/s
D2	0.62 in	D2	0.62 in	D2	0.62 in	D2	0.62 in
	0.015748 m		0.015748 m		0.015748 m		0.015748 m
A2	0.003116454 m2	A2	0.003116 m2	A2	0.003116 m2	A2	0.003116 m2
Vline	75.8638325 m/s	Vline	75.86383 m/s	Vline	75.86383 m/s	Vline	75.86383 m/s
Vinlet	1.185372383 m/s	Vinlet	1.185372 m/s	Vinlet	1.185372 m/s	Vinlet	1.185372 m/s
P1	514.7000611 psi	P1	514.7001 psi	P1	514.7001 psi	P1	514.7001 psi
% limit	0.360640866	% limit	0.366319	% limit	0.268452	% limit	0.366319
viscosity	0.000853477	viscosity	0.000853	viscosity	0.000853	viscosity	0.000853
Re	416489.8347	Re	423047.8	Re	310024.6	Re	423047.8

Appendix C: Detailed Calibration Reports

PRC Calibration Report

Date: 7/26/2018Operator : Dalton HicksInstrument Pressure TransducerRange 0-500 (psig)Manufacturer OmegadyneModel PX309-500G5VSerial Number 083131D112

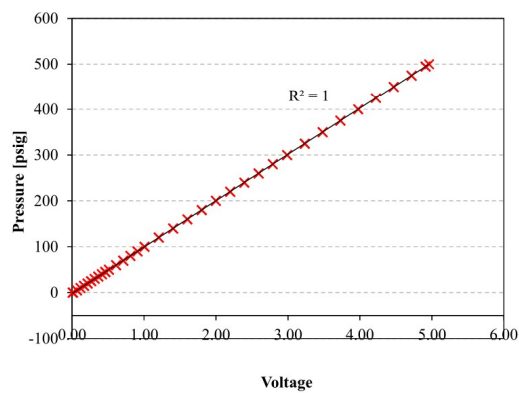
Calibration Source: Instrument Type: Dead Weight Pressure Tester

Model #: R 50

Serial #: 17745

Slope 101.05 psi/VOffset -1.64 psi

Known Pressure [psig]	Measured Voltage [V]
0	0.004221
5	0.065222
10	0.114711
15	0.1643
20	0.213592
25	0.263261
25	0.263322
30	0.312684
35	0.361935
40	0.41142
45	0.460641
45	0.460488
50	0.51006
60	0.608957
70	0.708069
80	0.806813
90	0.905461
100	1.005638
100	1.003914
120	1.201726
140	1.39958
160	1.601325
180	1.799197
200	1.996977
220	2.194906
240	2.392552
260	2.590554
280	2.788461
300	2.98622
325	3.233351
350	3.480575
375	3.728031



400	3.974383
425	4.221788
450	4.468337
475	4.715461
495	4.912183
500	4.961287
495	4.911791
475	4.715631
450	4.468841
425	4.221949
400	3.97461
375	3.728152
350	3.481134
325	3.233464
300	2.986172
280	2.788386
260	2.590768
240	2.393
220	2.195204
200	1.997444
180	1.79954
160	1.601454
140	1.403778
120	1.205881
90	0.908732
80	0.809563
70	0.710317
60	0.610878
50	0.511876
45	0.462449
40	0.412931
35	0.363368
30	0.313908
25	0.264441
20	0.214878
15	0.165333
10	0.115819
5	0.066348
0	0.015199

PRC Calibration Report



Date: 5/30/2018

Operator : Erik Korzon

Instrument Pressure Transducer

Range 0-500 (psig)

Manufacturer Omegadyne

Model PX309-500G5V

Serial Number 103110D878

Calibration Source: Instrument Type: Dead Weight Pressure Tester

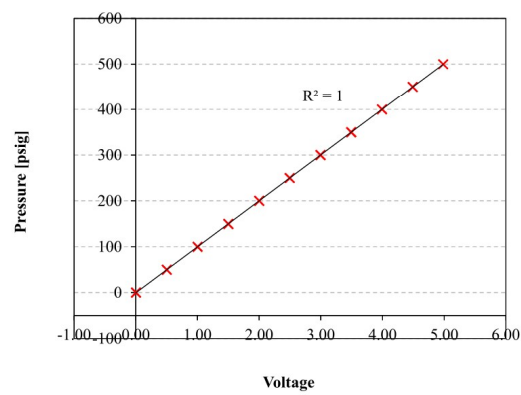
Model #: R 50

Serial #: 17745

Slope 100.33 psi/V

Offset -0.36 psi

Known Pressure [psig]	Measured Voltage [V]
0	-0.000406
50	0.499474
100	0.999998
150	1.498578
200	1.99669
250	2.493887
300	2.991094
350	3.48799
400	3.99023
450	4.48852
500	4.983268
450	4.488874
400	3.99176
350	3.495569
300	2.997966
250	2.498952
200	2.000952
150	1.502293
100	1.002848
50	0.501631
0	0.002651



PRC Calibration Report



Date: 7/12/2018

Operator : Jacey Allen

Instrument Pressure Transducer

Range 0-3000 (psig)

Manufacturer Honeywell

Model FPG

Serial Number 1144528

Calibration Source: Instrument Type: Dead Weight Pressure Tester

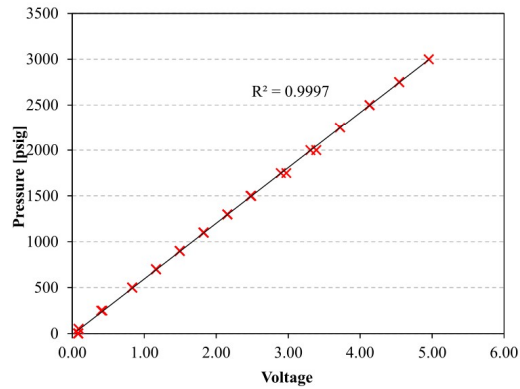
Model #: R-50

Serial #: 17745

Slope 607.27 psi/V

Offset -12.59 psi

Known Pressure [psig]	Measured Voltage [V]
0	0.085592
50	0.086885
250	0.41743
500	0.831121
700	1.161442
900	1.490363
1100	1.820972
1300	2.15255
1500	2.477123
1750	2.973038
2000	3.388498
2250	3.718924
2500	4.128329
2750	4.542052
3000	4.953651
2750	4.54238
2500	4.130769
2250	3.719144
2000	3.307009
1750	2.896078
1500	2.485174
1300	2.155942
1100	1.824403
900	1.493685
700	1.162999
500	0.831025
250	0.401857
50	0.08637
0	0.076036



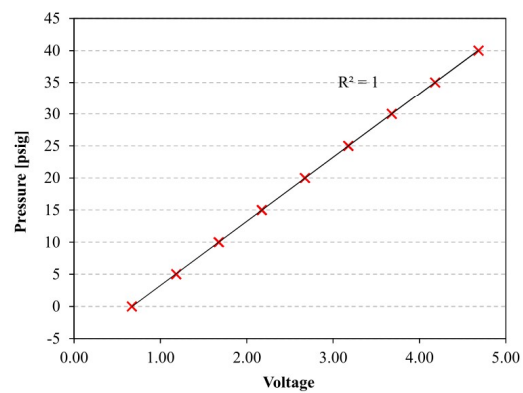
PRC Calibration Report

Date: 5/30/2018Operator : Dalton HicksInstrument Pressure TransducerRange 0-50 (psig)Manufacturer SensotecModel 2/741-OJZDSerial Number 750329

Calibration Source: Instrument Type: Dead Weight Pressure Tester
 Model #: TQ-130
 Serial #: 1230

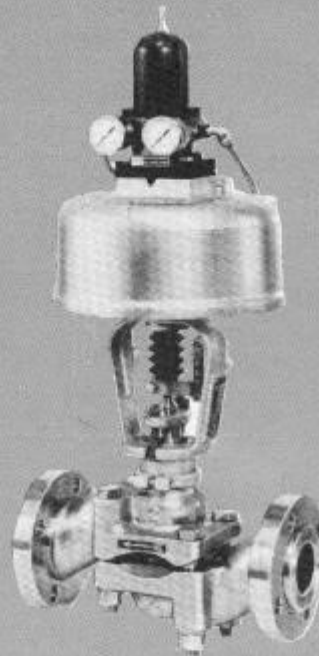
Slope 9.98 psi/VOffset -6.71 psi

Known Pressure [psig]	Measured Voltage [V]
0	0.668344
5	1.180787
10	1.672311
15	2.169637
20	2.670883
25	3.172368
30	3.675807
35	4.179203
40	4.68225
40	4.68291
35	4.181713
30	3.679285
25	3.177233
20	2.675866
15	2.175701
10	1.679082
5	1.183619
0	0.668241



Appendix D: Backpressure Control Valve Cutsheet

2600 Series Split Body Control Valve Building Blocks



Annin

Masoneilan **DRESSER**

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Foreword

The Group 26 split body control valve is the product of over 35 years of experience (longest in the industry) in the design and manufacture of split body valves. Designed as a standardized valve, it covers most normal applications and fulfills control requirements demanded of highly specialized valves.

The 2600 Series control valves are designed for applications requiring versatility as well as economy and where exotic material selections are a necessity. With its varied range of materials, configurations, trim options and the selection of actuators, it is a most versatile control valve. Features include:

Modular Construction

Allows one valve line to equip an entire plant for standard and severe services.

Quick Trim Changeout

Clamped-in seat ring allows "in line" trim replacement on corrosive services.

Smooth Internal Flow Passages

No-pocket design prevents material buildup.

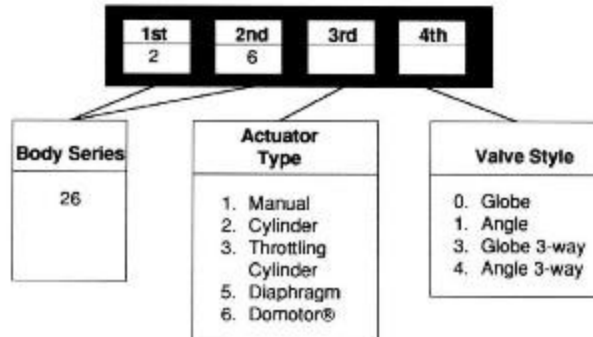
Stem Guiding

Stem guiding avoids buildup of sticky substances and plastic particles which collect behind conventional valve plugs guided by plug post and bushing.

Low weight and separable flanges permit low cost alloy bodies; one valve body adapts to ANSI Class 150 through 600 line flanges.

Domotor® actuator has maximum thrust to free valve plug in sticky service; integral positioner has no external feedback linkages, ideal in corrosive atmospheres. The positioner is mounted on top of the actuator, away from the packing box.

Numbering System



General Data

- | | |
|---|---|
| <ul style="list-style-type: none"> • Body <ul style="list-style-type: none"> types: cast split body
globe
angle
3-way globe
3-way angle flow direction: flow to open
flow to close C_v ratio: 50:1 materials: carbon and chrome-molybdenum steel; 316 and other 300 Series stainless steels; Alloy 20; Hastelloy "B" and "C", Monel and others • Flow Characteristics <ul style="list-style-type: none"> linear, equal percentage, semi-throttle • Actuator <ul style="list-style-type: none"> type: manual, cylinder, diaphragm Domotor® auxiliary handwheel: optional with Domotor® | <ul style="list-style-type: none"> • Trim <ul style="list-style-type: none"> types: contoured plug
LO-DB® multi-hole cage
Pee-Wee trim (1/2" - 1") materials: plug/stem
316 St. St.;
hardfaced 316 St. St.; Alloy 20;
other materials according to body material seat ring
316 St. St.; Alloy 20;
hardfaced 316 St. St.;
solid Stellite; soft seat Ⓞ
TFE or FEP Teflon and Kel-F;
other materials according to body material guide
Stellite (Standard);
Chrome plated 316 St. St.;
Aluminum bronze;
glass loaded Teflon;
Alloy 20; Monel |
|---|---|

Ⓞ Not available on LO-DB® trim or 3-way construction

Temperature Range/Seat Leakage

Valve Size (inches)	ANSI Class	Seat Type	Temperature Range		Globe & Angle	LO-DB® ①
			Min.	Max.		
1/2 - 8	150 - 600	Metal	-320°F	+1200°F	Class IV	Class IV
	150 - 600	Soft Seat	-320°F	+400°F	Class VI	-
10	150 - 300	Metal	-320°F	+1200°F	Class IV	-
	150 - 300	Soft Seat	-320°F	+400°F	Class VI	-

① LO-DB® through 6" only

Ratings/Connections

- Threaded (NPT)
- ▲ Separable Flange①
- Integral Flange
- Grayloc and Weld Ends

Valve Size (inches)	ANSI Class		
	150	300	600
1/2 - 2	• ▲ ■ □	• ▲ ■ □	• ▲ ■ □
3 & 4	▲ ■ □	▲ ■ □	▲ ■ □
6 & 8	■ □	■ □	■ □
10	■ □	■ □	-

① Carbon steel is standard
304 stainless steel is optional
other alloys available

Actuator Data

Manual		Domotor®	
type:	non-rising handwheel	type:	positioning pneumatic cylinder with integral positioner and loading regulator. (See SD CR4000 for additional information.)
material:	ductile iron	material:	cast aluminum
Cylinder		action:	increasing instrument signal retracts stem (direct positioner) increasing instrument signal extends stem (reverse positioner)
type:	pneumatic spring cylinder for on-off or throttling applications. (See SD CR5030 for additional information.)	instrument signal:	common full and split range signals
material:	glass fiber reinforced epoxy cylinder, steel piston, caps and connecting rods	supply:	40 - 100 psi
action:	spring to retract stem or spring to extend stem (also available without springs). Operated by a double acting positioner or a 3 or 4 way solenoid valve	loading pressure:	depends on available supply pressure, process conditions, fluid flow direction and fail safe action
supply:	40 - 150 psi	static air consumption:	0.5 SCFM @ 60 psi supply pressure
connections:	1/4" NPT upper and lower	air connections:	1/4" NPT instrument and supply
Diaphragm			
type:	field reversible spring diaphragm		
positioner:	Moore 750P		
handwheel:	not available		

Nominal Effective Area (sq. in.)	Maximum Stroke (in.)	Available Spring Ranges (psig) All Sizes
38	1.5	10-20
78	2.5	15-30
154	6.0	or
314	6.0	25-50

Domotor® Size	Maximum Stroke (in.)	Nominal Effective Area (sq. in.)
A	3/4	25
B	1 1/2	50
C	2 1/2	100
D	6	200

Standard actuator sizes

Valve Size (inches)	Actuator Size			
	Manual (in.)	Cylinder	Diaphragm	Domotor®
1/2	7	38 sq. in.	6	A
3/4	7	38 sq. in.	6	A
1	7	38 sq. in.	6	A
1 1/2	12	38 sq. in.	10	B
2	12	38 sq. in.	10	B
3	18	78 sq. in.	16	C
4 ANSI Class 300 or 600 ①	18	78 sq. in.	16	C
4 ANSI Class 600	18 ②	154 sq. in.	---	D
6 ANSI Class 150 or 300 ③	18	78 sq. in.	---	C
6 ANSI Class 300	18 ②	154 sq. in.	---	D
6 ANSI Class 600	18 ②	154 sq. in.	---	D
8	18 ③	C/F	---	D
10	18 ③	C/F	---	D

① Body for Series "C" actuators only

② 12" Yoke

③ 16" Yoke

Flow Coefficients - Rated C_v ^②

Critical Flow Factor F_L

Valve Size (inches)	Travel (inches)	Globe, Angle							LO-DB®	3-way
		Pee-Wee Trim ①			Reduced Trim		Full Trim			
1/2	.75	.04	.10	.25	0.6	1.5		4	4	4
3/4	.75	.04	.10	.25	0.6	1.5	4	6	4	6
1	.75	.04	.10	.25	0.6	1.5	4 6	12	6	10
1 1/2	1.5						12 16	25	16	25
2	1.5						16 25	46	25	40
3	2.5						46 75	110	75	95
4	2.5						75 110	195	110	175
6	2.5						195 275	-----	-----	-----
6	3						-----	400	275	360
8	5						275 400	640	-----	480
10	5						400 640	1000	-----	820

① C_v ratio 10:1

② Consult factory for other available C_v 's

Critical Flow Factor F_L Valve Fully Open

Valve Configuration	Flow to Close	Flow to Open
Globe, Full Trim	.80	.75
Angle, Full Trim	.80	.75
Globe, Reduced Trim	.80	.75
Angle, Reduced Trim	.80	.75
LO-DB® Trim	.95	.95
3-way Trim	.80	.80

C_v and F_L versus Travel

Standard Trim

Flow Direction: Flow to Open

ANSI Class: 150 through 600

Sizes: 1/2" through 10"

Flow Characteristic: SEMI-THROTTLE

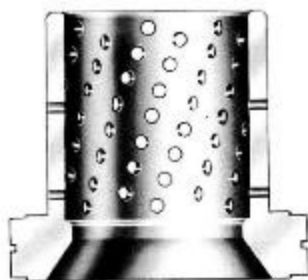
Percent (%) of Travel			10	20	30	40	50	60	70	80	90	100
F_L			0.90	0.88	0.87	0.84	0.82	0.79	0.78	0.77	0.76	0.75
Valve Size (Inches)	Orifice Diameter (Inches)	Travel (Inches)	Rated C_v									
1/2	.500	.50	.40	1.00	2.52	3.28	3.64	3.84	3.88	3.92	3.96	4
3/4	.625	.50	.60	1.50	3.78	4.92	5.46	5.76	5.82	5.86	5.94	6
1	.812	.50	1.20	3.00	7.50	9.80	10.90	11.52	11.60	11.70	11.80	12
1 1/2	1.250	.75	2.50	6.25	15.70	20.50	22.70	24.00	24.20	24.50	24.70	25
2	1.625	.75	4.60	11.50	28.90	37.70	41.80	44.16	44.60	45.00	45.50	46
3	2.625	1.50	11.00	27.50	69.30	90.20	100.00	105.80	106.00	107.00	108.00	110
4	3.500	1.50	19.50	48.75	122.00	159.00	177.00	187.28	188.00	189.10	193.00	195
6	4.625	2.50	40.00	100.00	252.00	328.00	364.00	384.00	388.00	392.00	396.00	400
8	4.250	2.50	27.50	68.75	173.00	225.00	250.00	264.00	266.00	269.00	272.00	275
6	4.500	2.50	40.00	100.00	252.00	328.00	364.00	384.00	388.00	392.00	396.00	400
8	6.250	5.00	64.00	160.00	403.00	524.00	582.00	614.40	620.00	627.00	633.00	640
10	8.000	5.00	100.00	250.00	630.00	820.00	910.00	960.00	970.00	980.00	990.00	1000

C_v and F_L versus Travel**Standard Trim**Flow Direction: Flow to Open
ANSI Class: 150 through 600
Sizes: 1/2" through 10"Flow Characteristic: **EQUAL PERCENTAGE**

Percent (%) of Travel			10	20	30	40	50	60	70	80	90	100
F _L			0.90	0.90	0.89	0.89	0.89	0.87	0.85	0.83	0.78	0.75
Valve Size (Inches)	Orifice Diameter (Inches)	Travel (Inches)	Rated C _v									
1/2	.500	.75	.10	.16	.30	.48	.64	.92	1.24	1.80	2.70	4
3/4	.625	.75	.15	.24	.45	.72	.96	1.38	1.86	2.79	4.02	6
1	.812	.75	.30	.48	.90	1.44	1.92	2.76	3.72	5.40	8.04	12
1 1/2	1.250	1.50	.62	1.00	1.87	3.00	4.00	5.75	7.75	11.20	16.70	25
2	1.625	1.50	1.15	1.84	3.45	5.52	7.36	10.50	14.20	20.70	30.80	45
3	2.625	2.50	2.75	4.40	8.25	13.20	17.60	25.30	34.10	49.50	73.70	110
4	3.500	2.50	4.87	7.80	14.60	23.40	31.20	44.80	60.40	87.70	130.00	195
6 300 ANSI	4.625	2.50	10.00	16.00	30.00	48.00	64.00	92.00	124.00	180.00	268.00	400
6 300 ANSI	4.250	2.50	6.87	11.00	20.60	33.00	44.00	63.20	85.20	123.00	184.00	275
6 600 ANSI	4.500	3.00	10.00	16.00	30.00	48.00	64.00	92.00	124.00	180.00	268.00	400
8	6.250	5.00	18.00	25.60	48.00	76.80	102.00	147.00	198.00	288.00	428.00	640
10	8.000	5.00	25.00	40.00	75.00	120.00	160.00	230.00	310.00	450.00	670.00	1000

Standard TrimFlow Direction: Flow to Open
ANSI Class: 150 through 600
Sizes: 1/2" through 10"Flow Characteristic: **LINEAR**

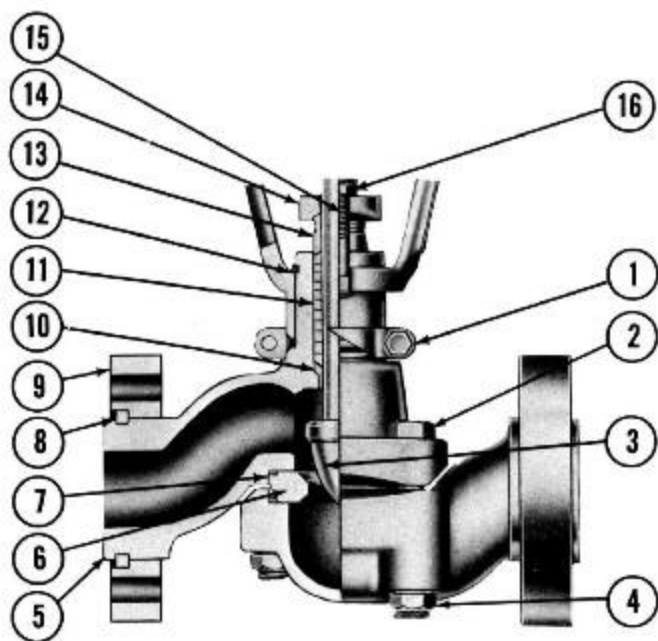
Percent (%) of Travel			10	20	30	40	50	60	70	80	90	100
F _L			0.90	0.88	0.87	0.84	0.82	0.79	0.78	0.77	0.75	0.75
Valve Size (Inches)	Orifice Diameter (Inches)	Travel (Inches)	Rated C _v									
1/2	.500	.75	.36	.72	1.04	1.40	1.80	2.24	2.64	3.08	3.52	4
3/4	.625	.75	.54	1.08	1.56	2.10	2.70	3.36	3.96	4.62	5.28	6
1	.812	.75	1.08	2.16	3.12	4.20	5.40	6.72	7.92	9.24	10.56	12
1 1/2	1.250	1.50	2.25	4.50	6.60	8.76	11.20	14.00	16.50	19.20	22.00	25
2	1.625	1.50	4.14	8.28	11.90	16.10	20.70	25.70	30.30	35.40	40.40	45
3	2.625	2.50	8.20	19.80	28.60	38.90	49.90	61.60	72.80	84.70	98.30	110
4	3.500	2.50	17.50	35.10	50.70	68.20	87.70	109.00	128.00	150.10	171.00	195
6 300 ANSI	4.625	2.50	36.00	72.00	104.00	140.00	180.00	224.00	264.00	308.00	352.00	400
6 300 ANSI	4.250	2.50	24.70	49.50	71.50	96.20	123.00	154.00	181.00	211.00	242.00	275
6 600 ANSI	4.500	3.00	36.00	72.00	104.00	140.00	180.00	224.00	264.00	308.00	352.00	400
8	6.250	5.00	57.60	115.00	166.00	224.00	288.00	358.00	422.00	492.00	563.00	640
10	8.000	5.00	90.00	180.00	260.00	350.00	450.00	560.00	680.00	770.00	880.00	1000



LO-DB Seat Ring



LO-DB Plug and Stem



Materials

Part No.	Temperatures	-320°F	-20°F	+400°F	+450°F	+750°F	+1000°F	+1200°F
	Description	Standard Materials						
1	Yoke Clamp	304 St. St.						
2	Valve Body Bolting	Alloy Steel ASTM A193 Gr B7						
		Stainless Steel ASTM A193 Gr B8						
		316 St. St. ASTM A479 TY						
3	Plug/Stem	Hardfaced 316 St. St. ASTM A479 TY (Std. on LO-DB®, opt. on others) ①						
4	Valve Body Nuts	Stainless Steel ASTM A194 Gr 8						
		Alloy Steel ASTM A194 Gr 2H						
		316 St. St. ASTM A351 Gr CF8M						
5	Body	Carbon Steel ASTM A216 Gr WC B						
6	Seat Ring	316 St. St. ASTM A479 TY						
		316 St. St./TFE						
		Hardfaced 316 St. St. ASTM A479 TY (optional)						
7	Seat Ring Gasket	Teflon						
		Non-asbestos Sheet						
		Inconel X-750 Metal O-ring						
8	Flange Half Rings	Carbon Steel						
		304 St. St. (optional)						
9	Separable End Flange	304 St. St. (optional)						
		Carbon Steel ASTM A515 Gr 70						
10	Stem Guide	Stellite						
		AL/BZ						
		25% GLT						
11	Packing	Teflon V-ring ②						
		Grafoil						
12	Yoke Half Rings	304 St. St.						
13	Packing Follower	316 St. St. ASTM A479 TY 316						
		Alloy 20 ASTM B473 (for Alloy 20 valves)						
14	Gland Flange	316 St. St. ASTM A351 Gr CF8M						
15	Packing Box Studs	304 St. St. ASTM A193 Gr B8						
16	Packing Box Stud Nuts	304 St. St. ASTM A194 Gr 8F						

① Hardfacing of stem is mandatory on LO-DB trim and services over 750°F

② No bonnet insulation allowed for teflon packings

Note: Extension bonnet is required for service temperature below -20°F and above +600°F

Grafoil packing necessary for services between 450°F to 600°F without extension

Bonnet Extension and Packing Arrangements



Plain extension



Double seal extension



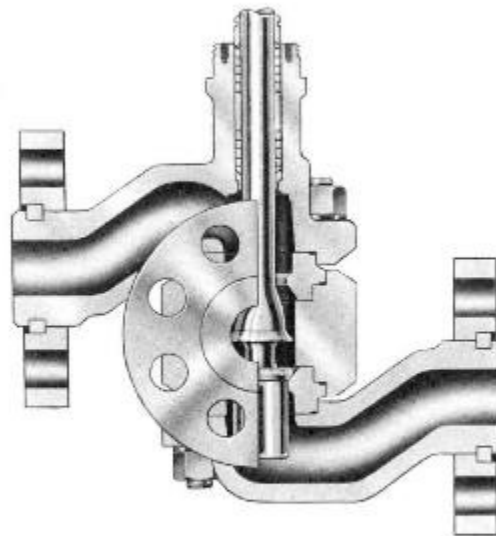
Bellows seal extension



Typical extension
for D actuators

3-Way Globe Valve Orientation

Orientation of the end connections of a 3-way valve is described with clock positions, when viewing the valve from above with the side of the yoke bearing the stroke indicator plate at 6 o'clock. For example, the 3-way globe, pictured here, has the body at 9 o'clock, the intermediate body at 6 o'clock and the adapter at 3 o'clock. This also applies to corner valves.



Allowable Pressure Drops (psi) - Manual Actuator

Flow to Close

Manually Actuated Valves

Metal Seat (Class VI) ①

Temperature: -320°F to +1200°F

Body Ratings: ANSI Class 150 through 600

Seat Leakage: per ANSI/FCI 70.2, Class IV

Valve Size (in.)	Travel (in.)	Rated C _v	Actuator Size (in.)	Metal Seat	Soft Seat
1/2	0.75	4	7	1500	1000
3/4	0.75	6	7	1500	1000
1	0.75	12	7	1500	1000
1 1/2	1.50	16	12	1500	1000
		25	12	1500	1000
2	1.50	46	12	1085	1000
		75	18	1500	1000
3	2.50	110	18	765	765
		195 ②	18	415	415
4	2.50	275	18 ③	650	650
			18	280	280
			18 ③	555	555
			18	235	235
6	2.50	400	18 ③	490	490
			18 ③	400	400
8	5.00	640	18 ③	260	260
10	5.00	1000	18 ③	155	155

① Soft seats are limited to 1000 psi pressure drop.
The preferred flow direction is flow to close.

② Body designed for 150 lb and 300 lb ratings, "C" Series yoke

③ 12" Yoke

④ 16" Yoke

Notes: LO-DB trim allowable pressure drop is equivalent to the allowable pressure drop for full area standard trim in each size.
The pressure drops shown are independent of ANSI pressure ratings.
When allowable pressure drops exceed ANSI ratings the ANSI ratings must govern.

Allowable Pressure Drops (psi) - Diaphragm Actuator

Air to Open/Air to Close

Diaphragm Actuated Globe and Angle Valves (87/88 Actuators)

Metal and Soft Seat

Temperature: -320°F to +1200°F

Body Ratings: ANSI Class 150 through 600

Seat Leakage: per ANSI/FCI 70.2, Class IV, Class VI

Valve Size (inches)	Travel (inches)	C _v	Act. Size (in.)	Flow to Open - Air to Close		F to O - A to O		F to C - A to O	
				3-15 Spring Air Supply Pressure		6-30	11-22	3-15	6-30
				20	35				
1/2	0.75	4	6	660	1440	920	1440	915	1440
3/4	0.75	6	6	330	1440	510	1395	585	1170
1	0.75	12	6	100	1440	210	755	345	675
1 1/2	1.50	16	10	230	1440	350	930	380	750
		25	10	95	1250	170	560	240	470
2	1.50	46	10	5	700	50	285	145	260
3	2.50	75	16	60	770	105	340	150	300
		110	16	---	425	30	170	85	165
4 ①	2.50	195	16	---	215	---	70	50	100

① 150 and 300 ANSI only

Notes: LO-DB trim allowable pressure drop is equivalent to the allowable pressure drop for full area standard trim in each valve size.

The pressure drops shown are independent of ANSI pressure ratings.

When allowable pressure drops exceed ANSI ratings the ANSI ratings must govern.

Allowable Pressure Drops (psi) - Cylinder Actuator

Air to Open/Air to Close

Cylinder Actuated Globe and Angle Valves
Metal and Soft Seat
Temperature: -320°F to +1200°F
Body Ratings: ANSI Class 150 through 600
Seat Leakage: per ANSI/FCI 70.2, Class IV, Class VI ③

Valve Size (inches)	Travel (inches)	C _v	Act. Size (in.)	Flow to Open - Air to Close 10 - 20 Spring Air Supply Pressure				F to C - A to O			F to O - A to O		
								10-20	15-30	25-50	10-20	15-30	25-50
				40	50	60	100	40	60	100	40	60	100
1/2	0.75	4	38	1440	1440	1440	1440	1440	1440	1440	1000	1440	1440
3/4	0.75	6	38	1440	1440	1440	1440	1440	1440	1440	600	1100	1440
1	0.75	12	38	950	1440	1440	1440	450	1100	1440	250	600	950
1 1/2	1.50	16	38	550	1000	1440	1440	250	900	1440	100	300	550
	1.50	25	38	300	600	900	1440	100	650	1440	50	150	300
2	1.50	46	38	150	300	500	1200	-----	300	1000	-----	50	150
	1.50	46	78	500	850	1200	1200	250	750	1440	150	300	500
3	2.50	75	78	250	550	750	1440	200	950	1440	50	150	250
	2.50	110	78	150	250	400	900	100	400	800	-----	50	150
4 ① (150 & 300)	2.50	195	78	-----	100	200	500	-----	150	400	-----	-----	-----
4 ② (600)	2.50	195	154	200	350	600	1200	250	600	1100	100	150	200
6 ① (150)	2.50	275	78	-----	75	125	325	-----	50	300	-----	-----	-----
6 ② (300)	2.50	400	78	-----	25	75	225	-----	-----	250	-----	-----	-----
6 ③ (300)	3.00	275	154	175	300	375	800	200	450	750	75	125	175
	3.00	400	154	125	200	275	575	150	350	550	50	75	125

- ① Body designed for Series "C" yoke
② Body designed for Series "D" bolted yoke
③ Soft seats limited to 1000 psi drop. Preferred flow direction is flow to close

Notes: L.O.D.B. trim allowable pressure drop is equivalent to the allowable pressure drop for full area standard trim in each valve size
The pressure drops shown are independent of ANSI pressure ratings
When allowable pressure drops exceed ANSI ratings the ANSI ratings must govern.

Allowable Pressure Drops (psi) - Domotor® Actuator

Air to Open/Air to Close ^②

Domotor Actuated Globe and Angle Valves

Metal and Soft Seats

Temperature: -320°F to +1200°F

Body Ratings: ANSI Class 150 through 600

Seat Leakage: per ANSI/FCI 70.2, Class IV, Class VI ^①

Valve Size (inches)	Travel (inches)	Rated C _v	Acuator Size	Flow to Open - Fail Open ^②			Flow to Close - Fail Closed ^②		
				Supply 40 psi Preload 30 psi	Supply 60 psi Preload 50 psi	Supply 90 psi Preload 60 psi	Supply 40 psi Preload 30 psi	Supply 60 psi Preload 30 psi	Supply 90 psi Preload 50 psi
1/2	0.75	4	A	1500	1500	1500	1025	1500	1500
			B	1500	1500	1500	1500	1500	1500
3/4	0.75	6	A	1150	1500	1500	550	1500	1500
			B	1500	1500	1500	1500	1500	1500
1	0.75	12	A	800	1500	1500	275	1500	1500
			B	1500	1500	1500	850	1500	1500
1 1/2	1.50	16	B	1150	1500	1500	600	1500	1500
			C	1500	1500	1500	1425	1500	1500
		25	B	700	1475	1500	350	1300	1500
			C	1500	1500	1500	825	1500	1500
2	1.50	46	B	375	850	1075	200	725	975
			C	1025	1175	1175	475	1500	1500
			C	625	1200	1500	350	1100	1500
3	2.50	75	D	1500	1500	1500	725	1500	1500
			C	325	700	875	175	600	800
		110	D	850	925	925	375	1150	1225
4 ^③	2.50	195	C	150	375	475	100	325	425
			D	450	500	500	200	625	650
4 ^④	2.50	195	D	450	850	1025	200	625	825
6 ^⑤	2.50	275	C	100	225	300	50	200	275
			D	300	325	325	125	400	450
		400	C	50	150	200	50	150	200
			D	200	225	225	100	300	300
6 ^⑤	3.00	275	D	300	550	675	150	425	575
		400	D	250	475	600	125	375	500
8	5.00	640	D	100	225	300	50	200	250
10	5.00	1000	D	50	125	175	50	100	150

^① Soft seats are limited to 1000 psi pressure drop. The preferred flow direction is flow to close.^② For flow to open/fail closed or flow to close/fail open actions, fail-safe volume tanks are required.^③ Body designed for 150 lb and 300 lb ratings, "C" Series yoke.^④ Body designed for 600 lb rating, "D" Series yoke.^⑤ Body designed for 300 lb and 600 lb ratings, "D" Series yoke.**Notes:** LO-DB® trim allowable pressure drop is equivalent to the allowable pressure drop for full area standard trim in each valve size.

The pressure drops shown are independent of ANSI pressure ratings.

When allowable pressure drops exceed ANSI ratings the ANSI ratings must govern.

Allowable Pressure Drops (psi)

Combining and Diverting Service

Globe and Angle 3-way Valves

Metal Seat

Temperature: -320°F to +1200°F

Body Ratings: ANSI Class 150 through 600

Seat Leakage: per ANSI/FCI 70.2, Class IV

Domotor® Actuator

Valve Size (inches)	Rated C _v	Travel (inches)	Actuator Size	Actuator Pressures		
				Supply 40 psi Preload 30 psi	Supply 80 psi Preload 40 psi	Supply 100 psi Preload 50 psi
1/2	4	0.75	A	640	1500	1500
			B	1430	1500	1500
3/4	6	0.75	A	500	1480	1500
			B	1150	1500	1500
1	10	0.75	A	355	1080	1440
			B	830	1500	1500
1 1/2	25	1.50	B	340	888	1160
			C	775	1500	1500
2	40	1.50	B	220	590	780
			C	520	1230	150
3	95	2.50	C	230	500	750
			D	540	900 ^①	-----
4	175	2.50	C	120	320	410
			D	300	535 ^②	-----
6	275	2.50	C	75	212	280
	320	2.50	C	45	140	190
	275	2.50	D	200	375 ^③	-----
	320	3.00	D	130	310	400
8	480	5.00	D	80	175	260
10	820	5.00	D	45	100	155

① 60 psi supply, 30 psi preload max. to prevent damage to valve

Notes: LO DB® trim allowable pressure drop is equivalent to the allowable pressure drop for full area standard trim in each valve size

The pressure drops shown are independent of ANSI pressure ratings

When allowable pressure drops exceed ANSI ratings the ANSI ratings must govern

Volume tanks required for fail safe action

Cylinder Actuator

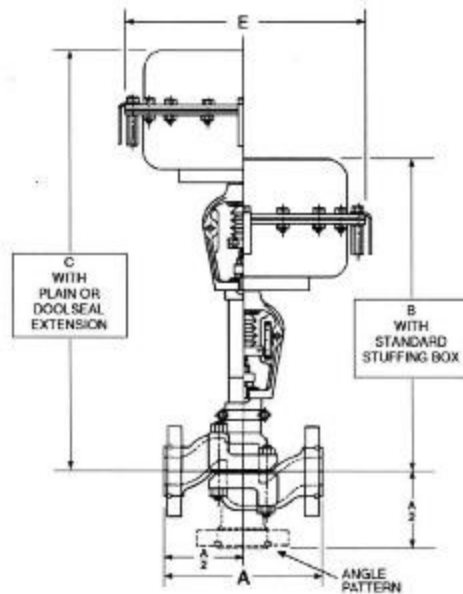
Valve Size (inches)	Travel (inches)	Rated C _v	Actuator Size	Supply 40 psi Spring Range 10-20	Supply 60 psi Spring Range 15-30	Supply 80 psi Spring Range 25-50
1/2	0.75	4	38	325	750	1500
3/4	0.75	6	38	225	550	1200
1	0.75	12	38	100	350	825
1 1/2	1.50	25	38	0	70	275
			78	175	400	825
2	1.50	46	38	0	10	150
			78	90	225	525
3	2.50	75	78	0	70	200
4 ^①	2.50	195	78	0	15	90

① Body designed for 150 lb and 300 lb ratings, "C" Series yoke

Notes: The pressure drops shown are independent of ANSI pressure ratings

When allowable pressure drops exceed ANSI ratings the ANSI ratings must govern

Dimensions (inches)



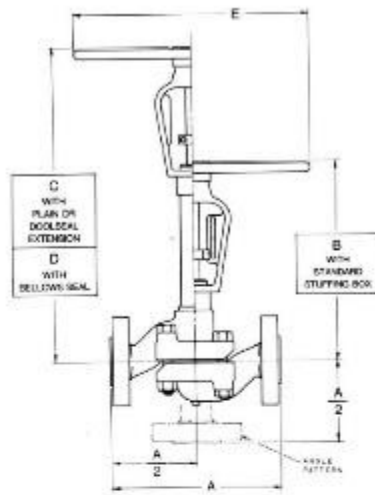
Diaphragm Actuator (87/88)

Valve Size (Inches)	ANSI Class 150, 300 & 600			
	A	B ①	C ①	E
1/2	6.75	13.7	17.7	11.9
3/4	6.75	13.7	17.7	11.9
1 ②	8.50	13.7	17.7	11.9
1 1/2 ②	9.50	19.5	25.5	14.7
2 ②	11.50	20.0	26.0	14.7
3 ②	14.00	28.0	37.0	18.8
4 ② ③	17.00	28.0	37.0	18.8

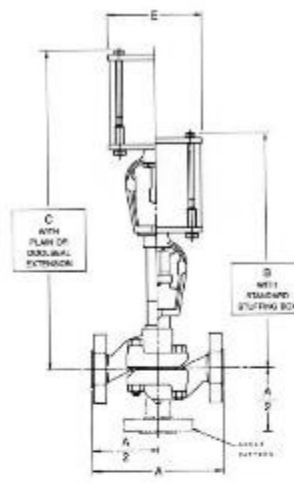
① Add 4 1/2" to B, C or D dimension for actuator removal clearance

② Dimension A is for separable flanges or weld ends only. See table on page 19 for integral flange dimension A (to ISA standards as noted)

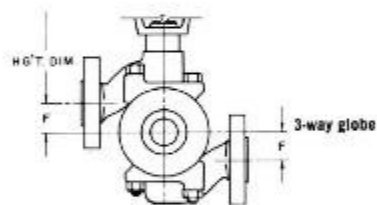
③ 150 and 300 ANSI only



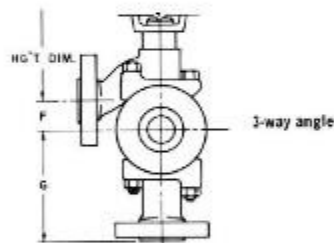
Manual Actuator



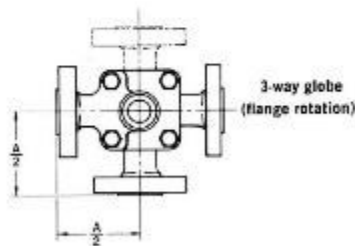
Cylinder Actuator



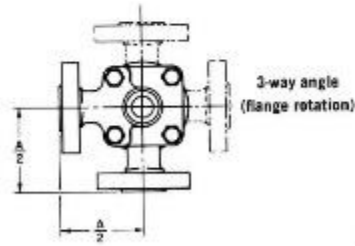
3-way globe



3-way angle



3-way globe
(flange rotation)



3-way angle
(flange rotation)

Add the following to B, C or D dimension when a side-mounted auxiliary handwheel is used with a Domotor® or cylinder
Series A Domotor® (7 1/4" O.D.) or A cylinder (4 1/4" O.D.) - 4 1/2"
Series B Domotor® (9 1/4" O.D.) or B cylinder (7" O.D.) - 5"
Series C Domotor® (13 1/4" O.D.) or C cylinder (9 1/4" O.D.) - 6"

Dimensions (inches)

Manual Actuator

Valve Size (in.)	ANSI Class 150								ANSI Class 300								ANSI Class 600							
	A	B ^①	C ^②	D ^③	E	F	G	H ^④	A	B ^①	C ^②	D ^③	E	F	G	H ^④	A	B ^①	C ^②	D ^③	E	F	G	H ^④
1/4	6.75	9.2	13.2	16.9	7.0	1.03	4.41	-----	6.75	9.2	13.2	16.9	7.0	1.03	4.41	-----	6.75	9.2	13.2	16.9	7.0	1.03	4.41	-----
1/2	6.75	9.2	13.2	16.9	7.0	1.03	4.41	-----	6.75	9.2	13.2	16.9	7.0	1.03	4.41	-----	6.75	9.2	13.2	16.9	7.0	1.03	4.41	-----
1 ^②	8.50	9.2	13.2	16.9	7.0	1.16	5.41	-----	8.50	9.2	13.2	16.9	7.0	1.16	5.41	-----	8.50	9.2	13.2	16.9	7.0	1.16	5.41	-----
1 1/2 ^②	9.50	11.9	17.9	24.6	12.0	1.66	6.41	-----	9.50	11.9	17.9	24.6	12.0	1.66	6.41	-----	9.50	11.9	17.9	24.6	12.0	1.66	6.41	-----
2 ^②	11.50	12.2	18.2	25.0	12.0	2.00	7.75	-----	11.50	12.2	18.2	25.0	12.0	2.00	7.75	-----	11.50	12.2	18.2	25.0	12.0	2.00	7.75	-----
3 ^②	14.00	17.8	27.4	40.7	18.0	3.00	10.00	-----	14.00	17.8	27.4	40.7	18.0	3.00	10.00	-----	14.00	17.8	27.4	40.7	18.0	3.00	10.00	-----
4 ^②	17.00	17.8	27.4	40.7	18.0	3.62	12.12	-----	17.00	17.8	27.4	40.7	18.0	3.62	12.12	-----	15.50 ^⑤	17.8	27.4	40.7	18.0	3.62	11.38	-----
4 ^②	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	15.50 ^⑤	23.7	35.6	-----	18.0	-----	-----	-----
6 ^②	24.00	20.0	29.5	42.9	18.0	4.25	16.25	7.7	22.00	21.5	31.0	-----	18.0	-----	-----	7.7	-----	-----	-----	-----	-----	-----	-----	-----
6 ^②	-----	-----	-----	-----	-----	-----	-----	-----	22.00	25.7	36.7	-----	18.0	5.25	16.38	7.7	28.00	33.1	43.8	-----	18.0	5.38	19.38	8.5
8	32.00	34.1	44.8	-----	18.0	5.69	21.69	9.5	32.00	34.1	44.8	-----	18.0	5.69	21.69	9.5	36.50	34.8	45.3	-----	18.0	-----	-----	10.0
10	37.00	35.3	46.1	-----	18.0	7.00	25.50	10.8	37.00	35.3	46.1	-----	18.0	7.00	25.50	10.8	-----	-----	-----	-----	-----	-----	-----	-----

① Add 4 1/2" to B, C or D dimension for actuator removal clearance

② Dimension A is for separable flanges or weld ends only. See table on page 19 for integral flange dimension A (to ISA standards as noted)

③ Bottom of valve extends below end flanges

④ Valve body with Series C actuators

⑤ Valve body with Series D actuators

Cylinder Actuator

Valve Size (in.)	ANSI Class 150							ANSI Class 300							ANSI Class 600						
	A	B ^①	C ^②	E	F	G	H ^③	A	B ^①	C ^②	E	F	G	H ^③	A	B ^①	C ^②	E	F	G	H ^③
1/4	6.75	16.5	20.5	7.60	1.03	4.41	-----	6.75	16.5	20.5	7.60	1.03	4.41	-----	6.75	16.5	20.5	7.60	1.03	4.41	-----
1/2	6.75	16.5	20.5	7.60	1.03	4.41	-----	6.75	16.5	20.5	7.60	1.03	4.41	-----	6.75	16.5	20.5	7.60	1.03	4.41	-----
1 ^②	8.50	16.5	20.5	7.60	1.16	5.41	-----	8.50	16.5	20.5	7.60	1.16	5.41	-----	8.50	16.5	20.5	7.60	1.16	5.41	-----
1 1/2 ^②	9.50	19.1	25.1	7.60	1.66	6.41	-----	9.50	19.1	25.1	7.60	1.66	6.41	-----	9.50	19.1	25.1	7.60	1.66	6.41	-----
2 ^②	11.50	19.6	25.6	7.60	2.00	7.75	-----	11.50	19.6	25.6	7.60	2.00	7.75	-----	11.50	19.6	25.6	7.60	2.00	7.75	-----
3 ^②	14.00	28.8	37.8	10.50	3.00	10.00	-----	14.00	28.8	37.8	10.50	3.00	10.00	-----	14.00	28.8	37.8	10.50	3.00	10.00	-----
4 ^②	17.00	28.8	37.8	10.50	3.62	12.12	-----	17.00	28.8	37.8	10.50	3.62	12.12	-----	15.50	28.8	37.8	10.50	3.62	11.38	-----
4 1/2 ^②	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	15.50	37.6	48.3	14.75	-----	-----	-----
6 ^②	24.00	40.6	50.1	10.50	4.25	16.25	7.7	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----
6 1/2 ^②	24.00	49.4	60.1	14.75	4.25	16.25	7.7	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----

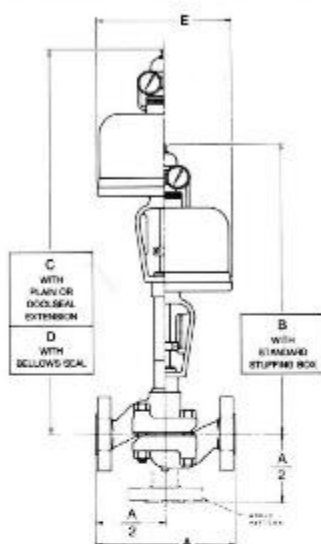
① Add 4 1/2" to B or C dimension for actuator removal clearance

② Dimension A is for separable flanges or weld ends only. See table on page 19 for integral flange dimension A (to ISA standards as noted)

③ Bottom of valve extends below end flanges

④ Valve body with 154 sq. in. actuator

Dimensions (inches)



Domotor® Actuator

Domotor® actuator

Valve Size (in.)	ANSI Class 150								ANSI Class 300								ANSI Class 600							
	A	B ⁽¹⁾	C ⁽²⁾	D ⁽³⁾	E	F	G	H ⁽⁴⁾	A	B ⁽¹⁾	C ⁽²⁾	D ⁽³⁾	E	F	G	H ⁽⁴⁾	A	B ⁽¹⁾	C ⁽²⁾	D ⁽³⁾	E	F	G	H ⁽⁴⁾
1/8	6.75	20.3	24.3	28.0	7.62	1.03	4.41	—	6.75	20.3	24.3	28.0	7.62	1.03	4.41	—	6.75	20.3	24.3	28.0	7.62	1.03	4.41	—
1/4	6.75	20.3	24.3	28.0	7.62	1.03	4.41	—	6.75	20.3	24.3	28.0	7.62	1.03	4.41	—	6.75	20.3	24.3	28.0	7.62	1.03	4.41	—
1/2	8.50	20.3	24.3	28.0	7.62	1.16	5.41	—	8.50	20.3	24.3	28.0	7.62	1.16	5.41	—	8.50	20.3	24.3	28.0	7.62	1.16	5.41	—
1 1/2	9.50	23.6	29.6	36.4	9.25	1.66	6.41	—	9.50	23.6	29.6	36.4	9.25	1.66	6.41	—	9.50	23.6	29.6	36.4	9.25	1.66	6.41	—
2	11.50	24.0	30.0	36.7	9.25	2.00	7.75	—	11.50	24.0	30.0	36.7	9.25	2.00	7.75	—	11.50	24.0	30.0	36.7	9.25	2.00	7.75	—
3	14.00	31.3	40.9	54.3	13.25	3.00	10.00	—	14.00	31.3	40.9	54.3	13.25	3.00	10.00	—	14.00	31.3	40.9	54.3	13.25	3.00	10.00	—
4	17.00	31.3	40.9	54.3	13.25	3.62	12.12	—	17.00	31.3	40.9	54.3	13.25	3.62	12.12	—	15.50 ⁽⁵⁾	31.3	40.9	54.3	13.25	3.62	11.38	—
6	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	15.50 ⁽⁵⁾	44.0	54.9	—	18.00	—	—	—
6 1/2	24.00	33.6	43.1	56.5	13.25	4.25	16.25	7.7	22.00	35.0	44.5	—	13.25	5.25	16.38	7.7	—	—	—	—	—	—	—	—
8	—	—	—	—	—	—	—	—	22.00	46.0	57.0	—	18.00	5.25	16.38	7.7	28.00	51.1	61.8	—	18.00	5.38	16.38	8.5
10	32.00	52.1	62.8	—	18.00	5.69	21.69	9.5	32.00	52.1	62.8	—	18.00	5.69	21.69	9.5	36.50	52.6	63.3	—	18.00	—	—	10.0
12	37.00	53.3	64.1	—	18.00	7.00	25.50	10.8	37.00	53.3	64.1	—	18.00	7.00	25.50	10.8	—	—	—	—	—	—	—	—

⁽¹⁾ Add 4 1/2" to B, C or D dimension for actuator removal clearance

⁽²⁾ Dimension A is for separable flanges or weld ends only. See table on page 19 for integral flange dimension A (to ISA standards as noted)

⁽³⁾ Valve size 6" & larger are integral flange ends

⁽⁴⁾ Bottom of valve extends below end flanges

⁽⁵⁾ Valve body with Series C actuators

⁽⁶⁾ Valve body with Series D actuators

See page 16 for definition of dimensions F and G

Dimensions - Integral Flanged (inches)

Dimension A (face to face) for valves with integral flanges not covered above
(Conforms to ISA standard for 1" to 4" valves)

Valve Size (Inches)	End Connection Type	ANSI Class 150	ANSI Class 300	ANSI Class 600
1	L & S Tongue	7.75	8.25	8.25
	L & S Groove	7.63	8.13	8.13
	Ring Joint	7.75	8.25	8.25
	Raised & Flat Face	7.25	7.75	8.25
1½	L & S Tongue	9.25	9.75	9.88
	L & S Groove	9.13	9.63	9.75
	Ring Joint	9.25	9.75	9.88
	Raised & Flat Face	8.75	9.25	9.88
2	L & S Tongue	10.50	11.00	11.25
	L & S Groove	10.38	10.88	11.13
	Ring Joint	10.50	11.13	11.38
	Raised & Flat Face	10.00	10.50	11.25
3	L & S Tongue	12.25	13.00	13.25
	L & S Groove	12.13	12.88	13.13
	Ring Joint	12.25	13.13	13.38
	Raised & Flat Face	11.75	12.50	13.25
4	L & S Tongue	14.38	15.00	15.50
	L & S Groove	14.25	14.88	15.38
	Ring Joint	14.38	15.13	15.63
	Raised & Flat Face	13.88	14.50	15.50

Approximate Shipping Weights (lbs)

Valve Size (Inches)	ANSI Class	With Diaphragm Actuator	With Manual Actuator	With Cylinder Actuator	With Motor Actuator	Extra for Bonnet Extension
½	600	35	18	24	30	3
¾	600	36	19	25	31	3
1	600	41	24	30	36	3
1½	600	75	45	48	56	5
2	600	100	57	60	68	5
3	600	225	122	126	136	12
4	300	285	176	180	190	12
4	600	----	415	573	522	65
6	150	----	303	307	317	12
6	300	----	403	561	510	85
6	600	----	767	925	874	130
8	300	----	662	820	769	130
8	600	----	1081	1239	1188	130
10	300	----	1144	1302	1251	130

Accessories and Options

Auxiliary Handwheels

Handwheel Sizes A, B, C

Oversize Actuators

Standard	to	Oversize
A		B
B		C
C		D

Model 6000 Electropneumatic Transducer
(See Specification Data CS6600)
Input Range 4-20 mA
Output Range 3-15 psi

Internal Regulator
Integral Universal Mounting Bracket

8005A/8006A Electropneumatic Transducer
(See Specification Data CS6600)
Input Signals 10-50 mA, 104 ohms
4-20 mA, 173 ohms
Output Signals (Direct or Reverse)
Model 8005A: 3-15 psi
Model 8006A: 3-15, 6-30, 0-20, or 0-35 psi

IPEX 9000 Electropneumatic Transducer
(See Specification Data CS9000)
Input Range 4-20 mA
Split range up to 3 times
Output (Direct or Reverse)
3-15 psi, adjustable to 0-20 psi

Moore 750P Positioner
3-15 psi Instrument Signal

Refer to specific actuator and accessory specification literature for complete information.

Microswitches
EXAR, EXHAR, EXDAR, OPAR, OPHAR

496 Rotary Switches
496-2 (2 switches) Limit Switch
496-3 Position Transmitter
(See Specification Data CS7000)

80-4 or 80-40 Airset
(See Specification Data CY7800)
77-6 or 77-60 Lockup Valve
(See Specification Data CY7700)
2" Gauge 0-30 psi

For Solenoid Valves Consult Price List

2700 Controllers
(See Specification Data CW6000)

Fail-safe Volume Tanks
w/ 77-8/77-80 Trip Valve
Super Response
Moore 61H Volume Booster

Additional Options Available

Other Body Materials
Other Flange Facings
U.O.P. Trim
N.A.C.E. Compliance
Non-Destructive Examination
Doolseal Double Packing
Bellows Seal Bonnets

Facilities: Brazil, Canada, France, Germany, Italy, Japan, Mexico,
Netherlands, Singapore, Spain, United Kingdom, United States

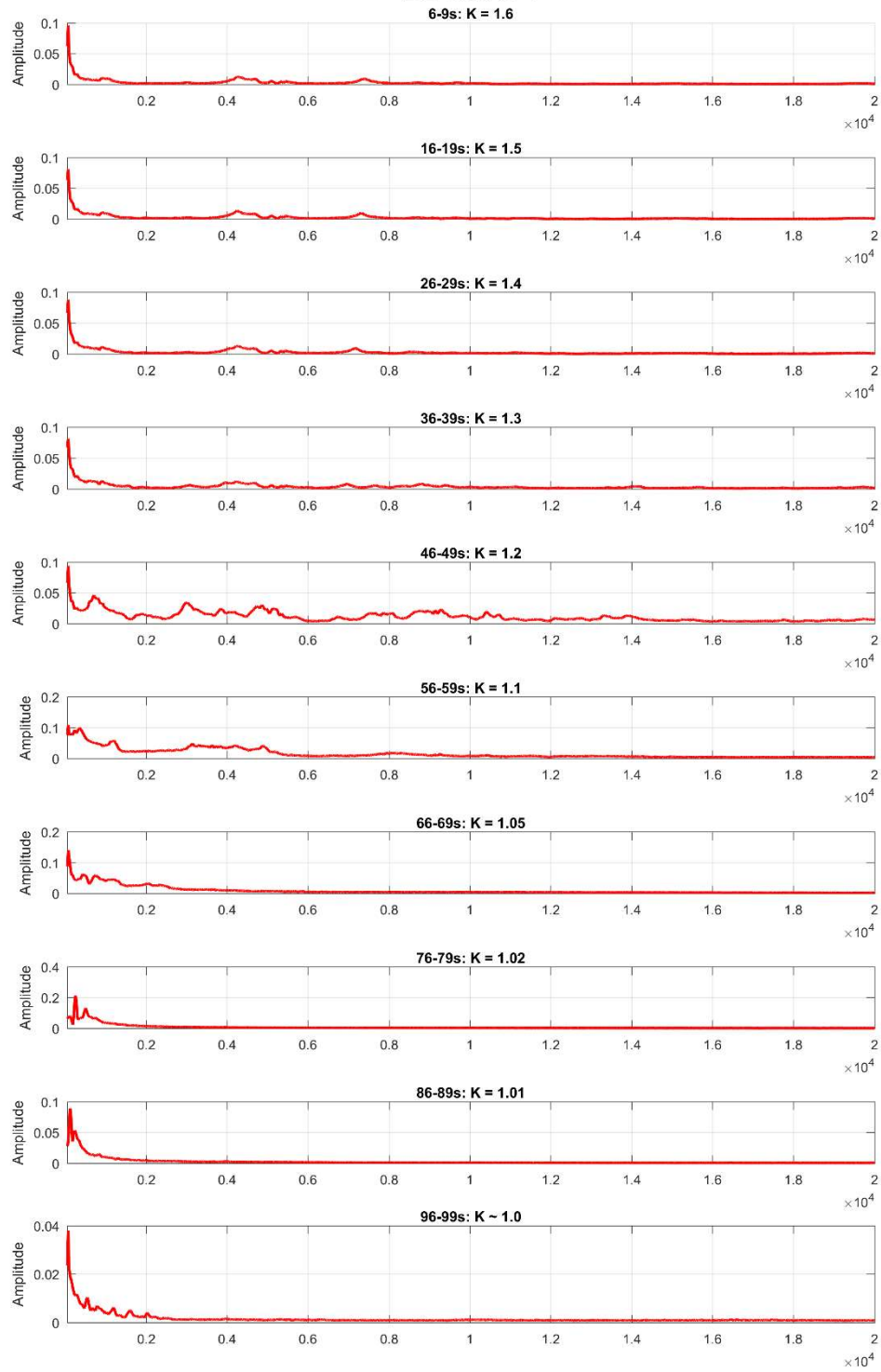


Signature Press 10/97/4M

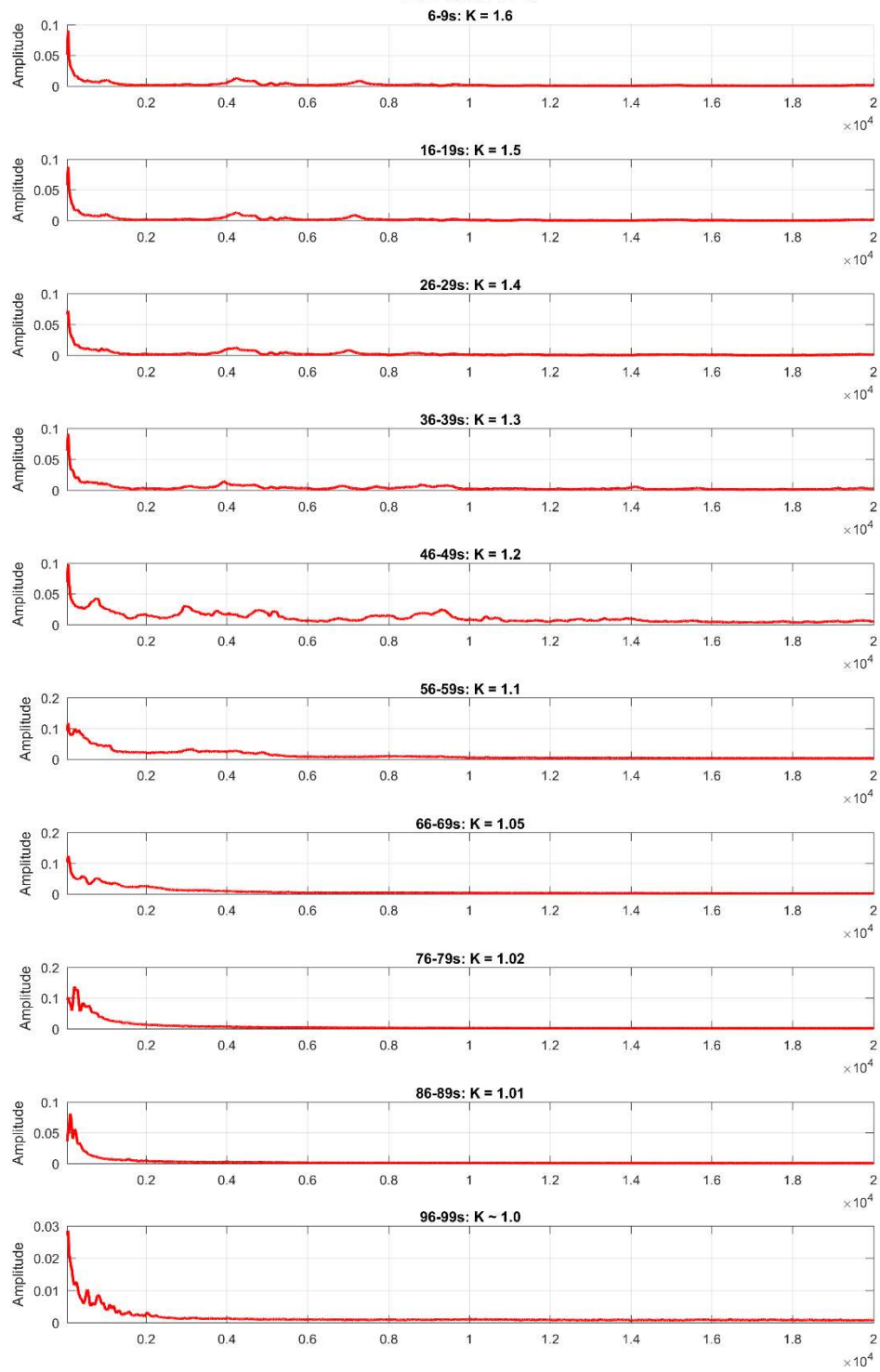
Masoneilan North American Operations
Dresser Valve and Controls Division
Marketing Services
15112 Morales Road
P.O. Box 60078 (77205-0078)
Houston, Texas 77032
Tel: (281) 871-6500 Fax: (281) 871-6569

Appendix E: Block 2 High Frequency Charts

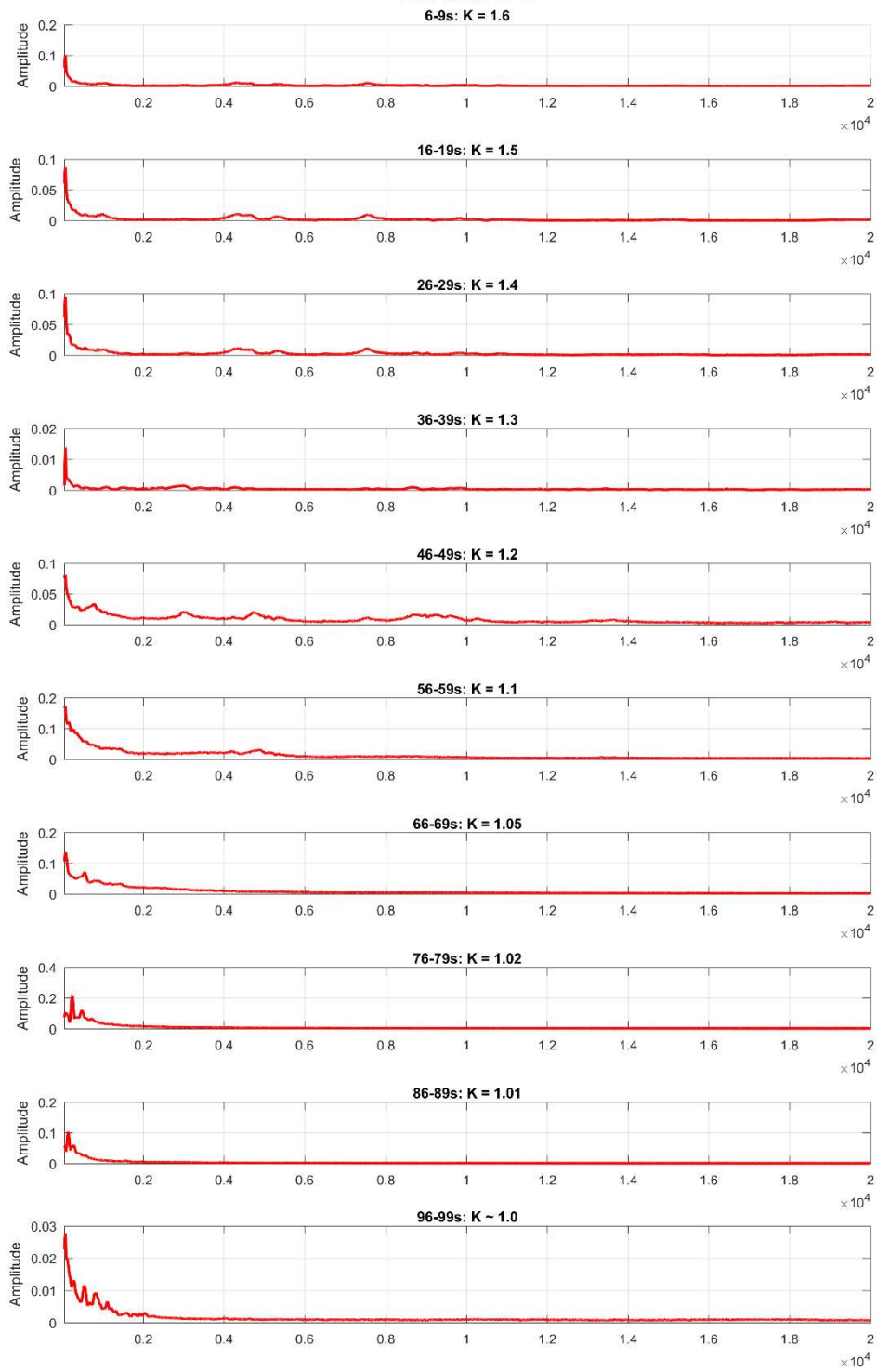
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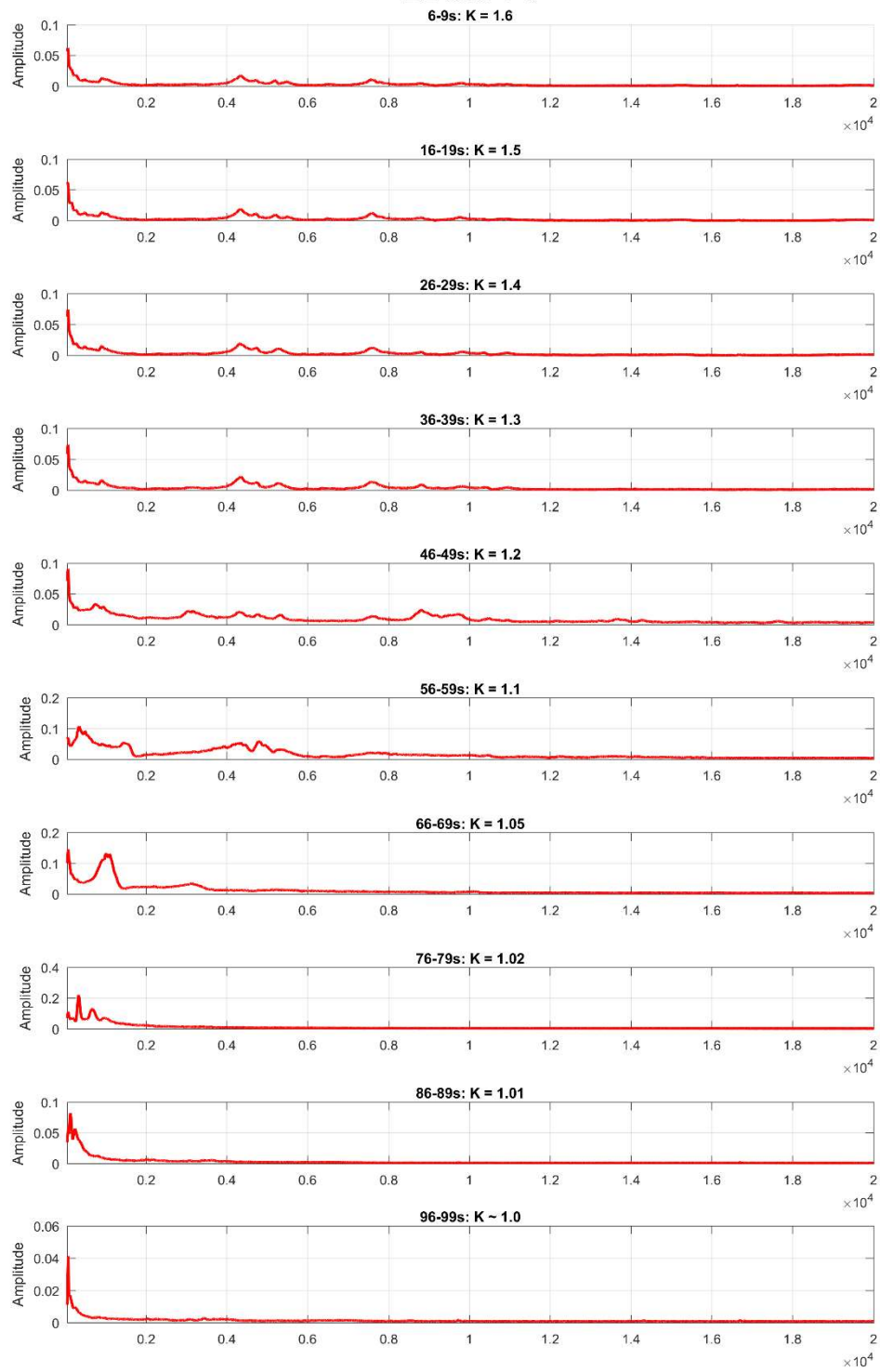
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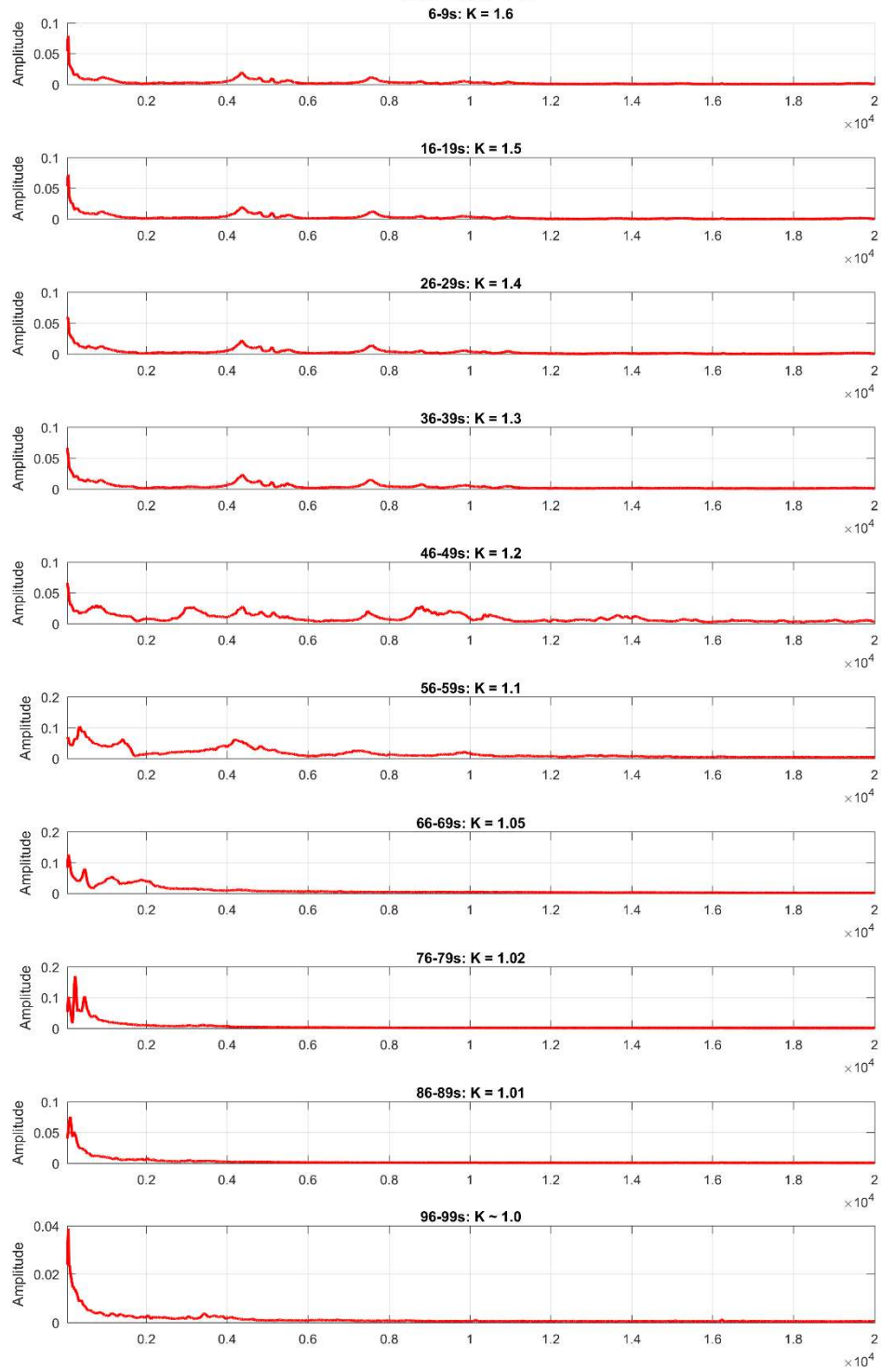
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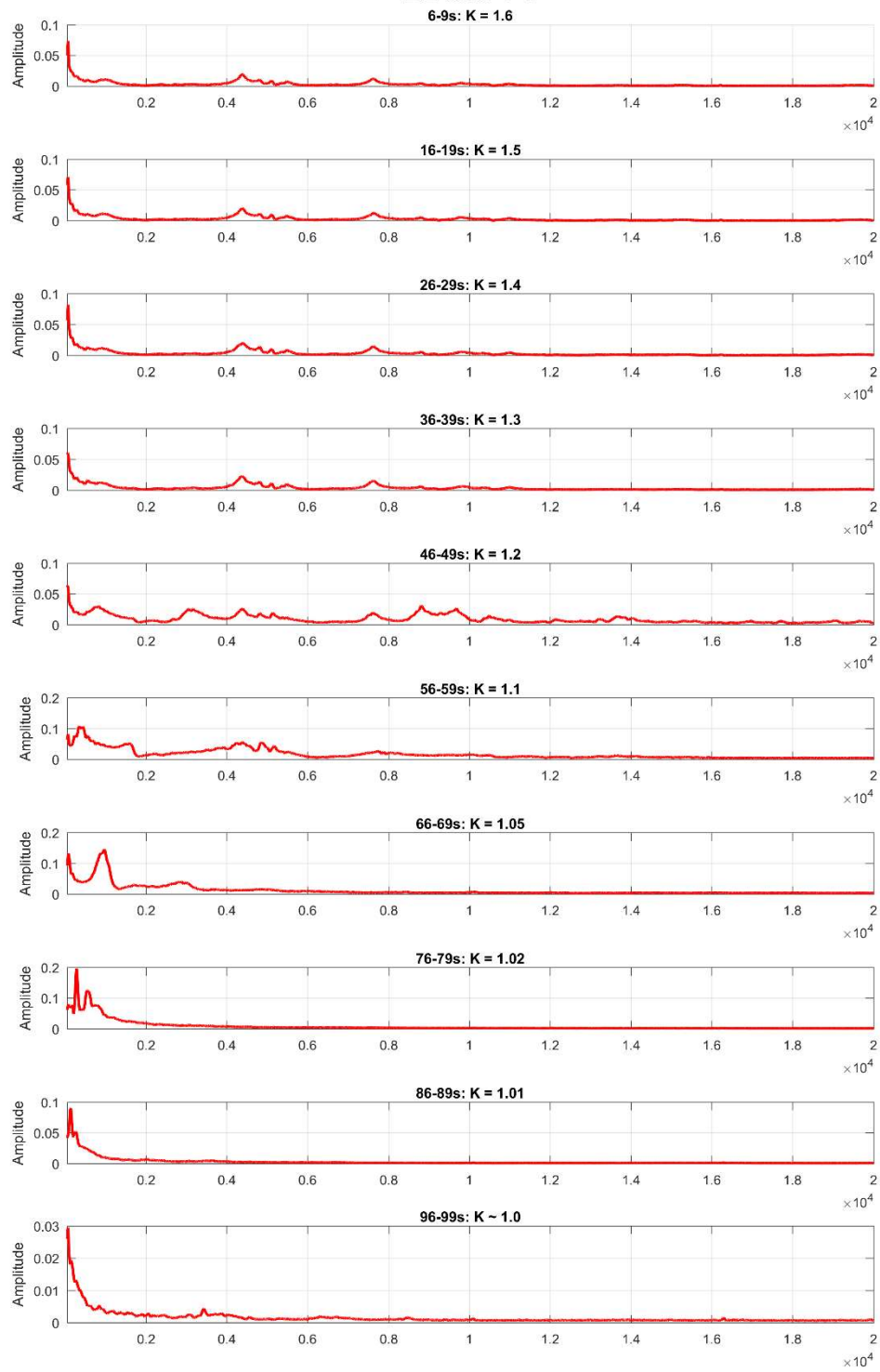
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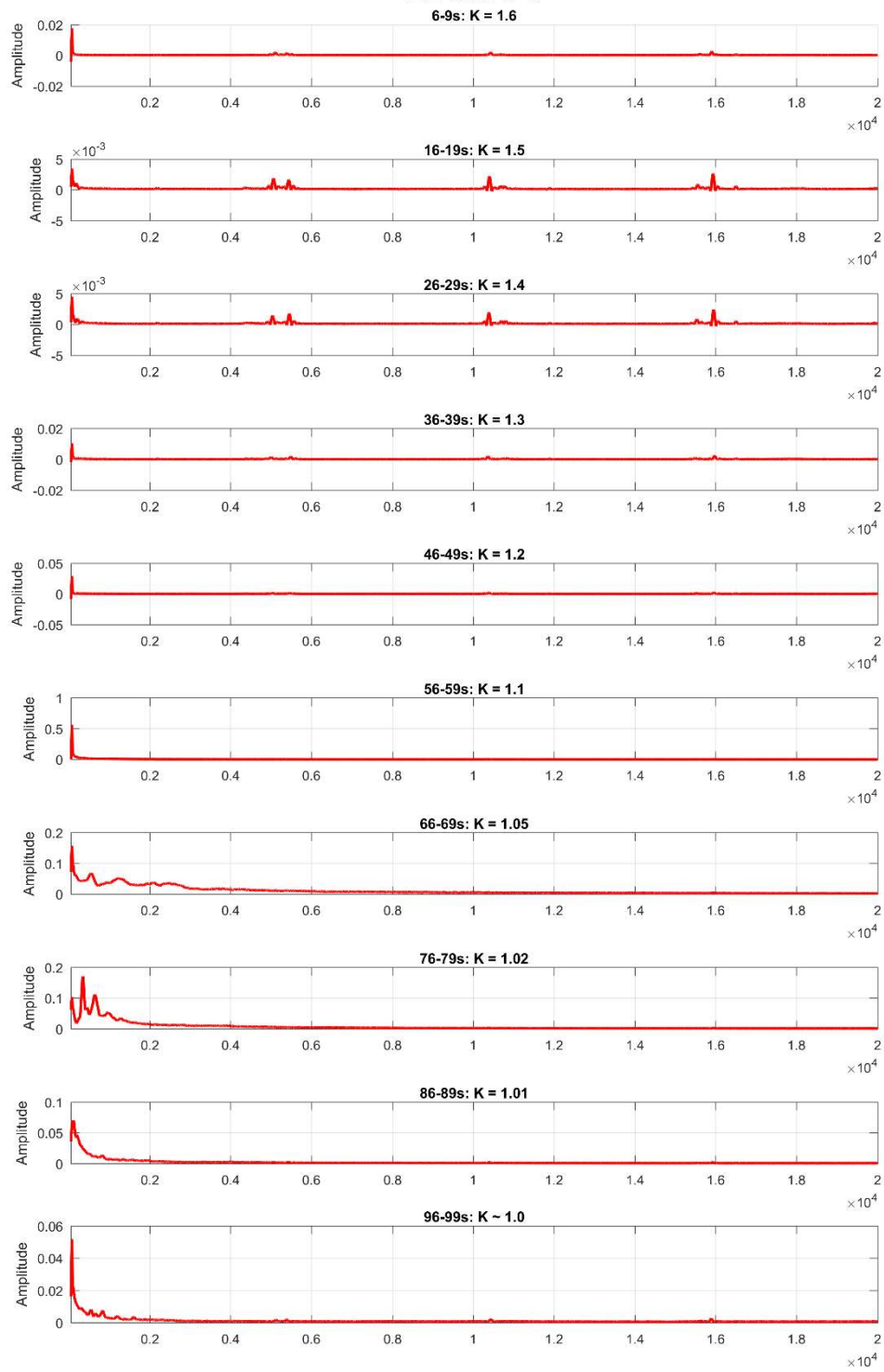
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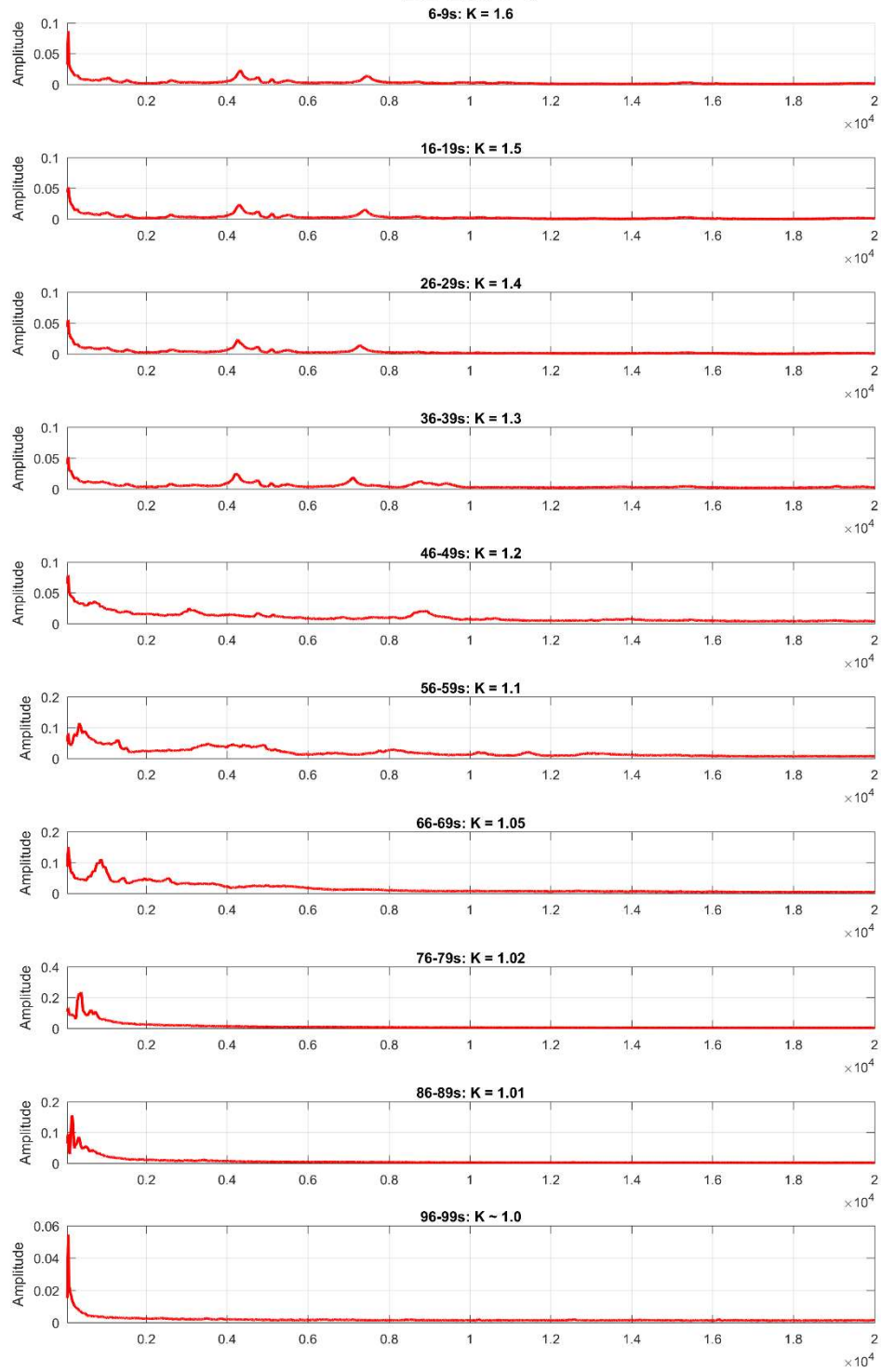
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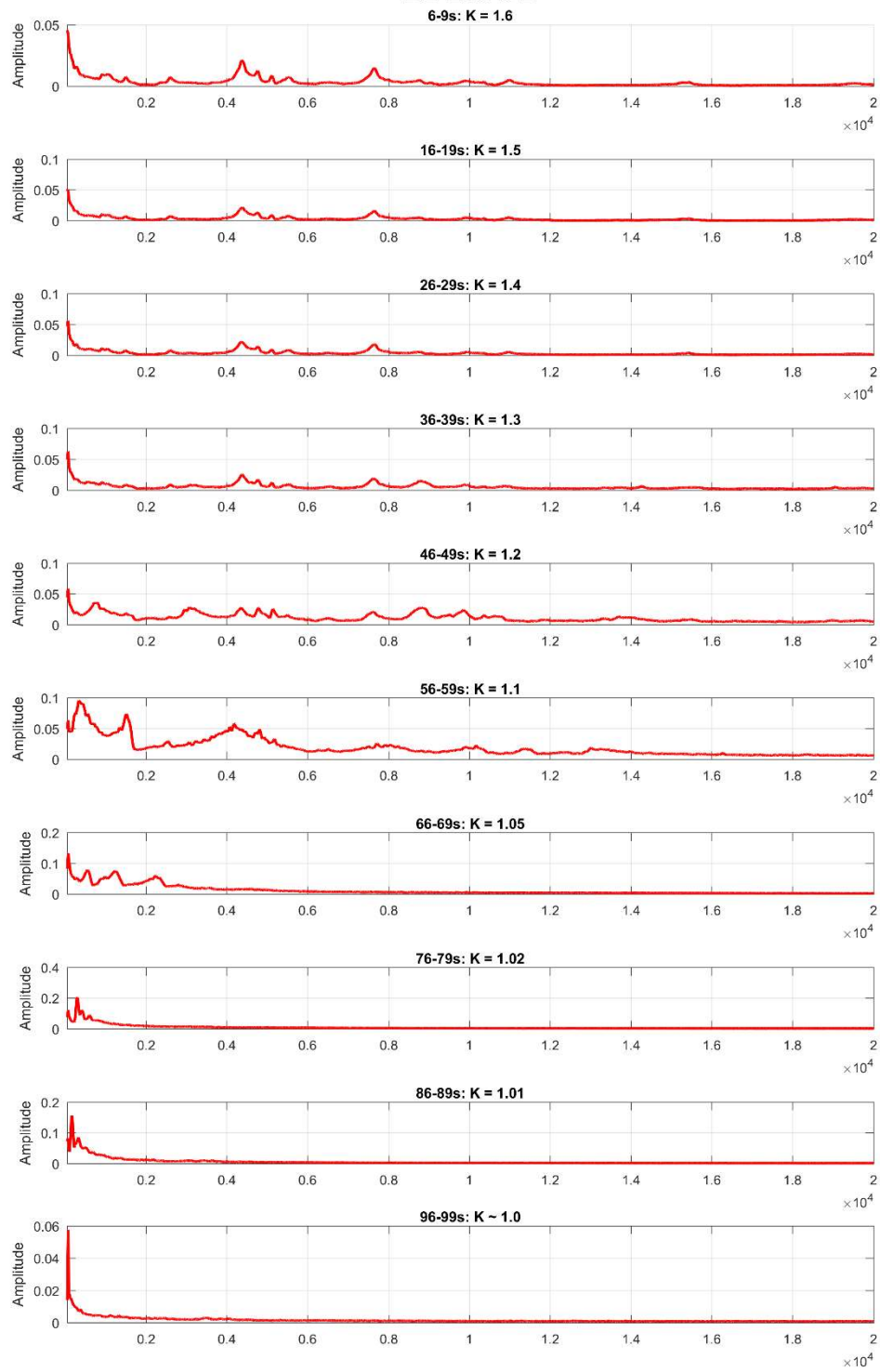
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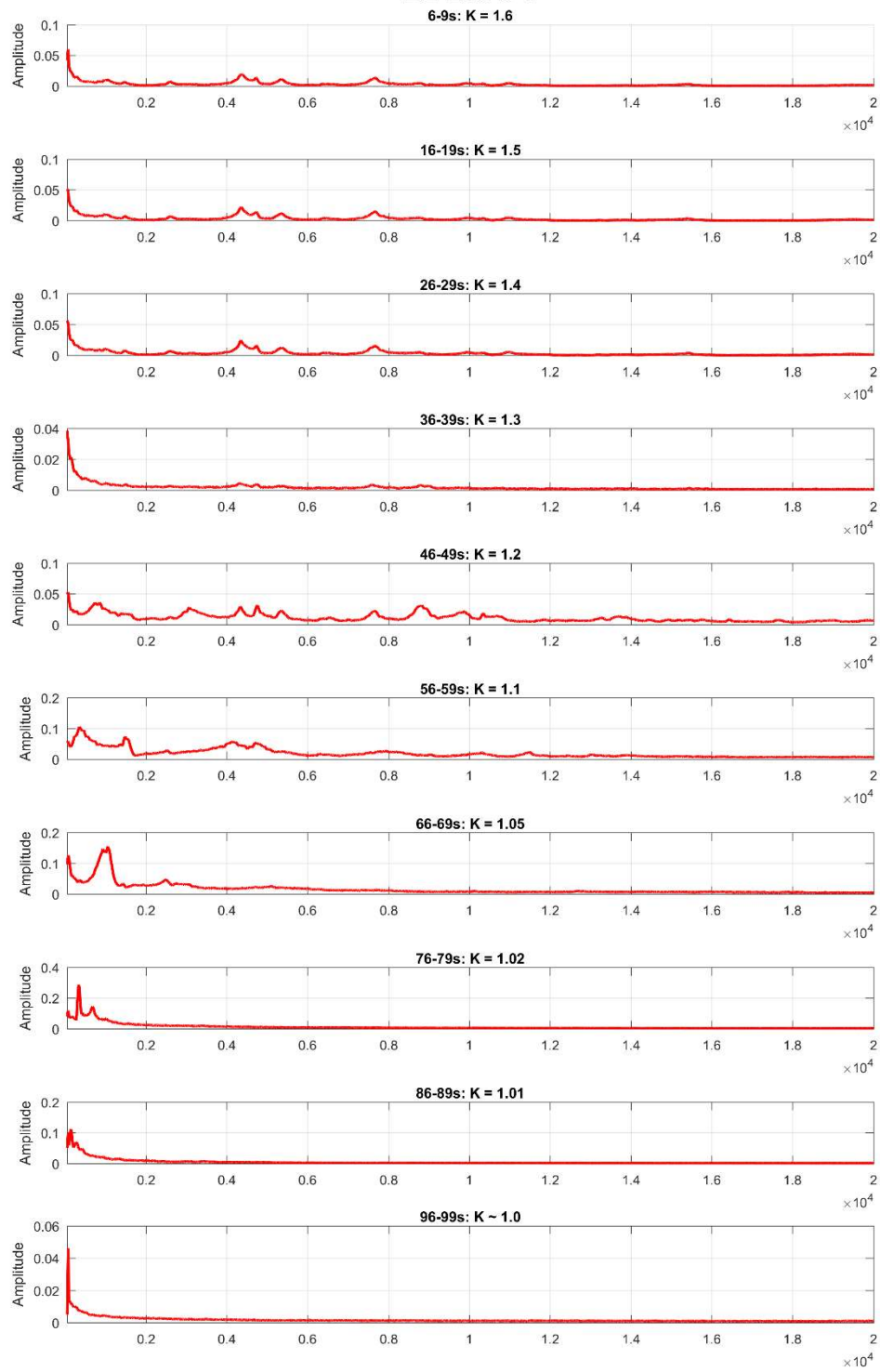
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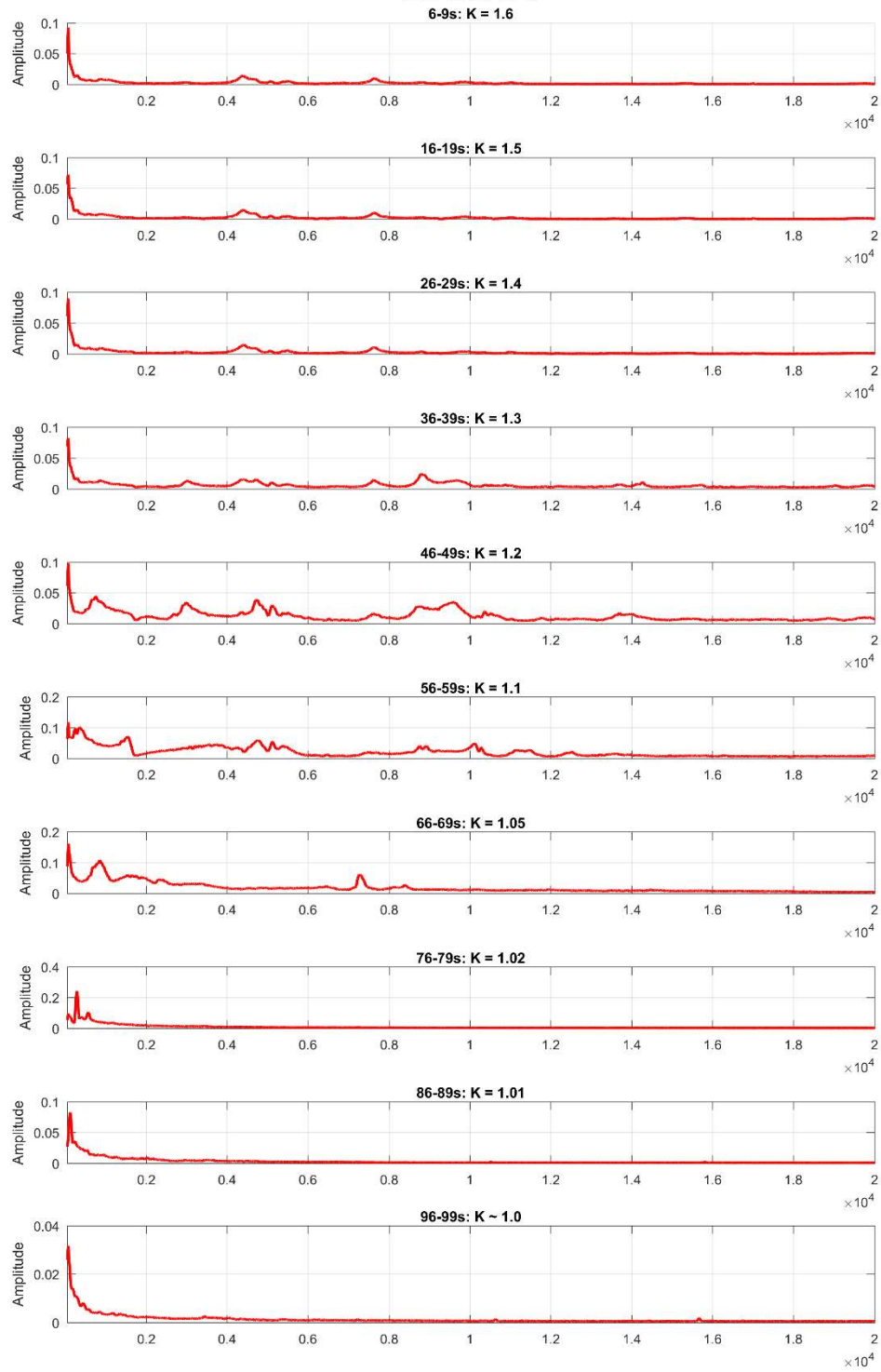
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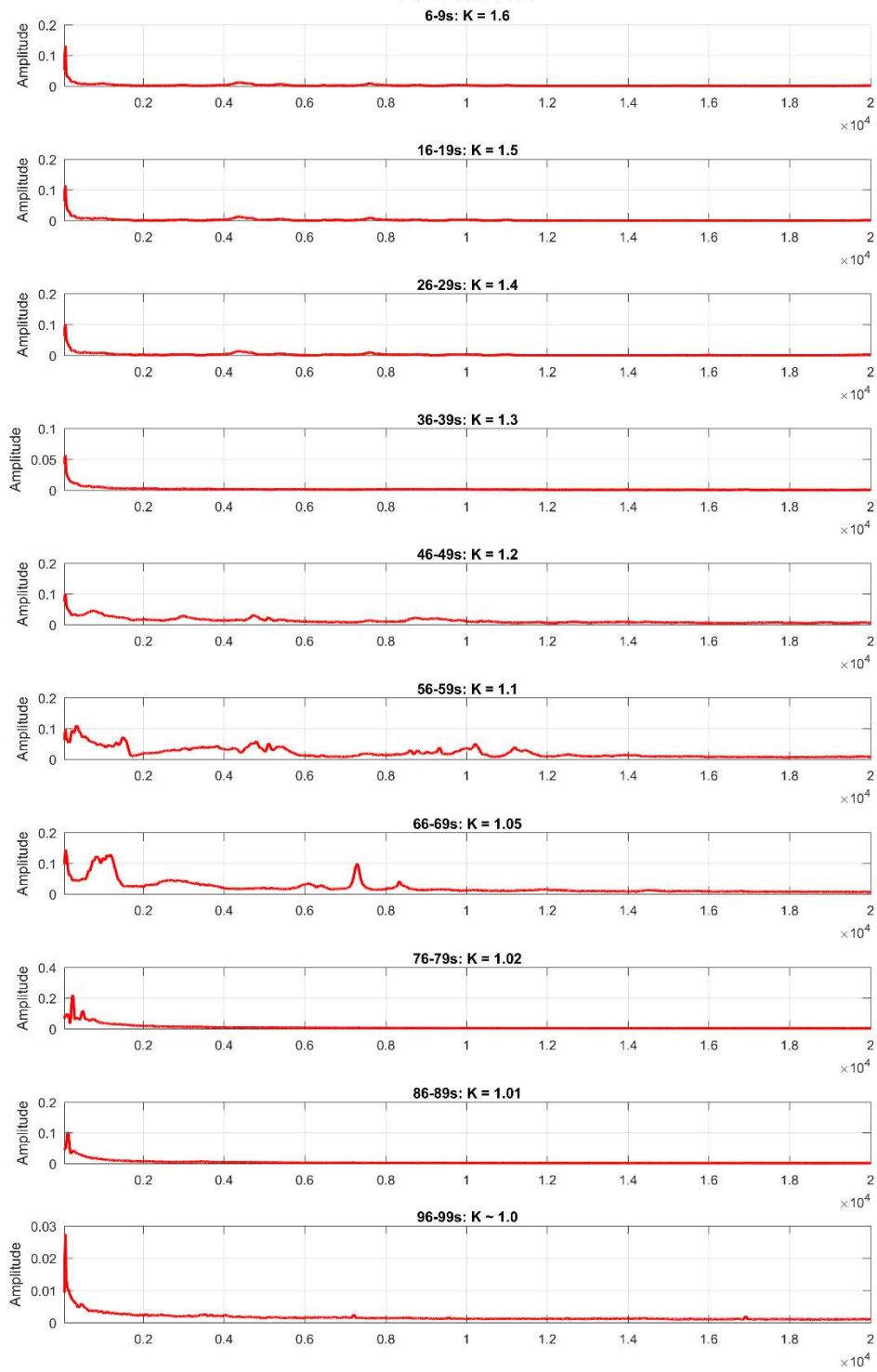
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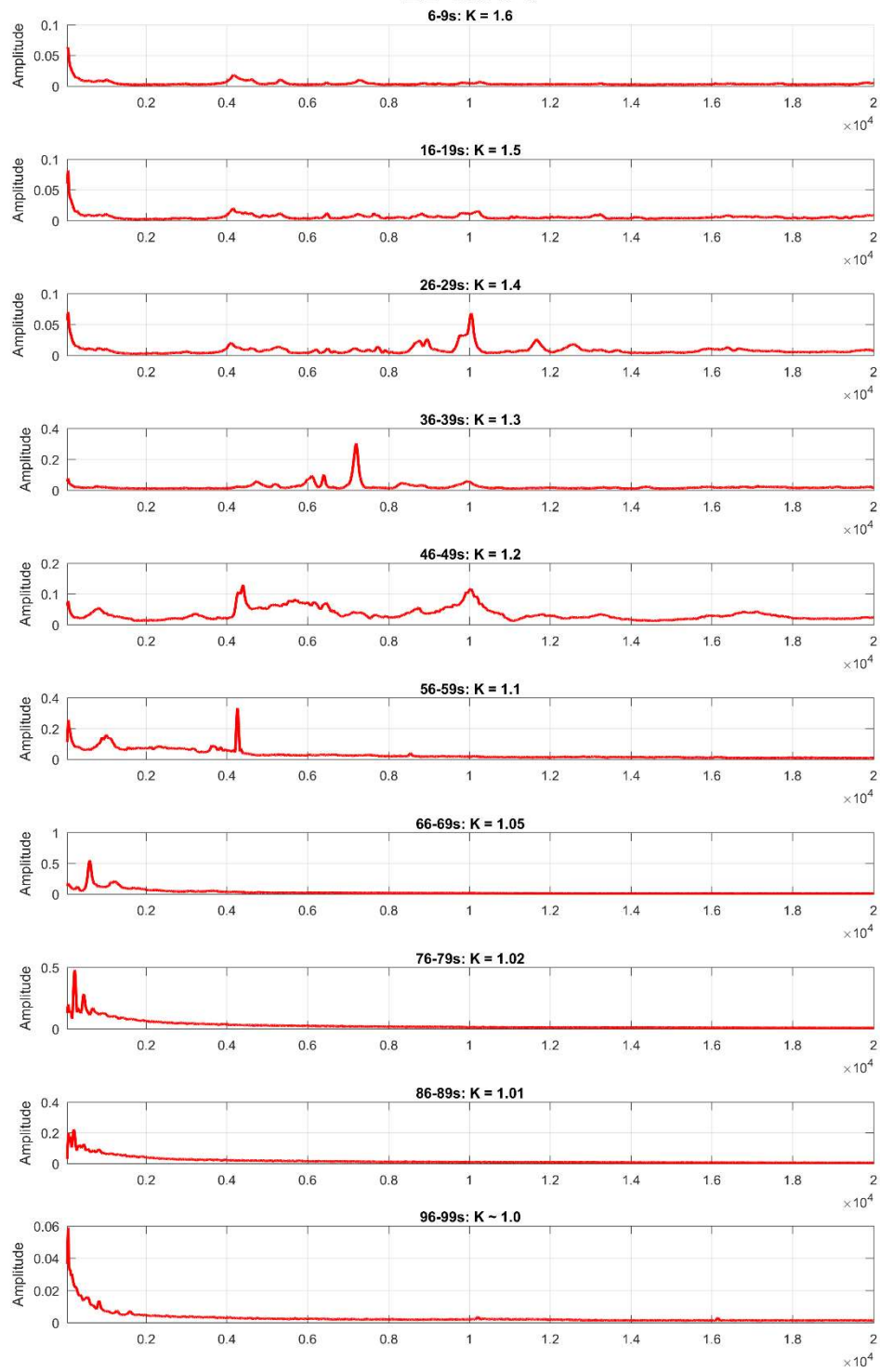
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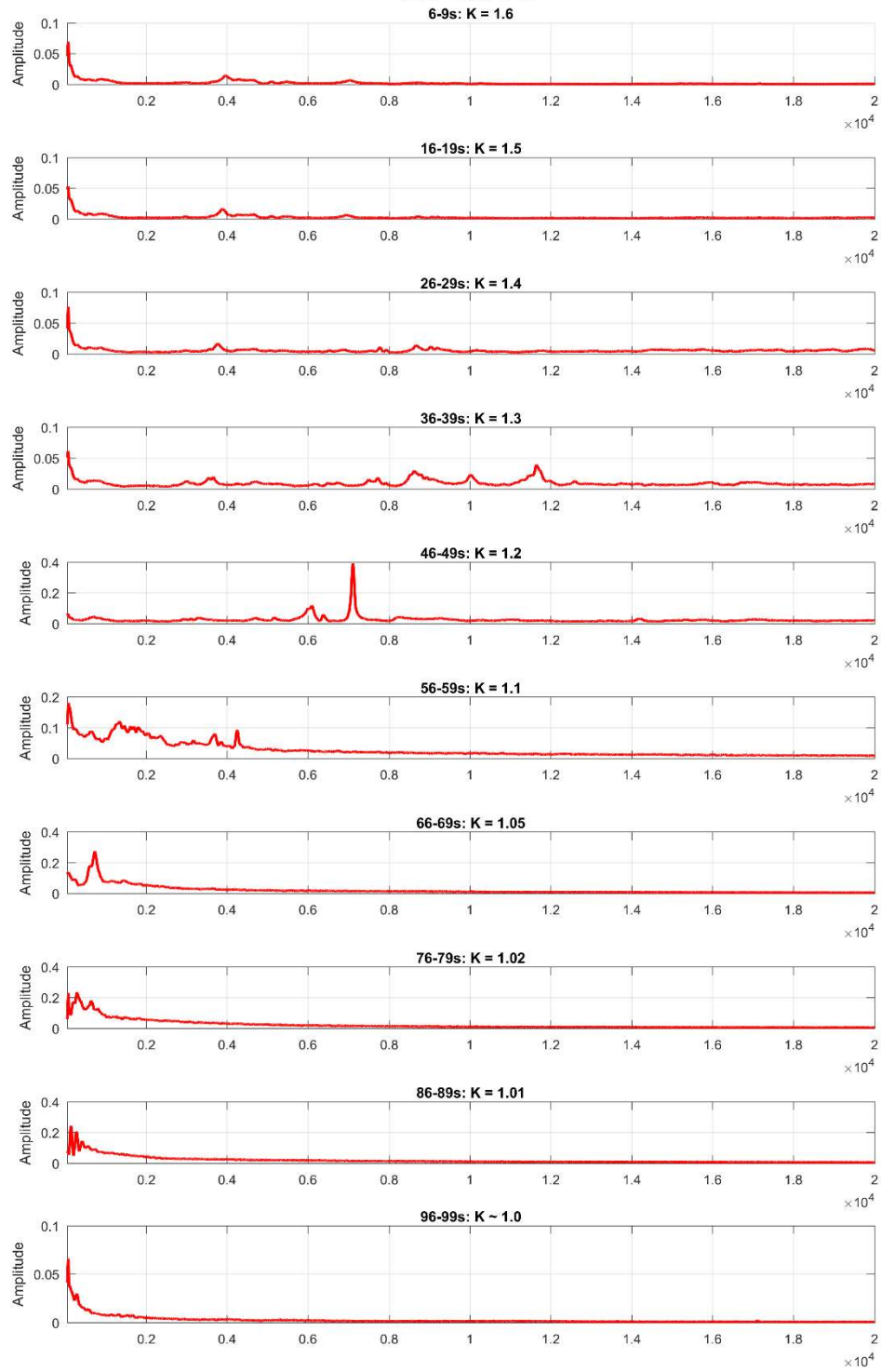
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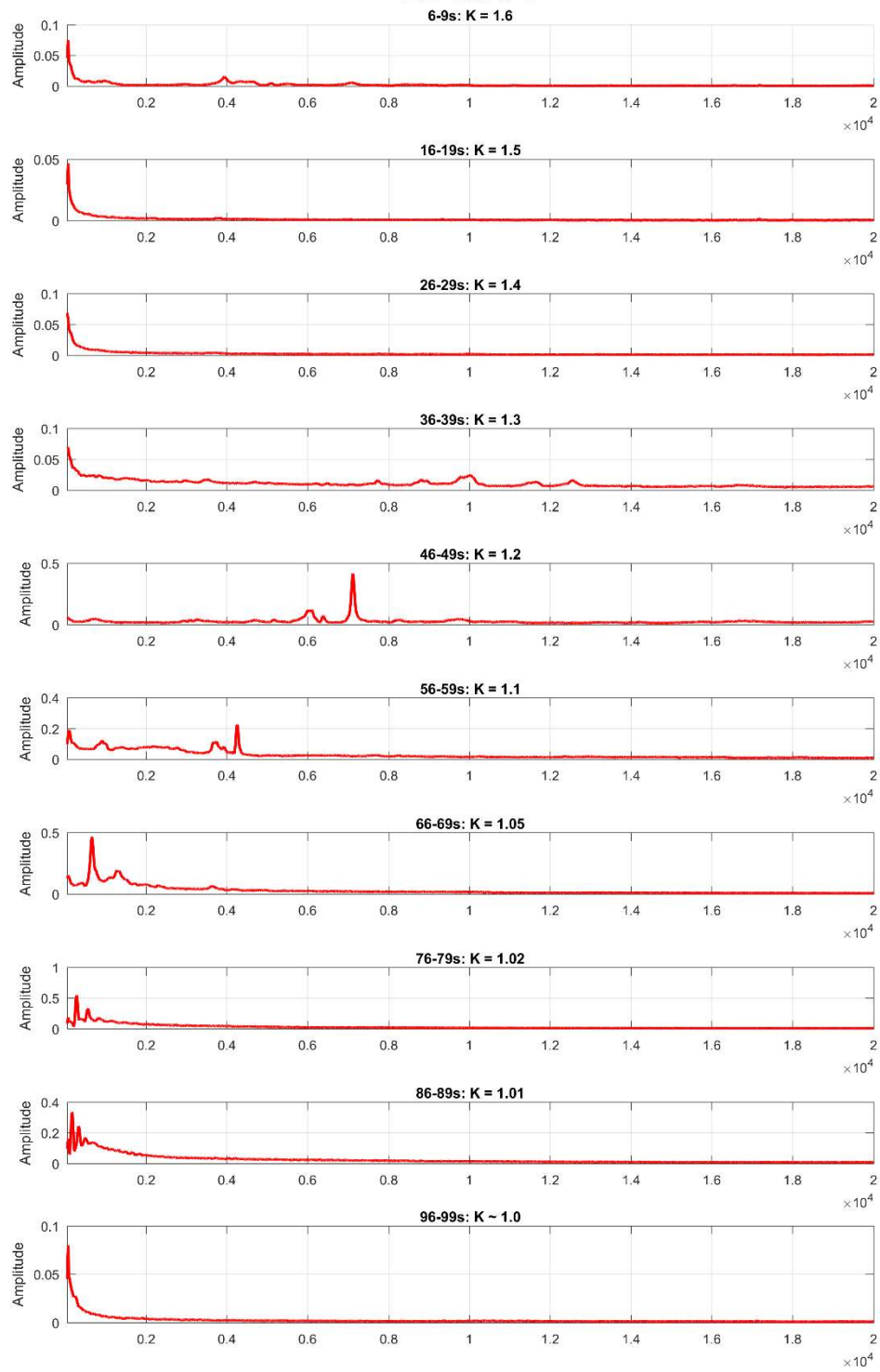
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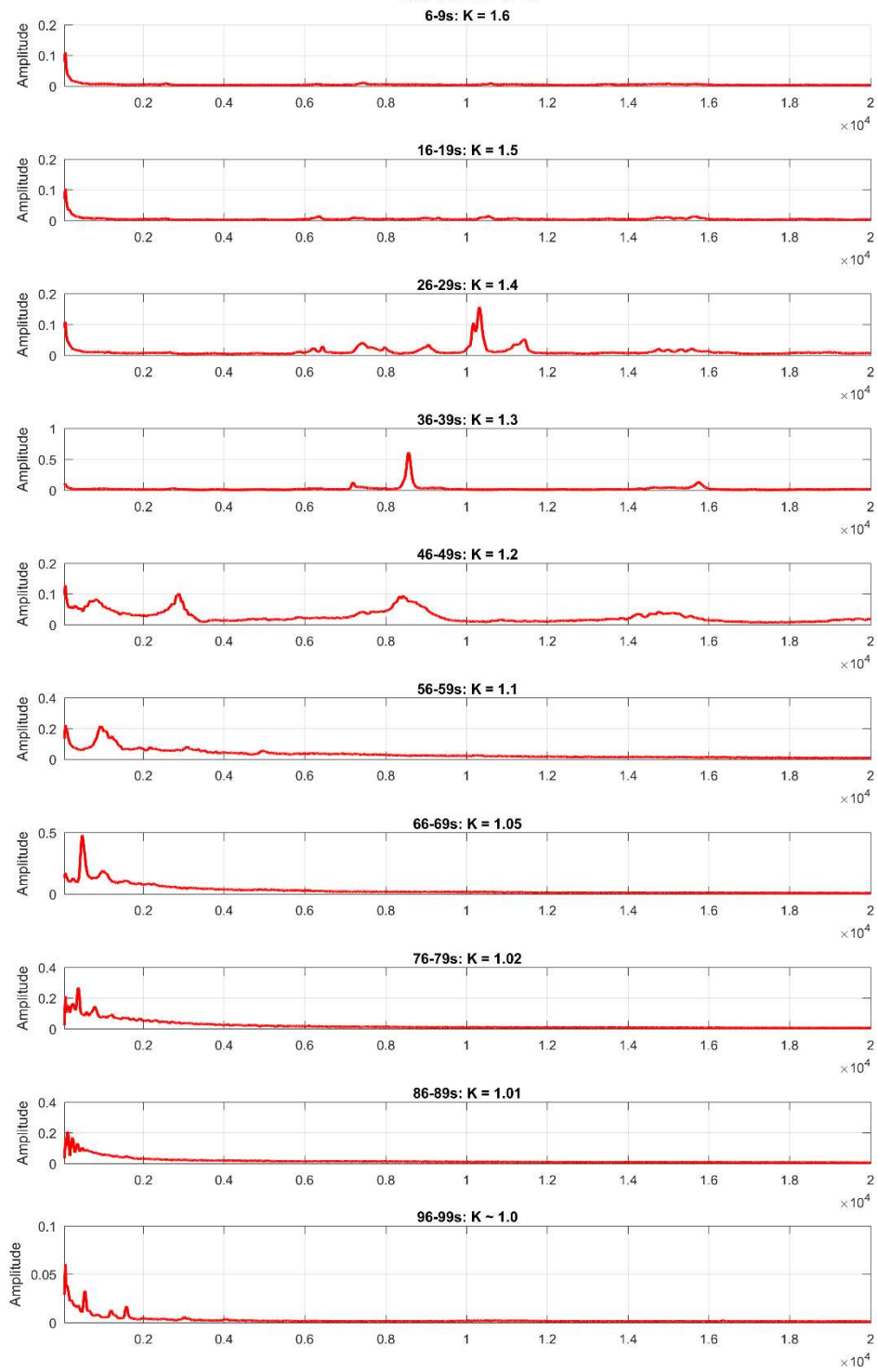


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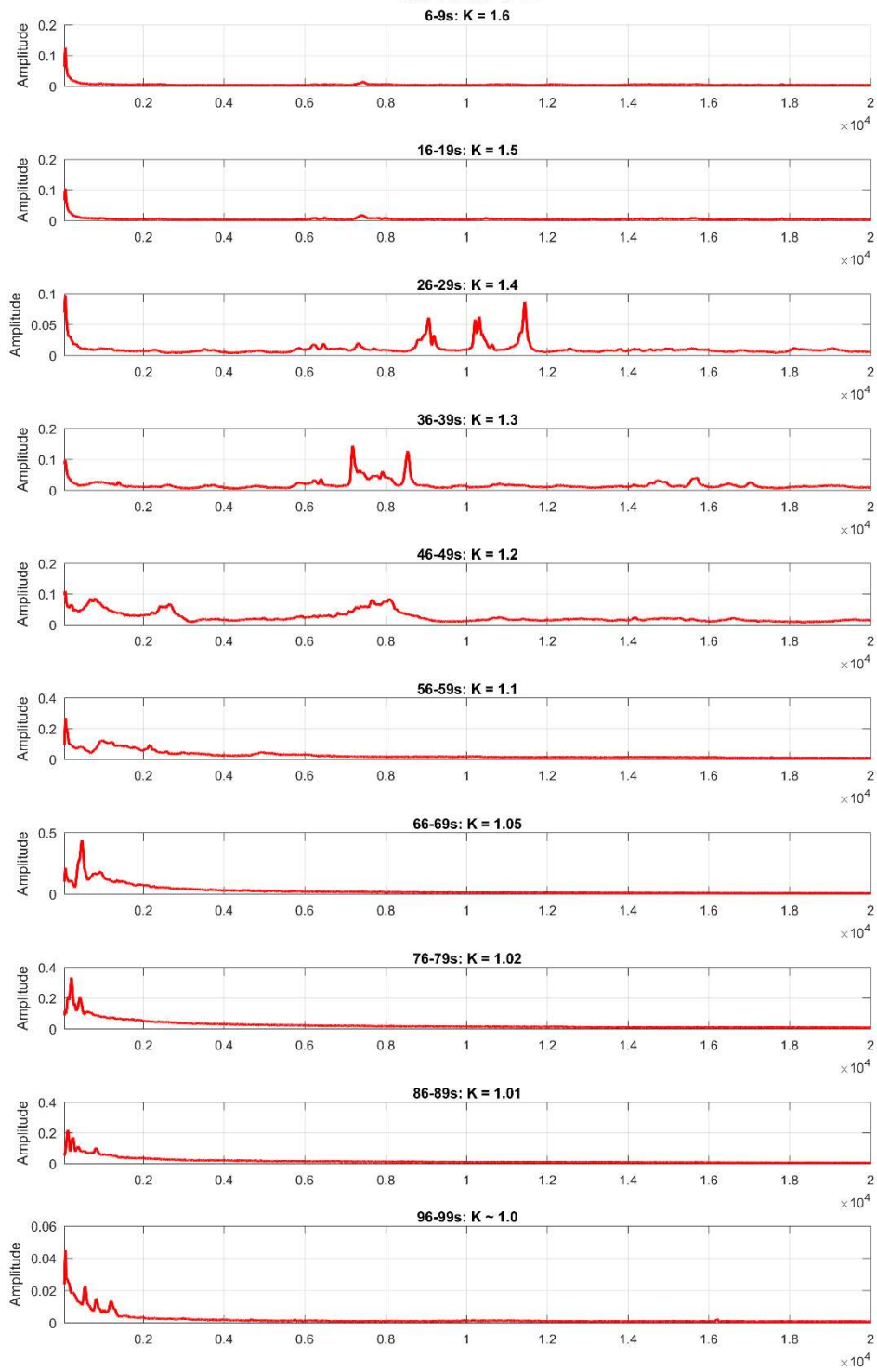


Appendix F: Block 3 High Frequency Charts

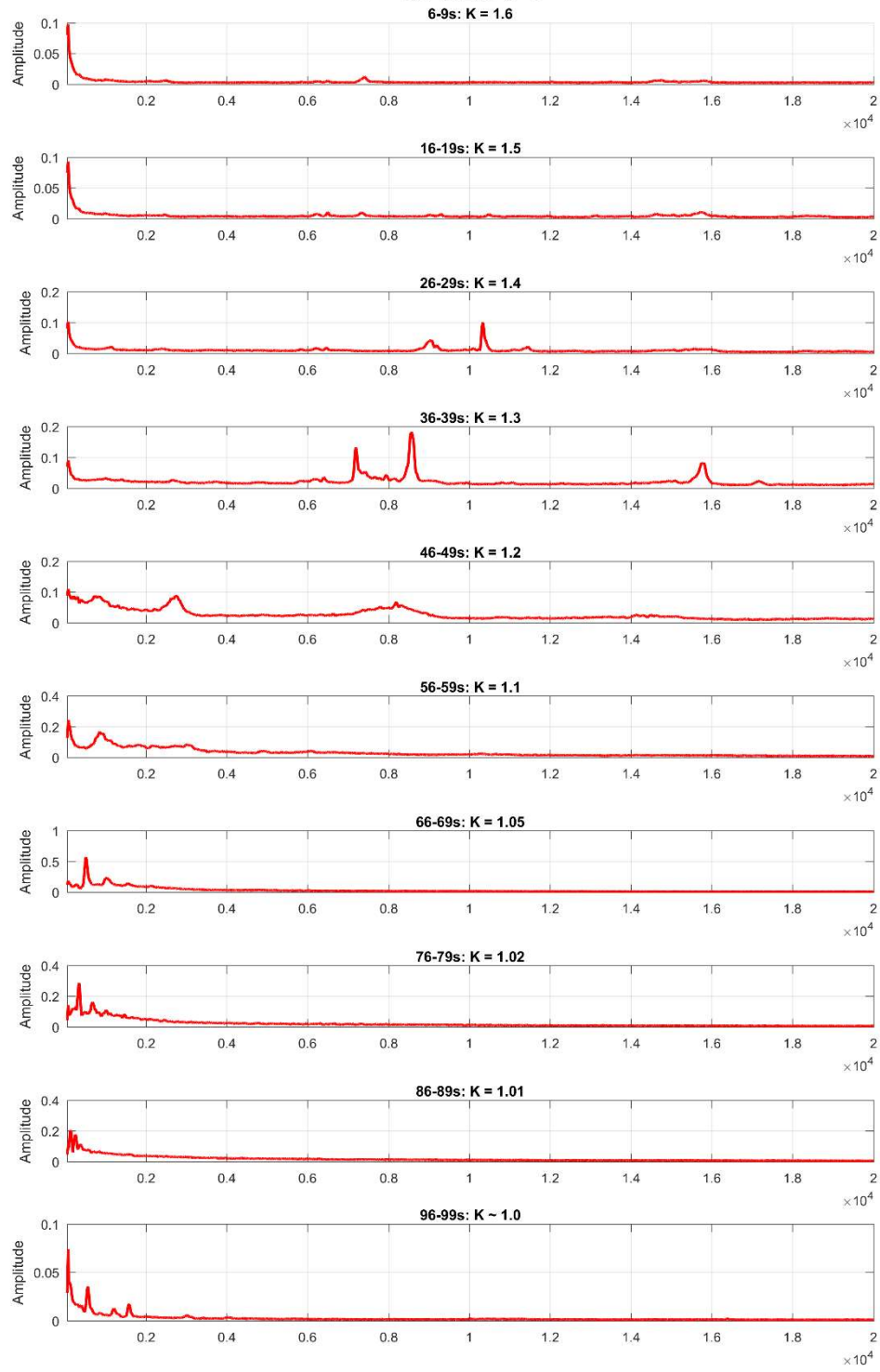
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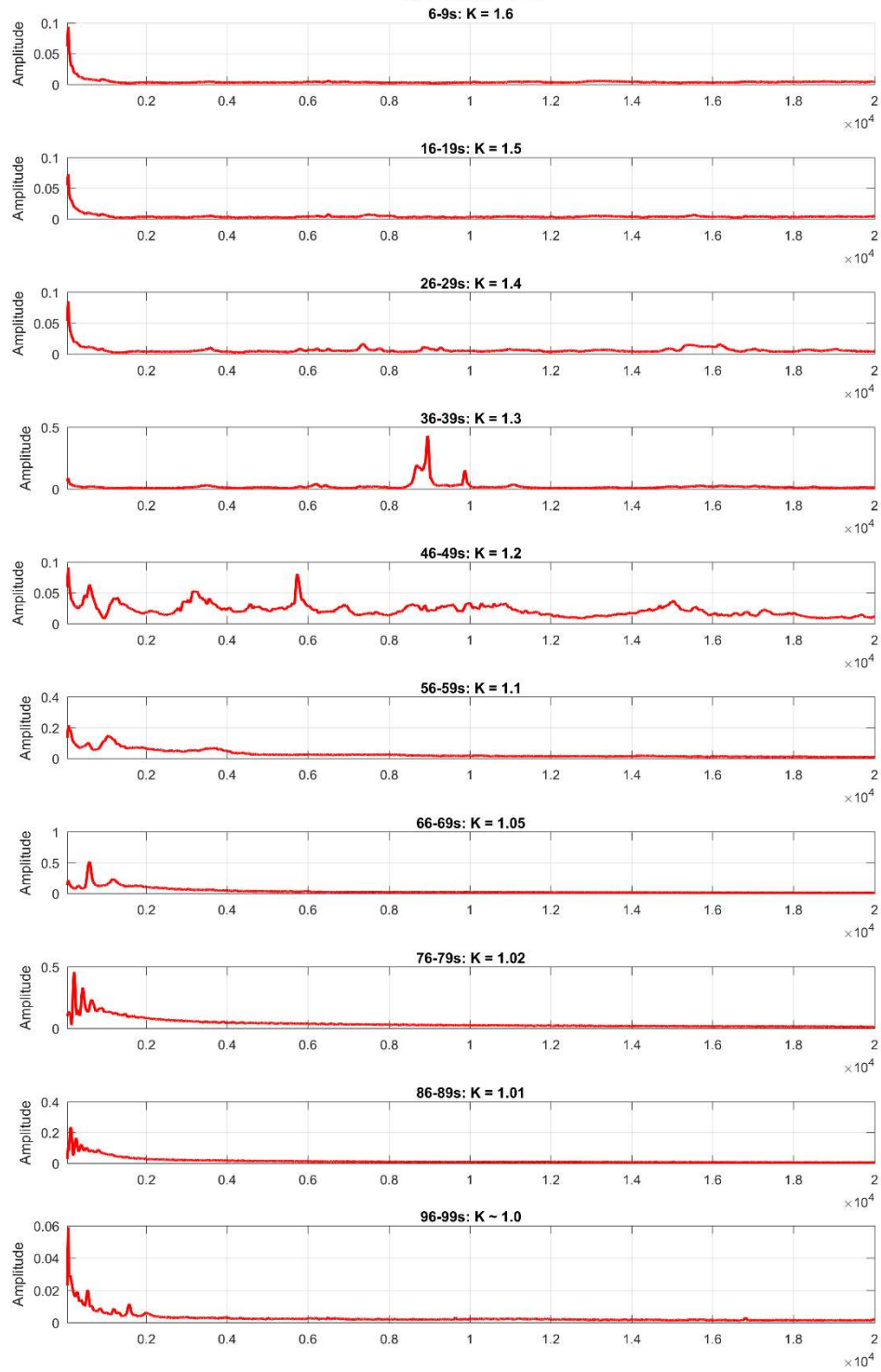
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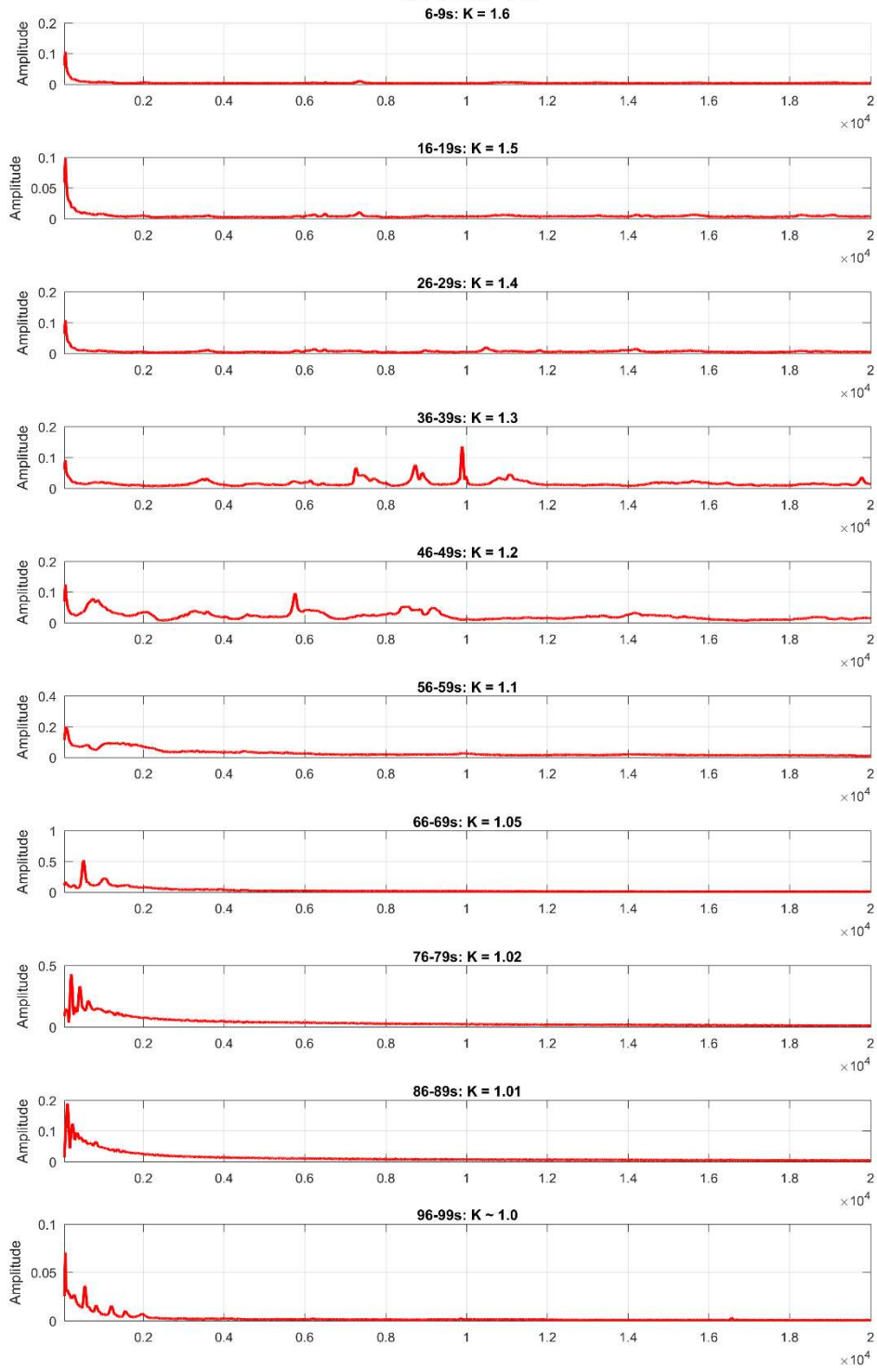
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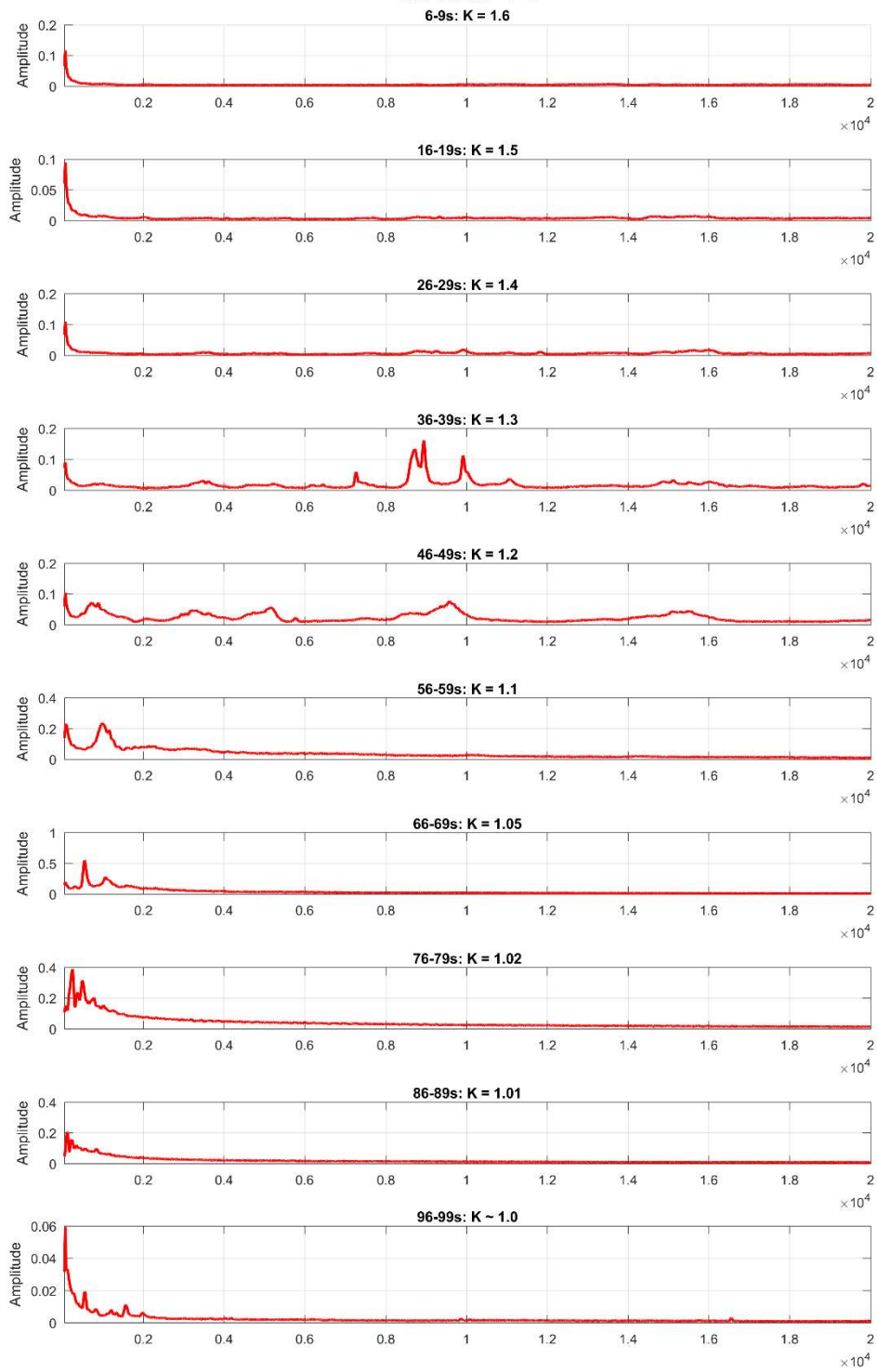
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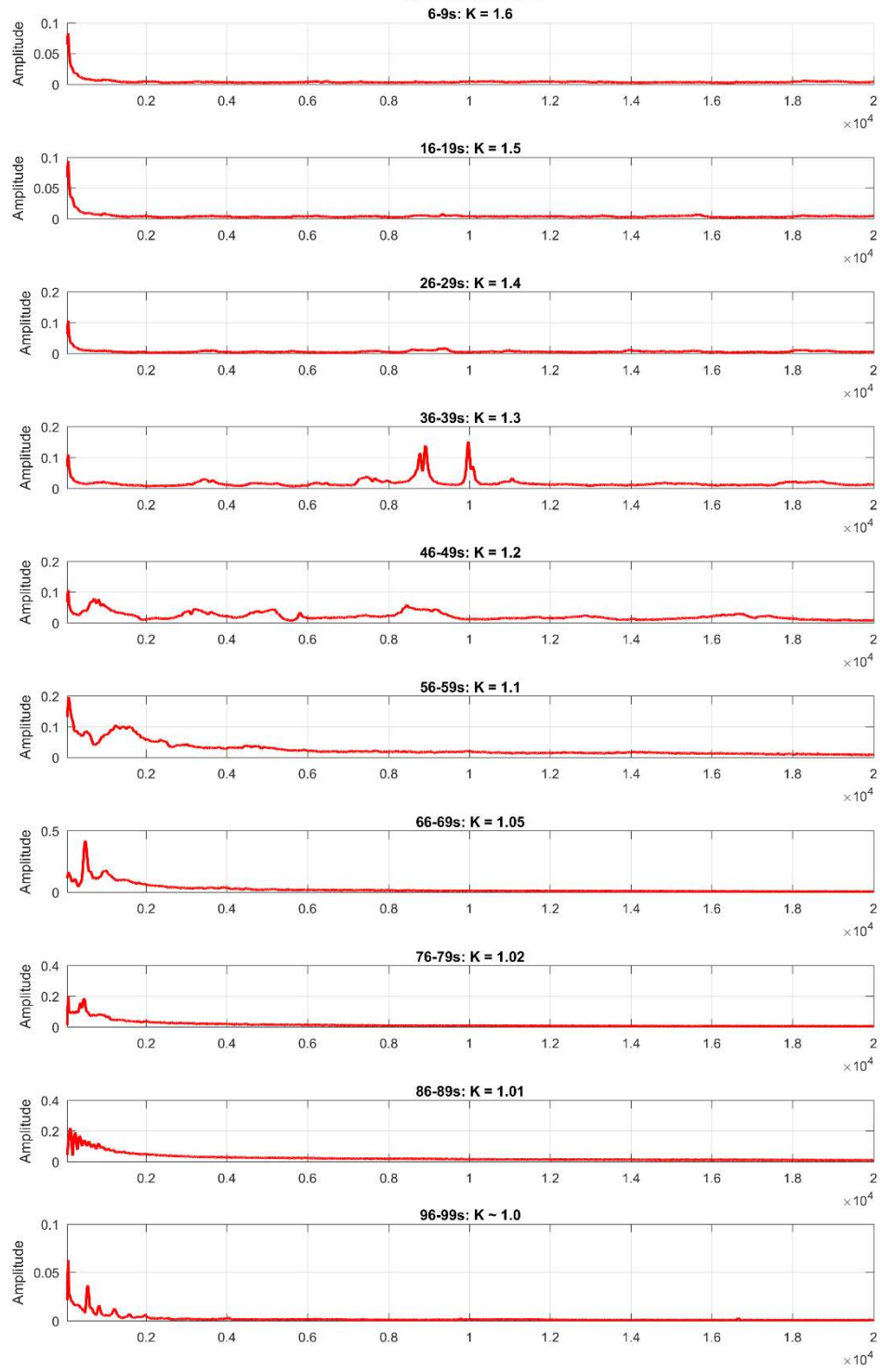
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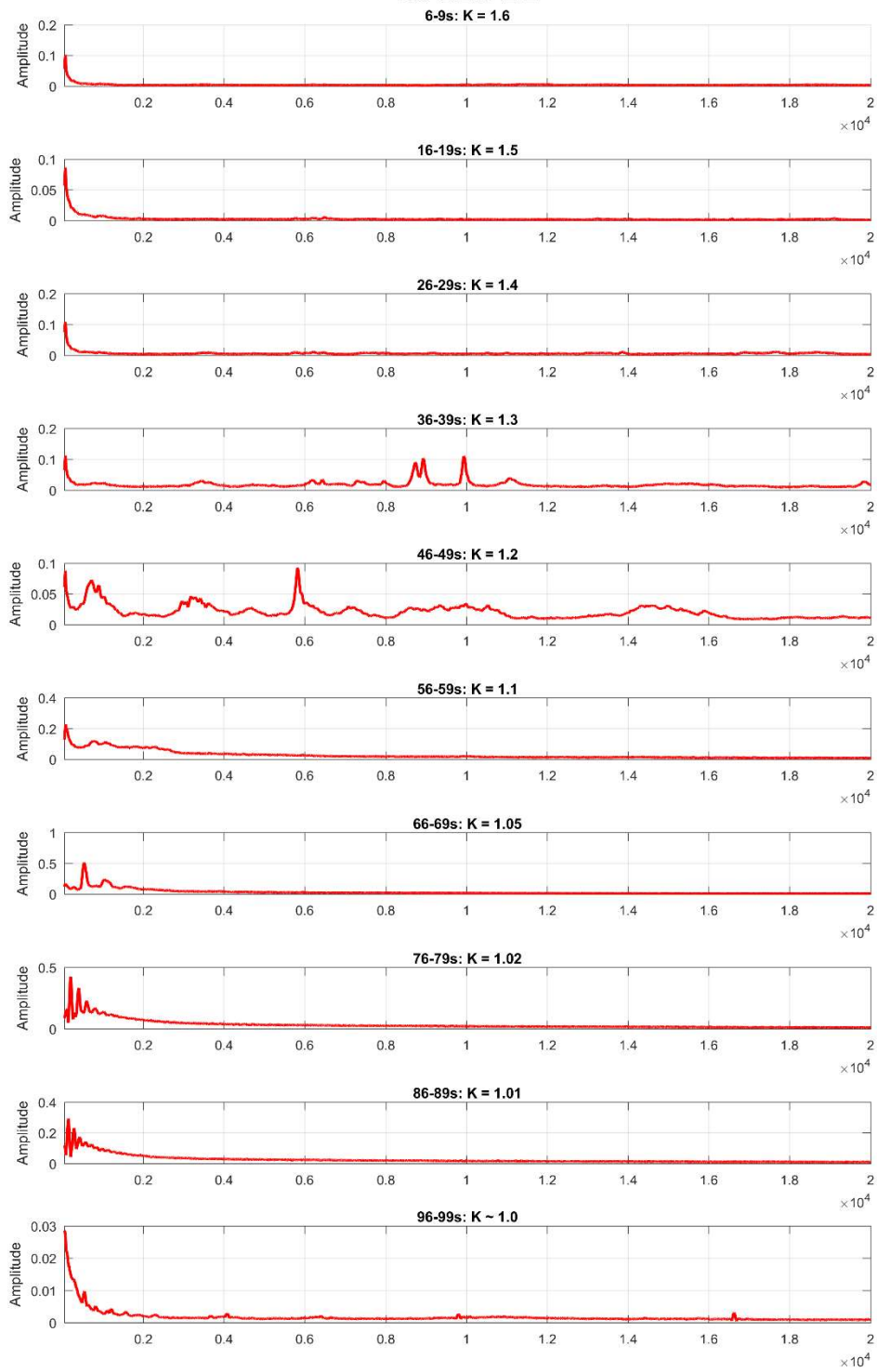
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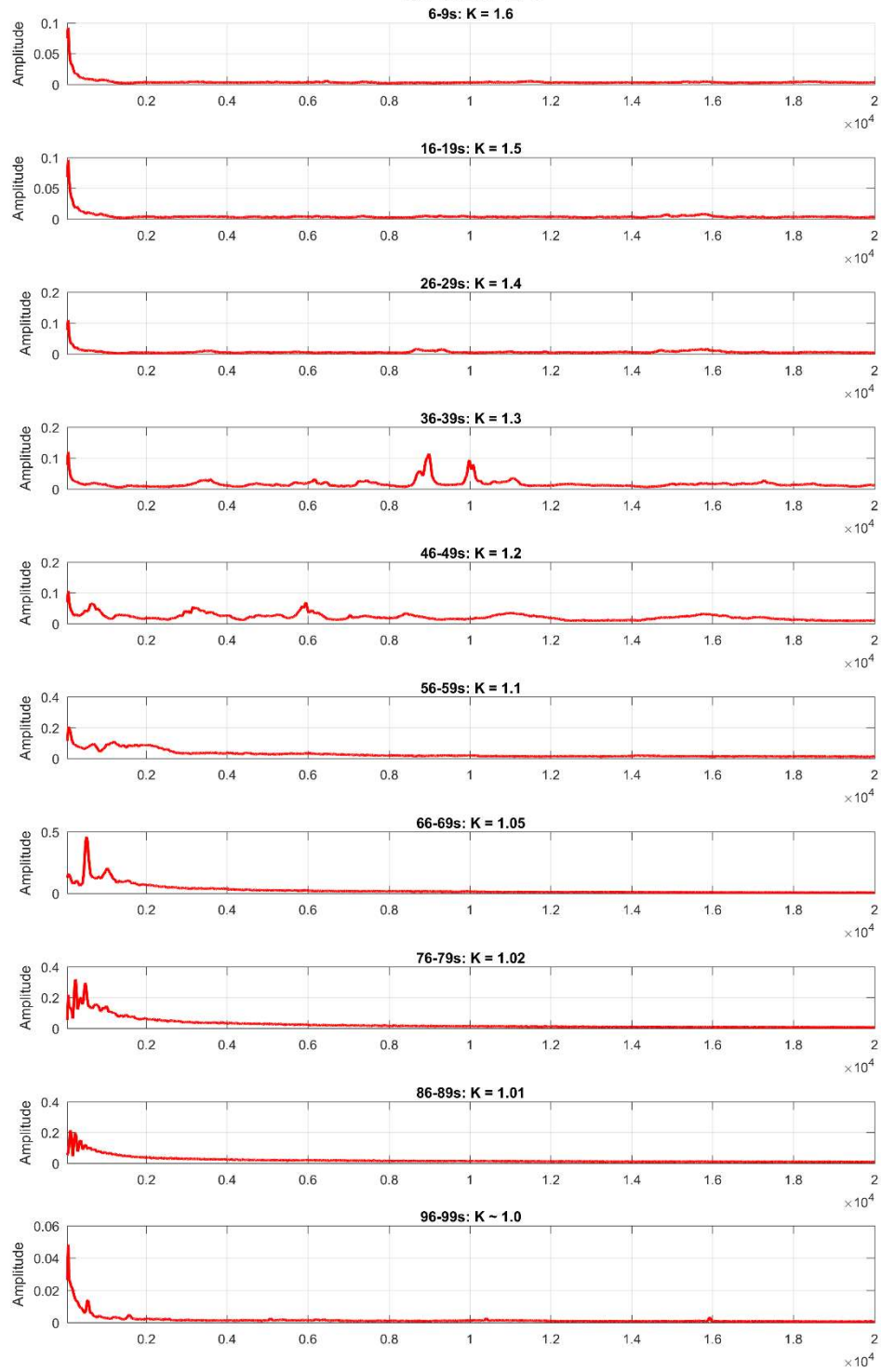
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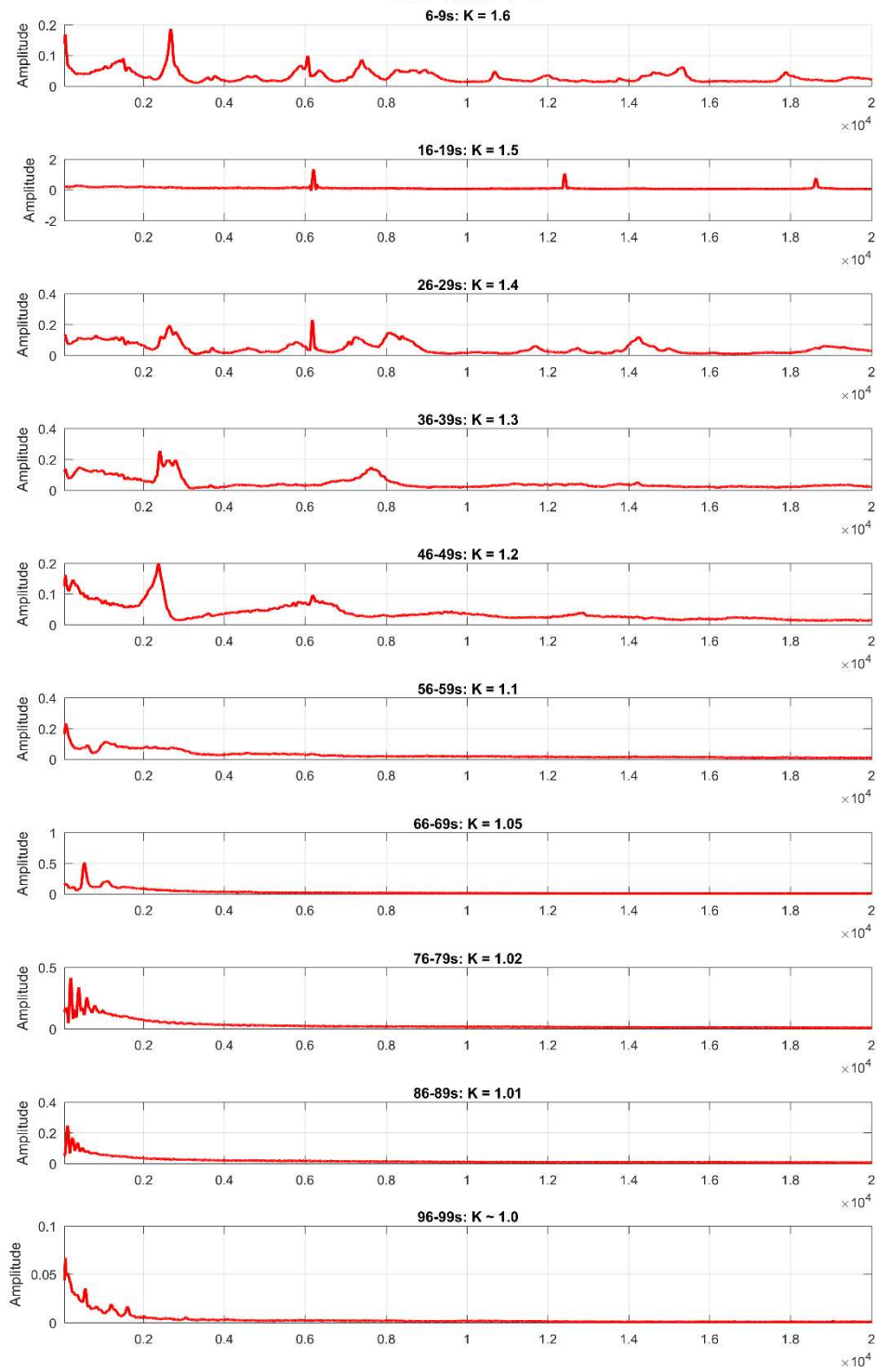


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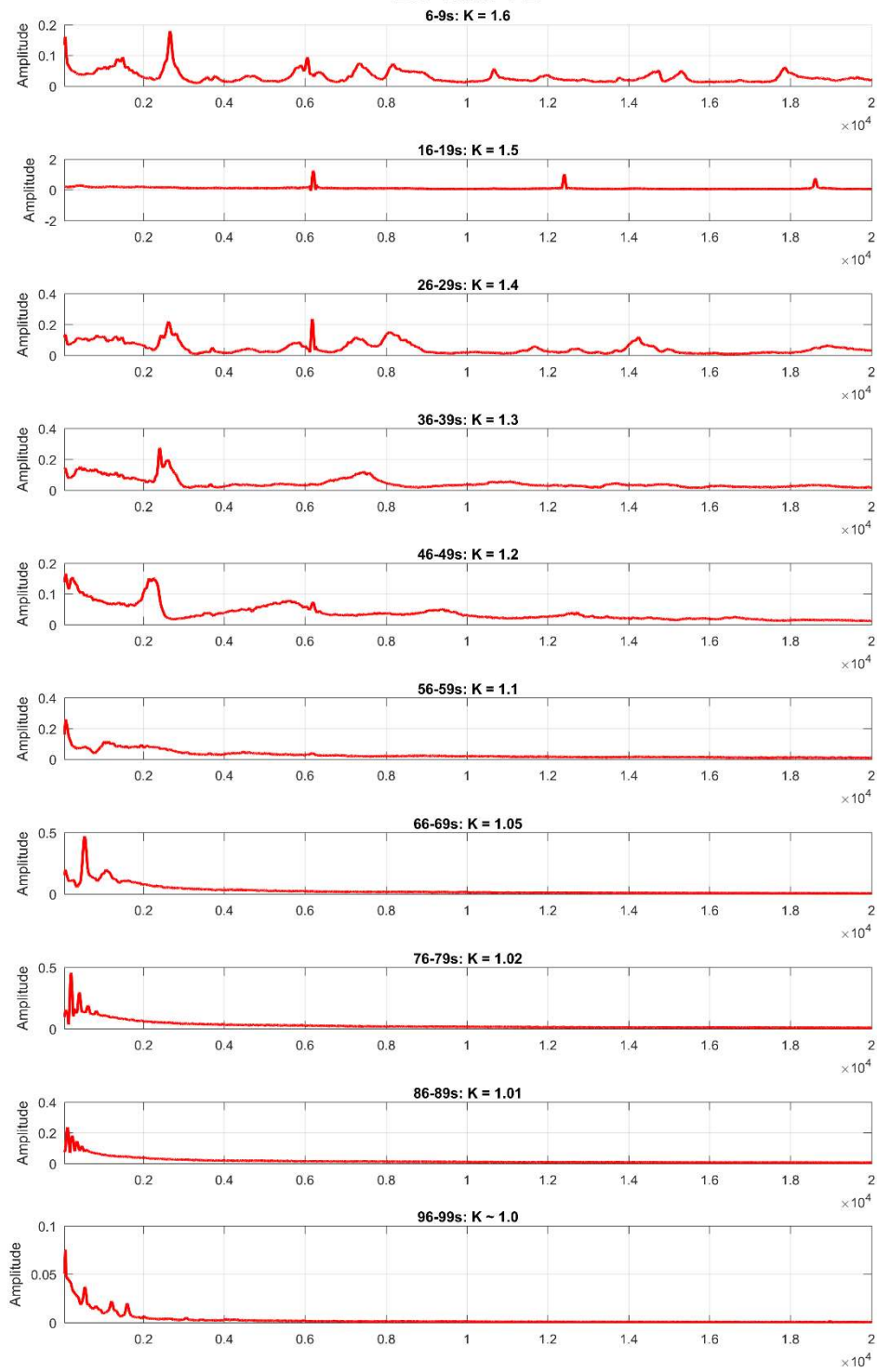


Appendix G: Block 5 High Frequency Charts

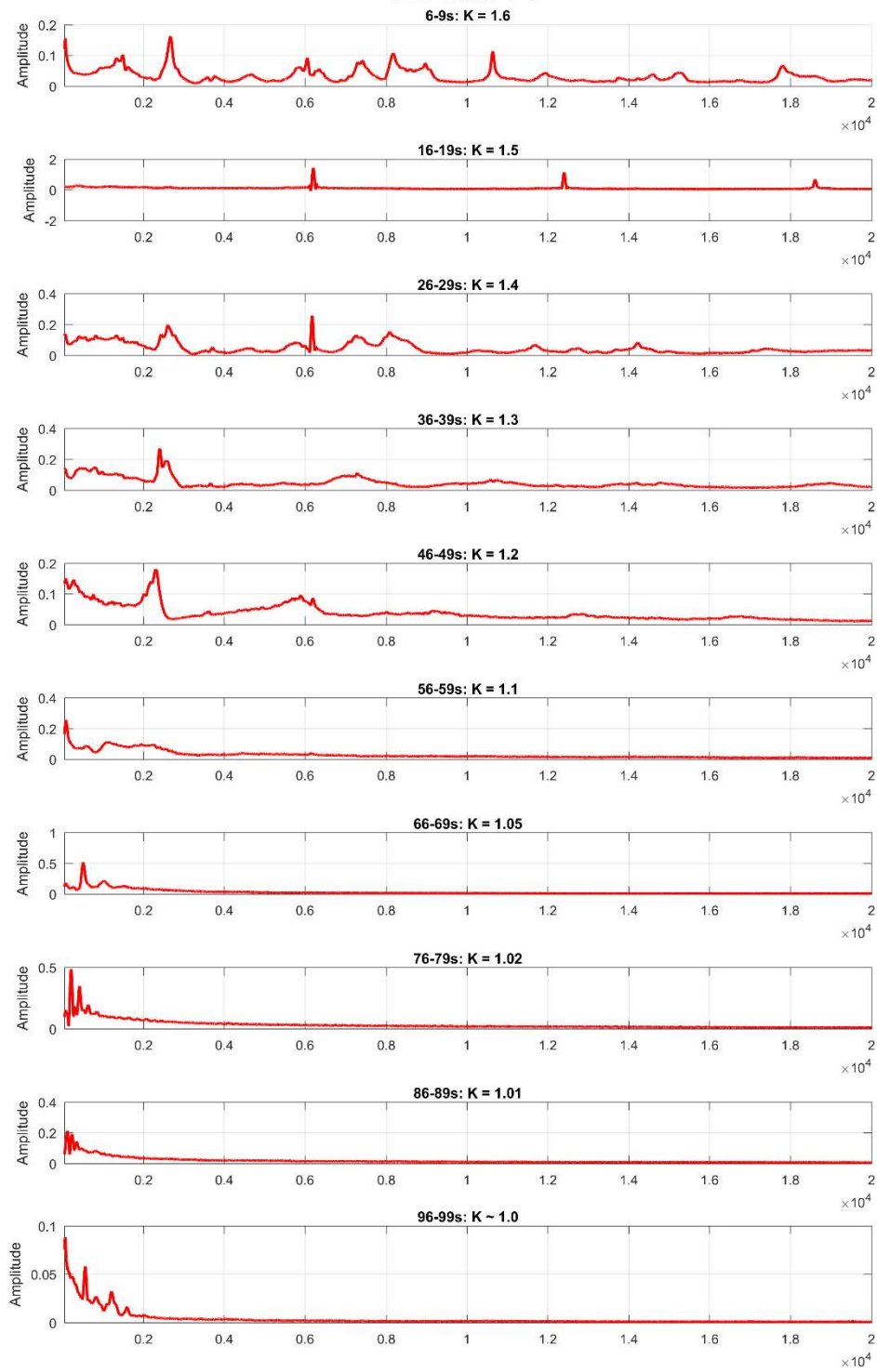
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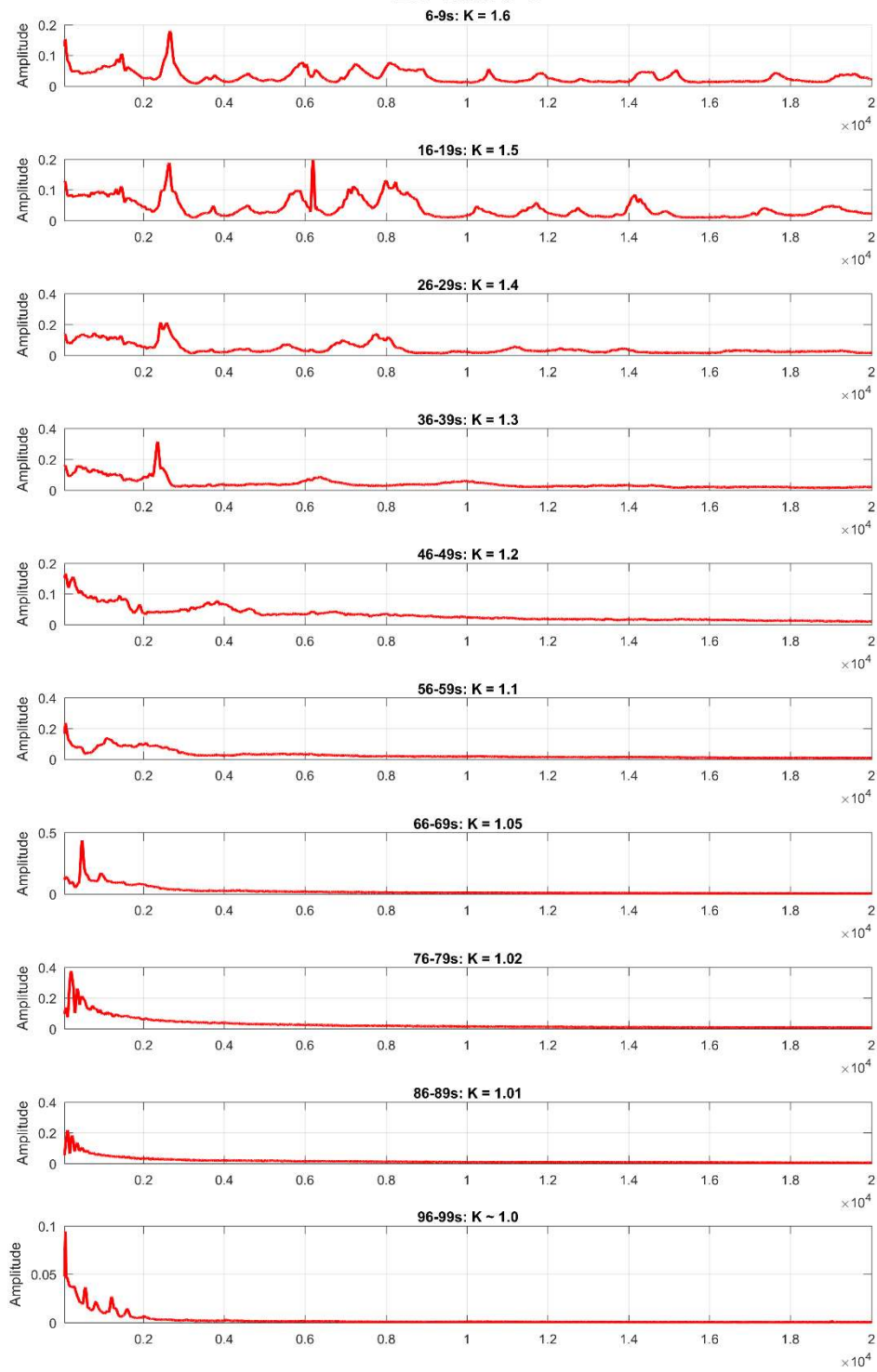
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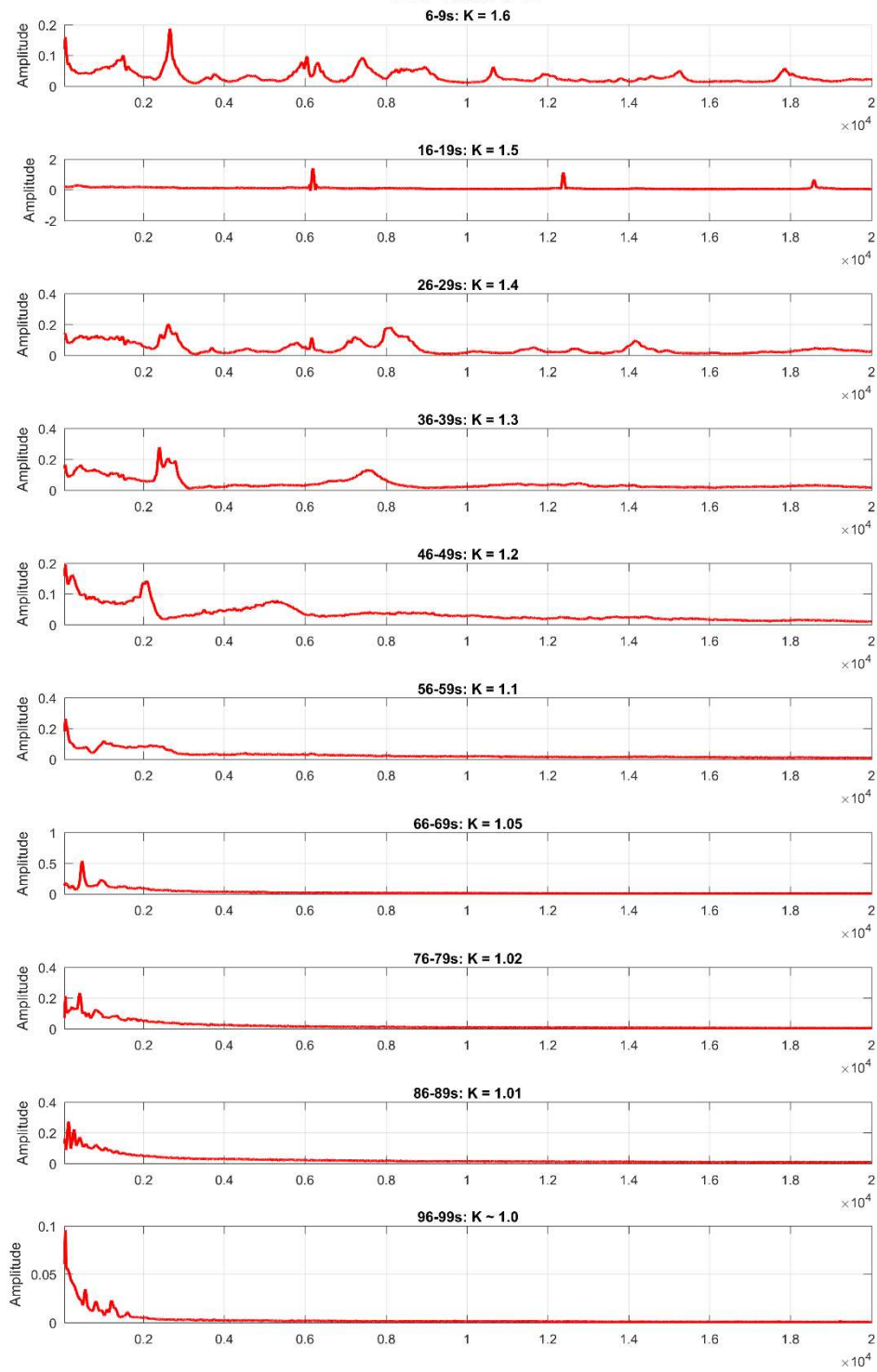
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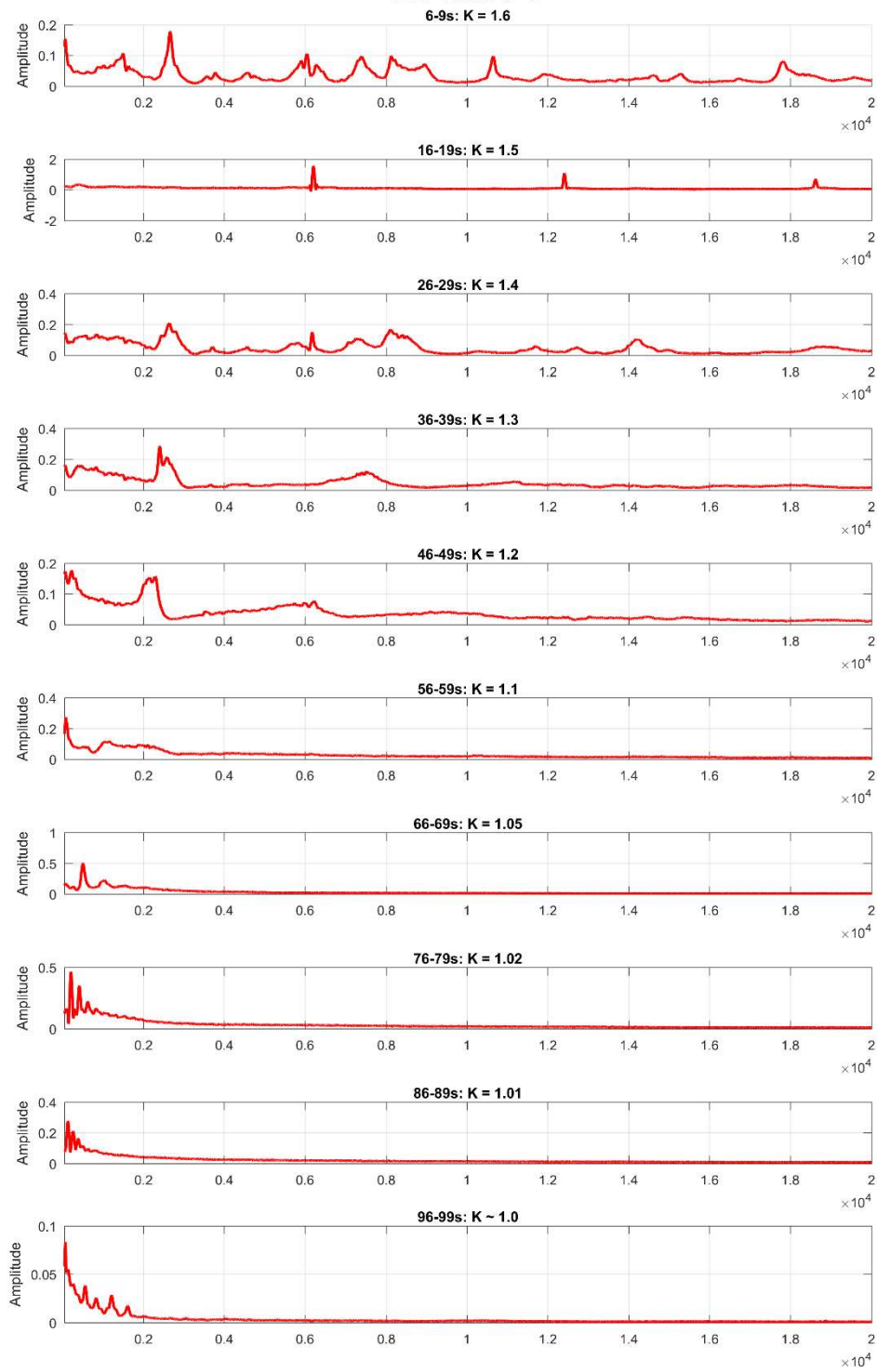
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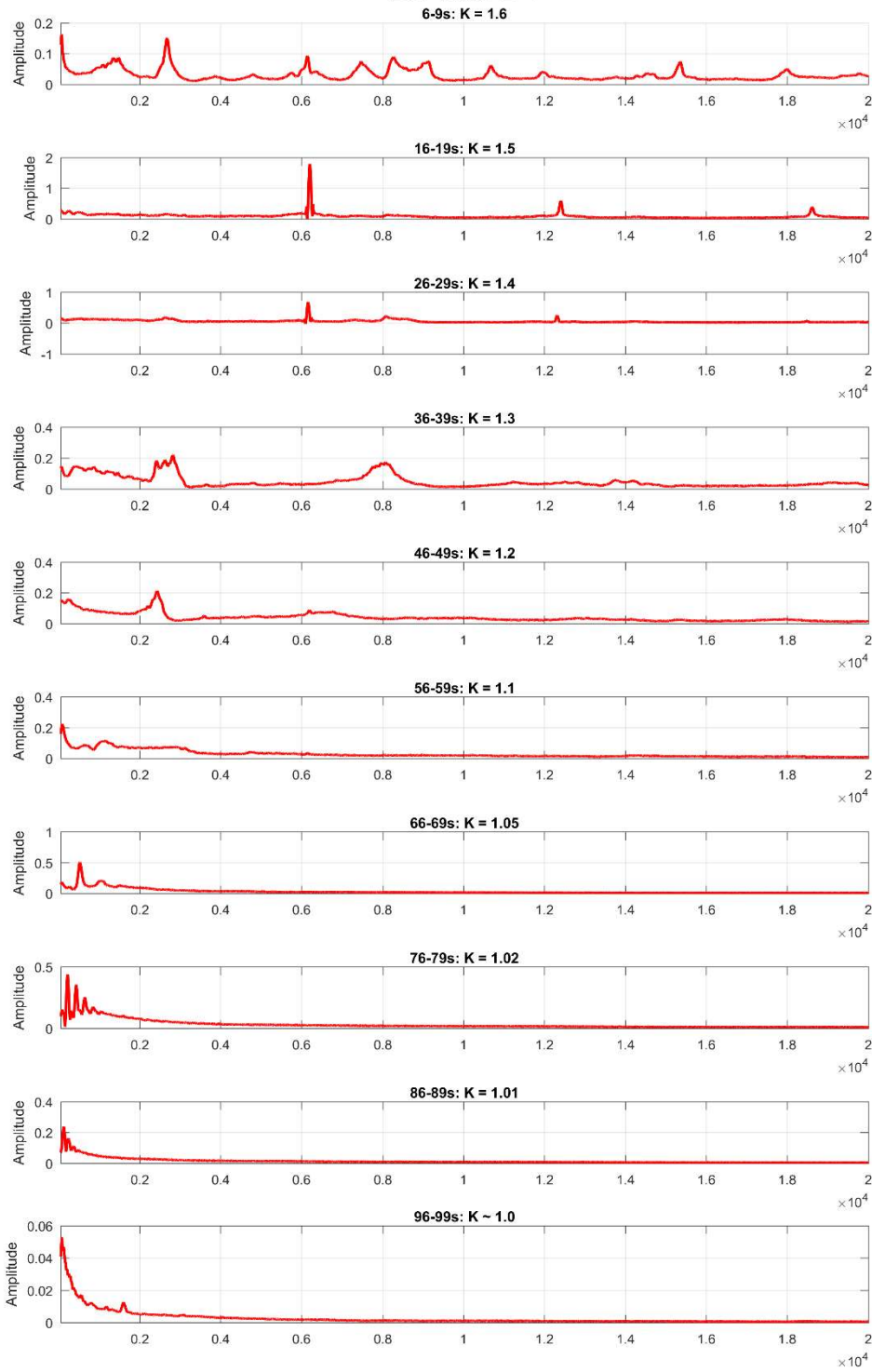
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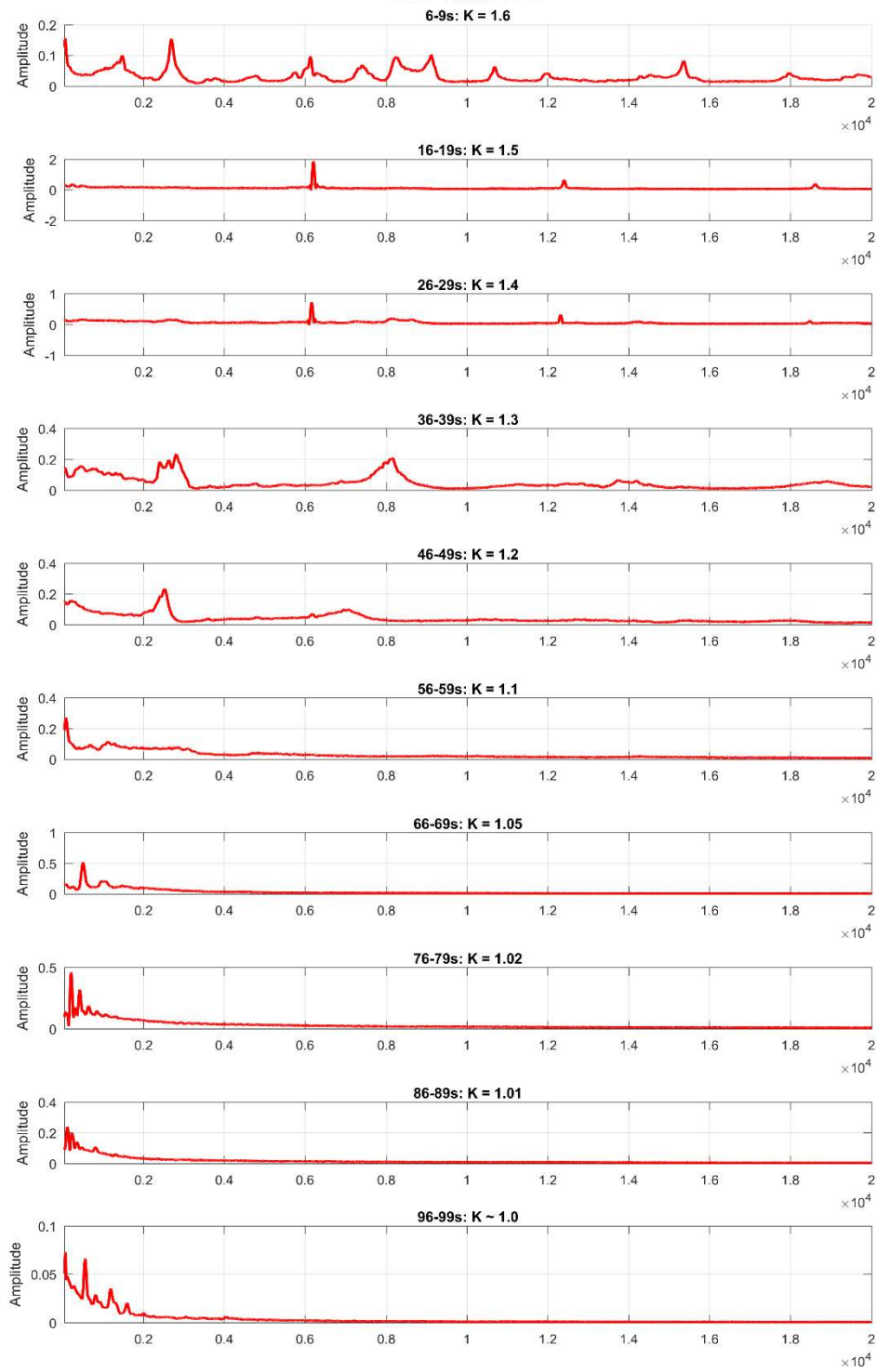
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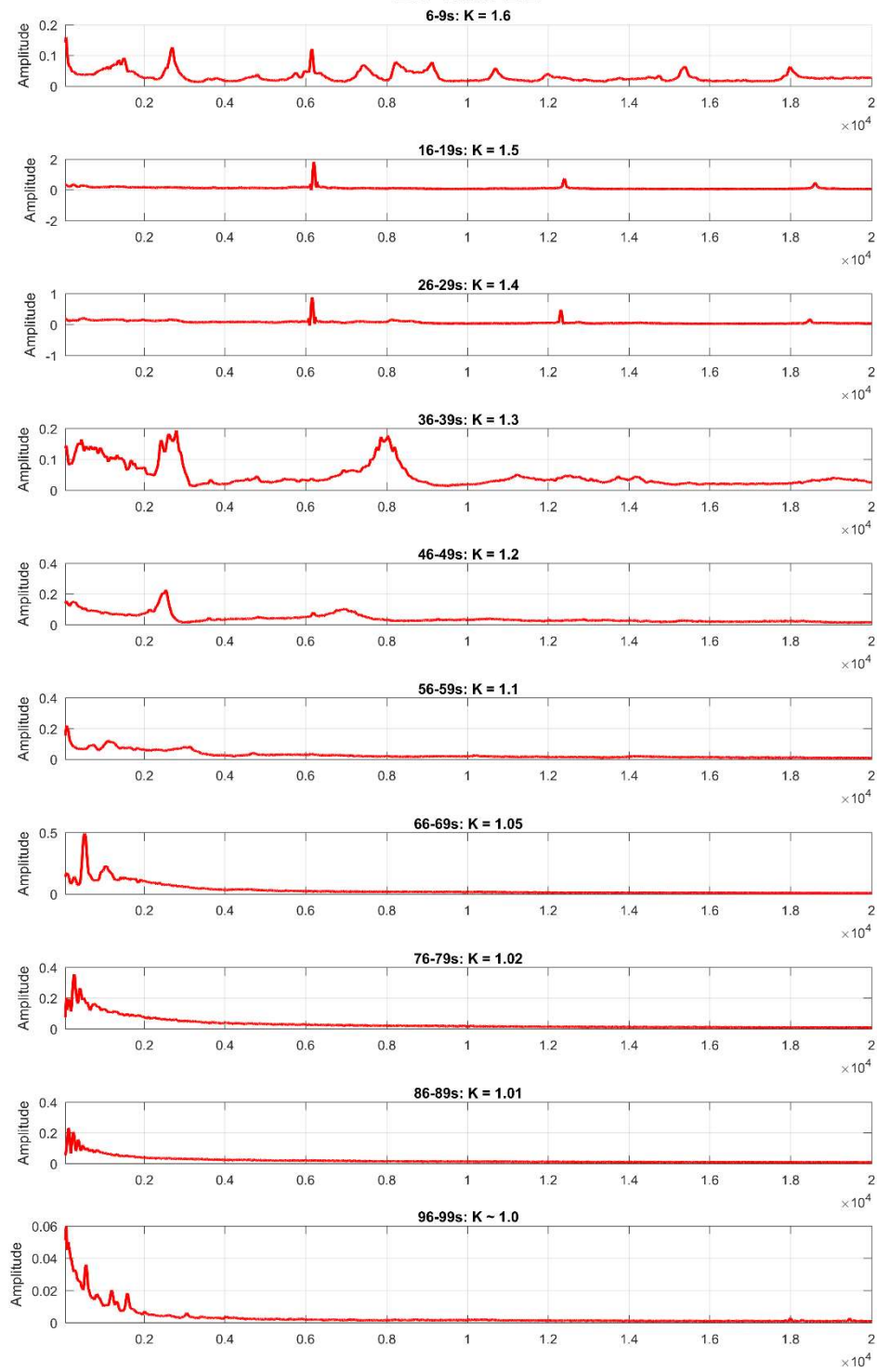
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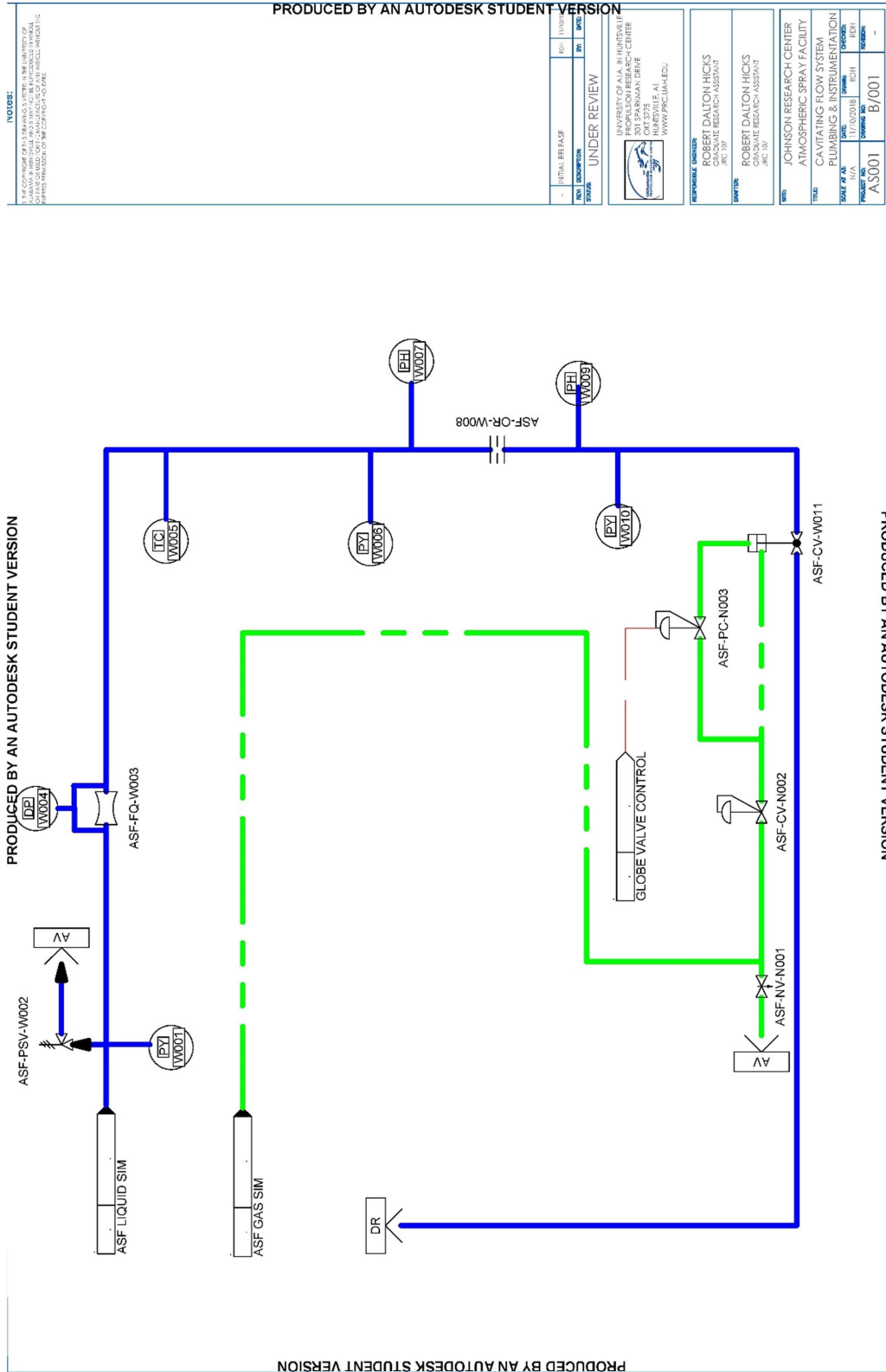
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B5-TRM-2-2



Appendix H: Cavitation Test Setup Plumbing & Instrumentation Diagram



Appendix I: Uncertainty Analysis of C_c

First step was to separate the C_c equation into multiple functional parts

$$C_c = \left(\frac{C_E}{A_{geo}} \right) \sqrt{\frac{DP_{meter}}{P_1 - P_v}}$$

With functional parts described by separate functions

$$X_1 = P_1 - P_v$$

$$X_2 = \sqrt{X_1}$$

$$X_4 = \sqrt{DP_{meter}}$$

$$X_3 = \frac{X_4}{X_2}$$

$$X_5 = \frac{C_E}{A_{geo}}$$

$$X_6 = X_5 * X_3$$

$$A_{geo} = \frac{\pi}{4} D^2$$

These were then used to determine the uncertainty of each functional part using uncertainty propagation methods.

$$\delta X_1 = \sqrt{\delta P_1^2 + \delta P_v^2}$$

$$\delta X_2 = \frac{1}{2} \frac{\delta X_1}{|X_1|} |X_2|$$

$$\delta X_4 = \frac{1}{2} \frac{\delta DP_{meter}}{|DP_{meter}|} |X_4|$$

$$\delta X_3 = |X_3| \sqrt{\left(\frac{\delta X_4}{X_4} \right)^2 + \left(\frac{\delta X_2}{X_2} \right)^2}$$

$$\delta X_5 = |X_5| \sqrt{\left(\frac{\delta C_E}{C_E} \right)^2 + \left(\frac{\delta A_{geo}}{A_{geo}} \right)^2}$$

$$\delta X_6 = |X_6| \sqrt{\left(\frac{\delta X_5}{X_5} \right)^2 + \left(\frac{\delta X_3}{X_3} \right)^2}$$

$$\delta A_{geo} = \frac{\pi}{2} * \delta D * D$$

With the values of the constituent variable uncertainties as:

$$\delta D = 0.0005 \text{ in}$$

$$\delta C_E = 9.216E - 08 \text{ m}^2$$

$$\delta P_1 = \sigma_{P_1}$$

$$\delta P_v = \sigma_{P_v}$$

$$\delta DP_{meter} = \sigma_{DP_{meter}}$$

This is then used to find the total uncertainty of the test average C_c . After the total uncertainty of the test is determined the largest uncertainty value is used for each configuration as the standard deviation of the mean C_c . This is then used to find the 95% confidence limits of the mean using:

$$U_{mean,95\% \text{ conf}} = \frac{t}{\sqrt{N}} * \delta X_{6,max}$$

Where t is the 2-tail t-test parameter for $N-1$ degrees of freedom. The confidence limits of the mean are therefore:

$$C_{c,mean,configuratin} \pm U_{mean,95\% \text{ conf}}$$

Uncertainty when determining the sharp-edge equivalent value for C_c is found as follows. First is to define the relation as follows.

$$C_{c,\frac{r}{d}=0} = \left[\left(\frac{1}{C_{c,\frac{r}{d}}} \right)^2 + 11.4 \left(\frac{r}{d} \right) \right]^{-\frac{1}{2}}$$

Functional parts can then be described by separate functions as such,

$$X_7 = \frac{1}{C_{c,\frac{r}{d}}}$$

$$X_8 = (X_7)^2$$

$$X_9 = 11.4 \left(\frac{r}{d} \right)$$

$$X_{10} = X_8 + X_9$$

$$X_{11} = (X_{10})^{-\frac{1}{2}}$$

The uncertainty propagation for each function can then be computed as such,

$$\begin{aligned}\delta X_7 &= \frac{\delta C_{c,\frac{r}{d}}}{\left| C_{c,\frac{r}{d}} \right|} |X_7| \\ \delta X_8 &= 2 \frac{\delta X_7}{|X_7|} |X_8| \\ \delta X_9 &= |11.4| * \left| \frac{r}{d} \right| * \sqrt{\left(\frac{\delta r}{r} \right)^2 + \left(\frac{\delta d}{d} \right)^2} \\ \delta X_{10} &= \sqrt{(\delta X_8)^2 + (\delta X_9)^2} \\ \delta X_{11} &= \left| -\frac{1}{2} \right| \frac{\delta X_{10}}{|X_{10}|} |X_{11}|\end{aligned}$$

With the following definitions for the variable uncertainties,

$$\begin{aligned}\delta C_{c,\frac{r}{d}} &= \delta X_6 \\ \delta r &= \sigma_r \\ \delta d &= \sigma_d\end{aligned}$$

The uncertainty for the sharp-edge equivalent value for C_c can be determined. After the total uncertainty of the sharp-edge equivalent value of C_c for each test is determined the largest uncertainty value for each configuration is used as the standard deviation of the mean sharp-edge equivalent C_c for that configuration. This is then used to find the 95% confidence limits of the mean using:

$$U_{mean,95\% co} = \frac{t}{\sqrt{N}} * \delta X_{11,max}$$

Where t is the 2-tail t-test parameter for $N-1$ degrees of freedom. The confidence limits of the mean are therefore:

$$C_{c,\frac{r}{d}=0,mean,configuration} \pm U_{mean,95\% conf}$$

Appendix J: Method and Data from Roughness Measurements

In order to measure the roughness of the parts, 6 parts were cut in half using various processes. One of these halves was then sent to the Center for Applied Optics Profilometry Lab where they performed nine tests per part as per the diagram in Figure 53. The “Left”, “Middle”, and “Right” areas are separated by 15° of angular distance and each line represents one evaluation length of 12.5-13mm.

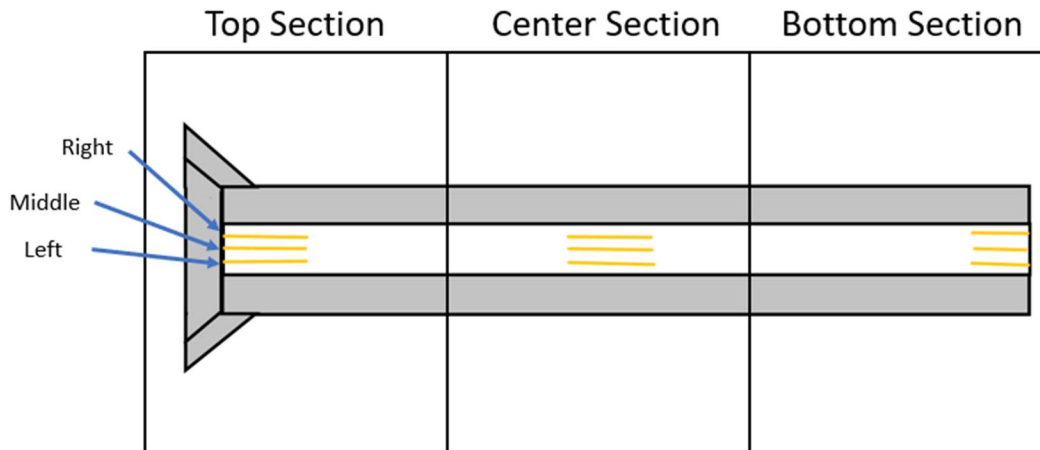


Figure 53: Roughness Testing Locations

A photo of the setup is shown in Figure 54 showing the orientation of the parts and the profilometer. After each evaluation length the variables are calculated. These are recorded in the tables in this appendix. With nine tests per part the roughness variations over the angular displacement and length of the part can be averaged out.



Figure 54: Testing Setup

Table 12: Roughness Data – 100 μm FDM #4

100 μm FDM #4									
	LB	LC	LT	MB	MC	MT	RB	RC	RT
Ra [μm]	12.485	13.934	18.93	13.507	13.19	14.173	13.673	12.748	15.756
Rq [μm]	15.89	17.49	24.872	17.626	16.557	17.587	16.821	15.824	20.236
Rsk [μm]	-0.6	-0.5	0.4	-0.7	-0.3	0.2	0	0.1	-0.4
Rku [μm]	3.7	3.7	3.5	4.6	3.1	2.8	2.6	2.7	3.6
Delq [$^{\circ}$]	30.06	30.09	27.08	30.29	30.35	30.83	29.71	28.9	31.62
Lamq [μm]	172.536	189.628	305.692	189.629	177.679	185.116	185.21	180.102	206.521
S [μm]	98.666	105.561	115.737	100.321	101.343	103.097	111.537	102.095	109.558
Sm [μm]	143.504	168.879	254.91	165.95	165.642	173.915	176.16	169.633	172.236
R3z [μm]	56.748	55.19	65.849	59.143	57.612	62.956	57.996	56.407	69.036
R3y [μm]	79.815	66.744	106.272	77.511	68.156	72.803	73.046	71.98	78.433
Rp [μm]	38.1	48.465	69.348	49.646	42.83	53.894	43.008	38.977	45.415
Rv [μm]	56.727	73.042	66.11	78.796	54.075	44.775	46.273	45.749	78.705
Rt [μm]	94.827	121.507	135.458	128.443	96.905	98.669	89.281	84.726	124.119
Rtm [μm]	79.819	89.068	95.803	86.053	80.39	83.895	75.16	74.67	91.743
Rpm [μm]	30.954	35.614	46.981	35.437	35.771	43.039	35.777	35.388	38.875
Ry [μm]	89.793	109.451	135.458	110.098	96.905	95.95	89.002	84.726	120.059
Rt1 [μm]	80.803	66.431	135.458	66.018	96.905	84.37	52.291	84.726	101.625
Rt2 [μm]	82.631	96.338	125.826	61.344	84.893	95.95	89.002	68.782	75.677
Rt3 [μm]	88.227	109.451	83.989	107.72	72.842	81.834	71.717	77.096	83.499
Rt4 [μm]	89.793	87.09	75.021	85.086	65.646	74.271	81.52	67.667	77.853
Rt5 [μm]	57.64	86.032	58.72	110.098	81.665	83.051	81.27	75.08	120.059

Table 13: 200 µm FDM #3

200 µm FDM #3									
	LB	LC	LT	MB	MC	MT	RB	RC	RT
Ra [µm]	19.846	17.763	17.031	17.135	16.681	23.575	19.349	22	18.592
Rq [µm]	25.855	21.73	21.376	20.734	20.456	30.486	24.933	28.56	23.588
Rsk [µm]	-0.9	-0.2	-0.4	-0.2	-0.3	0.3	-0.9	-0.6	-0.2
Rku [µm]	4.9	2.5	3.1	2.4	2.6	3.9	4.3	3.6	3.2
Delq [°]	32.99	33.28	32.13	32.32	32.97	32.42	32.97	31.87	30.75
Lamq [µm]	250.25	208.043	213.883	205.946	198.125	301.629	241.478	288.585	249.105
S [µm]	186.915	190.1	182.606	196.03	196.335	175.218	184.54	184.789	171.11
Sm [µm]	232.136	224.222	221.648	228.797	210.048	362.346	221.147	257.121	246.635
R3z [µm]	81.443	76.497	72.969	68.96	68.655	94.95	81.346	84.97	75.656
R3y [µm]	122.648	84.29	84.797	77.794	73.46	120.671	134.567	132.236	80.571
Rp [µm]	57.779	53.53	51.598	45.465	56.662	113.014	67.405	72.052	58.482
Rv [µm]	115.112	63.568	84.691	52.006	53.21	86.69	103.143	91.827	87.523
Rt [µm]	172.891	117.098	136.289	97.47	109.872	199.704	170.548	163.879	146.005
Rtm [µm]	99.043	94.202	97.48	79.799	92.949	148.101	103.374	131.378	114.735
Rpm [µm]	38.914	42.636	41.676	34.038	42.114	80.086	45.605	52.876	47.754
Ry [µm]	149.411	107.594	123.686	97.47	107.201	197.549	150.84	163.879	137.253
Rt1 [µm]	81.785	89.389	84.509	80.589	85.328	91	83.765	154.113	137.253
Rt2 [µm]	91.615	82.086	87.08	76.05	91.619	197.549	150.84	163.879	103.621
Rt3 [µm]	100.797	84.556	93.093	97.47	91.605	142.112	89.341	102.798	100.229
Rt4 [µm]	149.411	107.594	99.03	74.017	88.99	151.191	114.063	124.735	121.515
Rt5 [µm]	71.608	107.387	123.686	70.872	107.201	158.653	78.86	111.362	111.055

Table 14: 300 μm FDM #1

300 μm FDM #1									
	LB	LC	LT	MB	MC	MT	RB	RC	RT
Ra [μm]	39.738	19.018	26.484	24.559	25.659	24.927	25.3	30.324	25.652
Rq [μm]	57.256	23.781	31.704	29.231	30.799	30.206	30.634	36.806	30.958
Rsk [μm]	1.5	-0.1	-0.5	-0.4	-0.4	-0.3	-0.3	-0.5	-0.4
Rku [μm]	8.2	3	2.6	2.3	2.3	2.3	2.5	2.8	2.3
Delq [$^{\circ}$]	36.57	22.19	34.2	32.68	34.89	33.98	33.49	34.59	34.25
Lamq [μm]	484.87	366.364	293.128	286.286	277.497	281.59	290.96	335.373	285.732
S [μm]	298.856	292.25	288.307	278.692	299.49	292.437	285.438	292.272	291.47
Sm [μm]	395.557	410.177	305.213	322.072	314.137	315.235	333.011	330.896	320.596
R3z [μm]	121.313	64.226	92.4	93.35	102.666	104.097	95.935	107.804	99.601
R3y [μm]	199.316	95.755	103.424	105.88	104.137	116.307	99.136	116.89	109.859
Rp [μm]	296.026	63.184	56.754	55.609	58.971	58.581	72.872	75.755	53.17
Rv [μm]	156.083	81.497	106.327	77.421	81.527	78.611	88.86	125.33	81.604
Rt [μm]	452.109	144.681	163.081	133.029	140.497	137.192	161.732	201.085	134.774
Rtm [μm]	209.65	98.256	135.737	116.034	122.996	122.139	128.231	159.969	128.926
Rpm [μm]	101.441	45.056	49.659	48.063	51.288	51.286	55.74	64.951	50.484
Ry [μm]	452.109	144.681	156.109	121.022	140.497	127.945	161.732	197.083	132.316
Rt1 [μm]	164.509	87.474	107.406	118.549	122.4	124.947	102.509	163.192	132.316
Rt2 [μm]	175.877	144.681	153.822	113.685	116.051	110.986	116.566	197.083	127.853
Rt3 [μm]	452.109	87.983	124.344	121.022	115.261	127.489	119.562	137.317	129.615
Rt4 [μm]	132.546	70.69	137.005	113.607	140.497	119.328	140.785	167.967	122.534
Rt5 [μm]	123.21	100.45	156.109	113.31	120.768	127.945	161.732	134.287	132.311

Table 15: SLM #1

SLM #1									
	LB	LC	LT	MB	MC	MT	RB	RC	RT
Ra [μm]	6.58	5.443	5.337	7.088	4.969	5.229	8.455	5.14	5.393
Rq [μm]	8.835	7.045	6.827	9.476	6.466	7.096	11.048	7.185	7.259
Rsk [μm]	1.1	0.8	0.8	1.1	1	1.2	1.1	1.7	1.3
Rku [μm]	5.1	3.7	4	4.5	4.8	5.1	3.9	8	5.3
Delq [°]	15.82	14.48	15.9	18.58	14.16	15.71	19.75	15.08	17.17
Lamq [μm]	195.955	171.464	150.6	177.098	161.054	158.545	193.302	167.592	147.583
S [μm]	101.794	101.906	93.039	105.797	96.251	99.328	105.077	97.27	90.84
Sm [μm]	241.511	208.215	191.465	207.294	236.721	254.036	260.057	209.178	205.462
R3z [μm]	31.542	24.809	25.874	34.221	24.082	28.354	40.397	28.3	30.018
R3y [μm]	37.342	28.647	29.098	41.056	28.68	30.002	50.48	36.821	39.674
Rp [μm]	35.359	24.216	27.401	36.045	32.764	31.379	37.949	40.96	33.32
Rv [μm]	24.564	15.563	17.955	22.939	13.788	20.19	20.206	15.192	15.597
Rt [μm]	59.923	39.779	45.356	58.984	46.552	51.569	58.155	56.152	48.917
Rtm [μm]	47.597	35.641	37.362	50.333	37.026	39.426	50.362	40.427	38.53
Rpm [μm]	31.022	22.254	24.344	33.014	24.948	26.735	31.845	27.578	25.325
Ry [μm]	59.024	38.345	41.128	54.084	43.433	45.396	56.977	56.152	48.917
Rt1 [μm]	51.694	38.345	38.588	50.541	41.752	45.396	56.977	37.761	36.219
Rt2 [μm]	42.786	35.528	41.128	46.597	39.285	30.554	42.733	29.137	36.769
Rt3 [μm]	48.243	33.97	37.649	51.084	43.433	41.447	55.117	56.152	37.64
Rt4 [μm]	59.024	38.146	36.092	49.357	33.587	40.245	40.455	45.72	48.917
Rt5 [μm]	36.237	32.218	33.353	54.084	27.072	39.487	56.528	33.365	33.104

Table 16: Subtractive #1

Subtractively Manufactured #1									
	LB	LC	LT	MB	MC	MT	RB	RC	RT
Ra [μm]	0.382	0.113	0.483	0.393	0.123	0.562	0.369	0.122	0.8
Rq [μm]	0.478	0.145	0.606	0.5	0.164	0.67	0.47	0.162	1.016
Rsk [μm]	0.2	-0.3	-0.5	0.3	0.7	-0.3	-0.3	0.5	-1.1
Rku [μm]	3.1	6.8	2.7	3.1	5.2	2.2	3.8	5.1	5.5
Delq [°]	0.38	0.28	0.27	0.3	0.25	0.3	0.38	0.23	0.54
Lamq [μm]	456.758	184.632	806.066	593.253	234.915	794.59	444.32	253.265	681.301
S [μm]	70.426	58.941	82.57	59.427	54.79	94.888	66.302	56.198	174.137
Sm [μm]	527.821	257.31	1.157	583.055	231.297	1.331	690.236	373.647	1.485
R3z [μm]	1.445	0.491	1.702	1.266	0.602	1.932	1.187	0.656	1.943
R3y [μm]	2.329	0.619	2.201	1.761	0.796	2.329	2.25	0.947	2.653
Rp [μm]	1.477	0.438	1.24	1.475	0.693	1.186	1.229	0.638	2.29
Rv [μm]	1.2	1.18	1.496	1.104	0.682	1.922	1.996	0.594	4.781
Rt [μm]	2.677	1.618	2.737	2.578	1.375	3.108	3.225	1.232	7.072
Rtm [μm]	1.682	0.81	1.909	1.429	0.778	2.422	1.647	0.678	3.171
Rpm [μm]	0.877	0.289	0.868	0.699	0.339	0.99	0.696	0.293	1.524
Ry [μm]	2.677	1.451	2.44	1.932	1.004	2.529	3.225	1.031	7.072
Rt1 [μm]	1.314	0.731	2.409	1.24	1.004	2.354	1.423	1.031	7.072
Rt2 [μm]	1.208	1.451	1.37	1.144	0.643	2.199	0.7	0.502	2.284
Rt3 [μm]	1.782	0.721	2.44	1.447	0.543	2.506	1.509	0.338	2.437
Rt4 [μm]	2.677	0.485	1.781	1.381	0.931	2.529	3.225	0.633	1.895
Rt5 [μm]	1.428	0.663	1.544	1.932	0.771	2.523	1.376	0.887	2.165

Table 17: Subtractive #2

Subtractively Manufactured #2									
	LB	LC	LT	MB	MC	MT	RB	RC	RT
Ra [μm]	0.216	0.228	0.583	0.205	0.157	0.209	0.223	0.127	0.408
Rq [μm]	0.346	0.285	1.018	0.284	0.206	0.258	0.29	0.166	0.663
Rsk [μm]	-1.3	-0.2	-3.1	-0.2	0.1	-0.6	0	0.3	-2.8
Rku [μm]	12.8	2.6	12.5	6.1	3.6	3.2	4.3	3.4	11.3
Delq [$^\circ$]	0.63	0.32	0.39	0.55	0.29	0.4	0.5	0.28	0.52
Lamq [μm]	196.297	321.143	947.681	187.417	255.181	231.641	207.914	214.62	455.163
S [μm]	60.938	54.521	89.635	58.236	51.876	57.004	52.536	48.038	72.809
Sm [μm]	213.253	288.855	740.209	239.929	232.591	288.223	242.577	190.758	629.016
R3z [μm]	1.199	0.74	1.245	0.884	0.711	0.795	0.819	0.525	1.305
R3y [μm]	2.302	0.896	3.237	1.363	0.884	0.988	1.228	0.828	2.993
Rp [μm]	1.739	0.606	0.812	0.984	0.596	0.565	1.006	0.505	0.758
Rv [μm]	2.285	0.795	5.308	1.748	0.695	1.024	1.399	0.564	3.284
Rt [μm]	4.024	1.401	6.12	2.732	1.291	1.588	2.405	1.068	4.042
Rtm [μm]	1.817	0.974	2.129	1.22	0.873	1.075	1.247	0.725	2.072
Rpm [μm]	0.722	0.422	0.627	0.501	0.42	0.402	0.589	0.306	0.561
Ry [μm]	4.024	1.401	5.546	2.185	1.078	1.33	1.774	0.926	3.49
Rt1 [μm]	1.092	0.828	5.546	1.353	0.739	1.33	1.099	0.535	3.49
Rt2 [μm]	1.418	0.951	0.792	0.804	0.537	0.882	0.973	0.918	1.024
Rt3 [μm]	4.024	0.74	1.822	0.986	0.974	1.002	1.13	0.926	1.789
Rt4 [μm]	0.832	1.401	1.386	0.771	1.078	0.909	1.26	0.616	2.962
Rt5 [μm]	1.716	0.948	1.101	2.185	1.04	1.252	1.774	0.628	1.097

Appendix K: Experiment Procedure

UAH Propulsion Research Center
EXPERIMENTAL PROCEDURE FOR:
Axisymmetric Cavitation Testing

Revision: A

Test Location: JRC Atmospheric Spray Facility

Test Date: _____

Test Time Start: _____ Finish: _____

Notes: _____

This Procedure Contains the Following Hazards

	Radioisotopes or X-Rays
	Carcinogenic/mutagenic/teratogenic chemicals
X	Pressurized Gases
	Propellants/Combustion
X	High Electrical Voltage and/or Current

	Lasers
	Microbial and viral agents
	Recombinant DNA/RNA molecules
	Animal Subjects

R Dalton Hicks: _____ **Date:** _____

Author

SECTION I. TEST PROCEDURES

PRETEST FACILITY PREPARATION

- 1 If not already performed, perform PRC-SOP-JRC-032-A2
- 2 Ensure all personnel are wearing personal protective equipment (PPE).
- 3 Turn 3-way Gas Sim diverter valve to Pressurize.
- 4 Open Gas Sim Fire Valve.
- 5 Set Gas Sim Regulator to Full open.
- 6 Set Control Valve Regulator to 65 psig.

EXPERIMENT PROCEDURE

- 7 Open LabView.
- 8 Run: _____ .vi
- 9 Verify nominal pressure readings of zero
- 10 Verify nominal thermocouple readings
- 11 Verify/Install Test Article for Next Test
- 12 Log in Test Matrix
- 13 Choose Filename for Test and log in Test Matrix
- 14 Enable Datalogging
- 15 Verify Backpressure Valve is open
- 16 Open Liquid Sim Fire
- 17 Click "Start Routine"
- 18 Once Routine is complete Shut off Liquid Sim Fire
- 19 Disable Logging
- 20 Switch Pressure/Vent to Vent
- 21 Start Tank Fill Procedure
- 22 During Tank Fill Replace Test Article with next Article
- 23 Repeat Steps 12-22 until Testing has completed for the day

FACILITY SHUTDOWN PREPARATION

- 24 Back out Control Valve Regulator
- 25 Close Gas Sim Fire
- 26 Vent Gas Sim Line
- 27 Back Out Gas Sim Regulator
- 28 Continue with the rest of the steps in PRC-SOP-JRC-032-A2

Appendix L: SLM Printing Parameters

Material: Monel K500

Powder Size: -45/+15, Average of 31.8 μm

Power: 180W

Scan Speed: 600 mm/sec

Hatch Spacing: 0.105 mm

Layer thickness: 0.03 mm

Pattern: 3 mm island pattern, with islands offset 1 mm in the x and y directions every layer

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